## Anisotropic Gaussian Processes for PSF modeling & Implementation within Piff

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### PSFs In the Full FoV (Piff) package

- Piff is a new python software for PSF estimation developed initially to replace PSFex in DES and now also developed for LSST
- Modular package where it is easy to implement new PSF modeling and interpolation scheme over the FoV
- Package with unit testing and code review
- Will be used for the Weak-Lensing analysis of DESY3
- Contributors:

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### PSF decomposition

#### For a given exposure





Dark Energy Camera

### PSF decomposition

#### For a given exposure





Dark Energy Camera

Model that as a gaussian processes



Quick introduction to Gaussian process: How it works

- Gaussian processes are a probabilistic way to interpolate data
- Interpolation driven by the correlation function (aka kernel) described by "hyperparameters"; e.g.,
  - amplitude of the fluctuations
  - correlation lengths
  - •
- No problem taking into account measurement uncertainties
- Natural output is the mean and covariance at desired locations

Quick introduction to Gaussian process: How it works

1) Choose a correlation function (kernel)

2) Fit hyperparameters

3) Compute interpolation

- Involves inverting large matrices: N\*N matrix, where N = number of stars for PSF (N~10<sup>4</sup> for LSST full field of view)
  - Many matrix inversions for optimization of hyperparameters.
  - Only one matrix inversion for interpolation!

### Quick introduction to Gaussian Process: example in 1D

 Data generated with multivariate Gaussian and a squared exponential kernel

 $\xi(x) = \sigma^2 \exp\left(-\frac{1}{2}\left(\frac{x}{l}\right)^2\right)$ 

- $\sigma = 0.5, I = 2.0$
- Vary hyperparameters used in the gp interpolation
- Animation shows impact of assumed hyperparameters on the interpolation



## Hyperparameter fitting: the problem

• Classical method is to do a maximum likelihood fit (ML)

$$\mathcal{L} \propto rac{1}{|\boldsymbol{\xi}|^{rac{1}{2}}} \exp\left(-rac{1}{2} \mathbf{y}^{T} \boldsymbol{\xi}^{-1} \mathbf{y}
ight)$$

- But you must then invert at each step of the maximization an N\*N matrix (N~10<sup>4</sup> for LSST field of view)
- Possibility of local maxima
  - Difficult to determine if hyperparameters are optimal without inverting many N\*N matrices.
- Difficult to determine whether kernel was best choice for correlations in data

- Basic idea:
  - Instead of using maximum likelihood to find hyperparameters, use two-point correlation function
  - Indeed, Kernel ~ two-point correlation function
  - How it works:
    - Measure two-point correlation function on the data (using treecorr)
    - Fit the (1D) two-point correlation function with different kernels to find the best kernel and optimal hyperparameters
    - Use these hyperparameters to interpolate with gp



300 realizations of Gaussian random field generated with squared exponential kernel  $\sigma$  =0.03, l=0.5

Hyperparameter fit using 2-point correlation function with squared exponential kernel for 300 realizations



300 realizations of Gaussian random field generated with squared exponential kernel  $\sigma = 0.03$ , l=0.5

Hyperparameter fit using 2-point correlation function with squared exponential kernel for 300 realizations







The current scheme implemented within Piff



Atmospheric PSF

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The current scheme implemented within Piff

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Atmospheric PSF



2-point correlation function with treecorr

#### The current scheme implemented within Piff

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Compute covariance matrix using bootstrap resampling

Compute 2D 2-point correlation function with treecorr

The current scheme implemented within Piff

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The current scheme implemented within Piff

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- Exemple on real data (exp id: 510463)
  - Optical model removed and work only on the atmospheric parameters
  - size, gl, g2
- 80% used for training (hyperparameters fitting and interpolation)
- 20% kept for validation to compute Rowe Stat

size anisotropy 2-PCF



 Von-Karman correlation function size anisotropy 2-PCF









Isotropic Von Karman



#### Anisotropic Von Karman

- What is next:
  - Start to run on ~6000 images of DESY3 in order to look the overall improvement.

PSF profile  $\sim$  Optical part of the PSF  $\otimes$  Atmospheric part of the PSF

**PSF** profile Optical part of the PSF  $\otimes$ Atmospheric part of the PSF  $\sim$ as a Fraunhofer Diffraction  $I(u,v) \sim \left| F \left\{ P(\rho,\theta) e^{2\pi i W(\rho,\theta)/\lambda} \right\} \right|$ Wavefront Pupil function

**PSF** profile Optical part of the PSF  $\otimes$ Atmospheric part of the PSF as a Fraunhofer Diffraction  $I(u,v) \sim \left| F \left\{ P(\rho,\theta) e^{2\pi i W(\rho,\theta)/\lambda} \right\} \right|$ Wavefront **Pupil function** Wavefront decomposed as a double Zernike polynomial that depends on the focal plane coordinate  $W(\rho,\theta) = \sum_{i} \left[ a_{i,reference}(u,v) + a_{i,corr}(u,v) \right] Z_{i}(\rho,\theta)$  $a_{i,corr}(u,v) = \sum_{i} b_{i,j}(u,v) Z_{j}(\rho,\theta)$ 

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