Analysis techniques for HESS

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Reminder about Atmospheric Cerenkov Technique
 Reconstruction techniques

 Hillas parameters based techniques
 More elaborated reconstruction techniques

 Background subtraction
 Toward diffuse emission analysis?

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Crab > 1 TeV : ~ 1 γ /century/m² Need for huge collection area





An electromagnetic shower



Variability of showers



Variability of showers

γ, 100 GeV

Protons, 500 GeV





 Hadronic showers fluctuate more (Good for discrimination)
 Contain some muons

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Atmospheric Cherenkov Imaging



I – "Hillas Parameters" based techniques



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Image parametrisation

 Hillas Parameters (1984): γ images are ~ elliptical

 reduce information to a few numbers:
 Length (L) & Width (w)
 Amplitude (size)
 Nominal Distance (d)
 Azimuthal Angle (φ), pointing angle (α)

 Additional parameters : asymmetry, ...
 Need pixel-in-shower identification (cleaning)







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Stereoscopy

Direction reconstruction: intersection of image main axis (angular space)



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γ /h Separation – Energy reconstruction

- $\Box MC \Rightarrow \text{lookup table}$ (width, length = f(impact, size)) $<w>(\rho,I), \sigma_w(\rho,I)...$
- Normalized parameter, averaged over telescopes

$$S_{w} = \frac{(w - \langle w \rangle)}{\sigma_{w}}$$
$$MSW = \sum_{tels} S_{w} / \sqrt{ntels}$$

Mean Scaled Width

- MeanScaledWidth and MeanScaledLength most discriminant (factor ~ 100)
- Energie : Similar technique : Lookup tables (Image Size, Impact distance) \Rightarrow Energy and σ_{Energy}
 - □ Resolution 20 25%
 - Can be improved using additional variables e.g. Depth of shower maximum

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Possible improvements

□ Some possible improvements in reconstruction

Uncertainty on Hillas Parameters
Constrains on nominal distance

 Discrimination: additional informations can help
 Depths of shower maximum
 Consistency between telescopes (i.e. energy reconstruction)
 Temporal structure (time gradient

in images)

Significant improvement (~ 2) only in single telescope mode

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3D Model Analysis

Principle: extend Hillas parameters using correlations between several telescopes

- Model the shower by a 3D Gaussian photosphere
- Intensity in each pixel : line of sight integral of photosphere

□ Fit model to actual images (after cleaning) (log-likelihood)

8 parameters fit

Altitude, impact, direction, width, length, brightness

Lemoine-Goumard, Degrange, Tluczykont, Astropart Phy 25 (2005) Mathieu de Naurois Annecy,



Discrimination



Energy reconstruction

- Result of shower fit: number of photons in shower
- Empirical relation to energy : ln(E) = a + b * ln(Nphot) a and b function of zenith angle (from MC)
- Resolution < 15% in [800 GeV 50 TeV], no bias, worsen at lower energies



III – Model Analysis



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Principles

□ Fit the raw (uncleaned) images to a precalculated shower model

- Semi-analytical shower model, function of shower true parameters (energy, direction, impact,...), done once for all
- Log-likelihood fit, using actual noise distribution in every pixel (=> more precise)

Prob. of observing x when μ is expected

1 W PF"

Model image for each

- zenith angle
- energy
- impact distance
- first interaction depth

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$$P_{df}(x,\mu,\sigma_{p}) = \sum_{n} \frac{\mu^{n} e^{-\mu}}{n! \sqrt{\pi \left(\sigma_{p} + n - \sigma_{\gamma}^{\Box}\right)}} \exp\left(\frac{-(x-n)^{\Box}}{\Box \left(\sigma_{p}^{\Box} + n^{\Box} - \sigma_{\gamma}^{\Box}\right)}\right)$$

$$\sigma_{p} = Pedestal \ width(NSB+electronic \ noise)$$

$$\sigma_{\gamma} = PMT \ resolution$$





Discrimination: goodness-of-fit

□ NOT a likelihood ratio (no alternate hypothesis)

Comparison of actual log-likelihood with expectation value (analytically calculated)

$$\langle \ln L \rangle = \int_{x} \ln \left(P_{df}(x,\mu,\sigma_p) \right) \times P_{df}(x,\mu,\sigma_p) \times dx$$



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Performances

Resolution on first interaction point ~0.5 X_o

Good energy resolution 15% (a) 80 GeV, 8% (a) 2 TeV □ Improved angular resolution

□ Improved rejection, in particular at low energy



Reconstructed Primary Depth #events 600 ON 500 OFF **ON-OFF** 400 300 200 100 **PrimaryDepth**



Conclusion on reconstructions

□ 3 different techniques:

- □ Hillas / Scaled cuts : robust, quite stable and fast
- □ 3D Model : improved performances at high energy
- Model : improved efficiency (at low energy), improved resolution and separation at the expense of a much larger computing time

Quite different assumptions:

- Scaled cuts : selects the « most frequent showers », according to MC, in parameter space. Shower fluctuations taken into account, but not correlation between telescopes.
- Model analysis : selects the shower looking the most « similar » to a model, even if they are rare. Includes telescope correlations, and partially shower fluctuation (first interaction depth).

Quite different sensitivity to external (atmosphere state, nsb, ...) parameters. Good for investigation of systematics

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Background subtraction

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Foreword

Trigger rate:

- \Box HESS : 300 Hz in ~ 5° FOV \Rightarrow raw rate ~ 10 s⁻¹ deg⁻²
- □ Chandra : ACIS 7.5' × 7.5' FOV \Rightarrow raw rate ~ 10 s⁻¹ deg⁻²

□ Photon rate:

- \Box HESS : ~ 10⁻² γ /s (10% Crab)
- □ X-Ray : ~ 1 count/s for similar sources

 $\square \Rightarrow IACTS$ are background dominated

- \Box Background rejection is essential & challenging (factor > 10² needed) □ Remaining irreducible background, \Rightarrow statistical determination of signal N_{exc} = NOn - α × NOff
- Background subtraction essential part of business. Must be controlled at ~ 1% (faintest HESS sources) => acceptance determination (background model) Mathieu de Naurois

Background model?

Acceptance (= expected background) depends on:

- □ zenith angle (atmospheric depth)
- □ primary energy
- □ distance to FOV centre (off-axis angle)
- azimuthal angle (for array without azimuthal symmetry)
- □ primary nature (and discrimination cuts)
- atmospheric transparency
- □ night sky background (NSB) intensity
- □ instrument status (gains, reflectivity, missing pixels,...)

Acceptance determination on same data as signal extraction! Annecy, Mai 2009 22

Radial (= off-axis) acceptance



As function of energy

As function of zenith angle

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Wobble observation mode

Pioneered by Whipple / HEGRA

 \Box Alternating observation position, shifted in FOV (±0.5°)

Background from mirror region in FOV

Rely on azimuthal symmetry of acceptance. ~ True in single telescope, not in stereo. Zenith angle gradient.

□ Can derive a signal, a spectra, but not map (no mirror for centre)



Multiple Off Background

Extension of wobble mode:

- Several OFF regions distributed at equal distance to camera centre
- *a priori* exclusion of known source (iterative process)

□ No map...





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Ring Background

- Background from a ring centred on each test position. Not at equal distance to centre
- □ Radial acceptance correction (averaged)
- □ Energy dependency of radial acceptance not taken into account (yet) ⇒ no spectra, just maps







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Template Model

- Use an alternate ("hadron-like") population at the same position
- $\square \Rightarrow$ Acceptance needed for both populations
- Only map (energy badly controlled for hadrons)
- Good for large sources and/or crowded FOV (RXJ 1713,...)





Field-of-view background Toward diffuse emission?

□ To be able to detect large structure, one need to derive the acceptance from alternate data (or MC)

Precalculated acceptance curves (as function of zenith)

□ Still need normalisation on a fraction of FOV (absolute level) ⇒ signal free region needed in FOV

Good for large sources (and for diffuse?)

But control of systematics (NSB,...) very tricky, not reliable yet for faint sources

Need large amount of data taken with similar conditions (NSB, reflectivity, ...) and without source



Night sky background measurement (NSB)

□ HESS estimation from pedestal width (noise dist. in PMTs)



NSB anisotropies effect

 \Box Acceptance to hadrons in Galactic plane: $\pm 3\%$ (RMS) fluctuations



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NSB effect on event rate in cuts

Correlated fluctuations at the level of 1%
Does not account for all discrepancies...



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NSB effect on discrimination

\Box Effect on acceptance to γ

- Hillas: Scaled parameters degraded
- □ Model : goodness stable
- □ Model 3D : worse fit convergence

Quite similar effect on hadrons





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Toward a diffuse emission analysis

□ Is diffuse emission analysis possible?

□ i.e. Do we understand the instrument enough ?



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Trigger rate

□ With zenith angle correction



Only partially correlated with meteorological measurement (backscattered light, radiometers, ...)

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Conclusions

Various reconstruction techniques (different performances and sensitivity to systematics)

Various background determination techniques (making different assumptions – symmetries)

□ Using part of the FOV as normalisation: a few % precision. Reliable techniques for extended sources up to ~1° scale

But absolute background controlled only at ~ 20% => not suitable yet for diffuse (> FOV) emission

Trying to detect extended, faint sources, is very challenging.
 Acceptance determination needed at 1% or better (absolute)
 Huge work needed to fully understand effect of NSB, stars, atmospheric transparency, ...

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