

Event Reconstruction and Particle Identification with ALICE

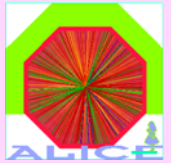
I. Belikov for the ALICE detector performance group (PWG1)



- Introduction
- Offline tracking with the central ALICE detectors
- Charged-particle ID with the central ALICE detectors
- Appendix: A few unclear questions...



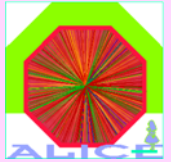
Reconstruction and PID: What is this ?



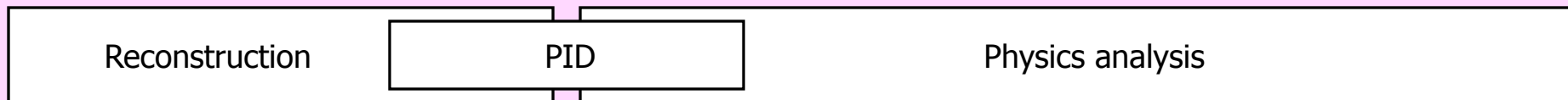
- (Offline) reconstruction and PID is software.
- Reconstruction is everything between the **raw data** and **ESD**.
 - The **raw data** are files containing encoded "positions & ionization" (in pad/wire number, ADC/TDC counts etc).
 - The **Event Summary Data** are files containing fitted particle momenta and vertex positions, probabilities related to PID (in GeV/c, cm, etc).
- **Particle Identification** is everything that provides some **information about the masses** of the registered particles.
 - PID is tightly connected with the reconstruction (tracking needs masses, fitted momenta are needed for PID). PID is based on quite similar algorithms as many parts of reconstruction. PID contributes to ESD. This is a part reconstruction.
 - However, PID extends beyond the reconstruction towards the physics analysis. This is quite fundamental...



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A view on Reconstruction and PID



Mathematics

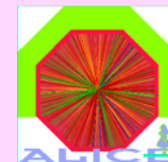
Statistics

Programming

Physics



A view on Reconstruction and PID



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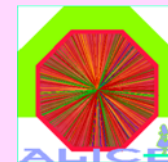
Reconstruction & PID

Programming

Physics



A view on Reconstruction and PID



Mathematics

Statistics

Analyt. geometry
Diff. equations
...

Bayesian methods
Kalman filter
...

Reconstruction & PID

...
Num. algorithms
Design/implement.

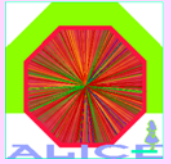
...
Particle prop.
Material prop.

Programming

Physics



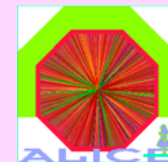
A view on the statistical methods (used in ALICE reconstruction and PID)



Bayesian methods



A view on the statistical methods (used in ALICE reconstruction and PID)



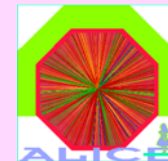
Bayesian methods

Likelihood

(Bayesian, with equal priors)



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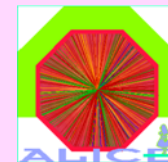
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Kalman filter

(Likelihood, with Gaussian PDFs)



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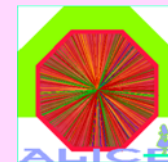
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We are quite used to the Kalman-filter-based tracking, to likelihood-based fitting of histograms, to the Bayesian approach in PID...



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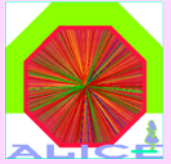
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However, there is nothing wrong about fitting histograms with Kalman filter, or doing a Bayesian tracking ! ☺



What is the Kalman filter ?

Example: measuring the "length of a table"



$l(i)$, $i=1, \dots, N$ -- the results of N successive independent measurements
 σ – the precision of the measurements

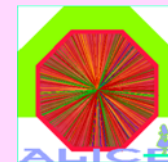
The classical estimate:

- $l(1, \dots, N) = [l(1) + l(2) + \dots + l(N)] / N$; $\sigma^2(1, \dots, N) = \sigma^2 / N$



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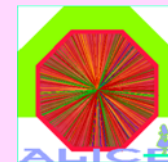
The Kalman filter estimate:

1. $l(1)$, σ (the seed)
2. $l(1,2) = \frac{1}{2} l(1) + \frac{1}{2} l(2) = \frac{1}{2} l(1) + \frac{1}{2} m_2$; ($l(i) \equiv m_i$, $i > 1$, the measurements)
 $\sigma^2(1,2) = \sigma_{12}^2 = \frac{1}{4} \sigma^2(1) + \frac{1}{4} \sigma^2(2) = [1/\sigma^2 + 1/\sigma^2]^{-1} = \frac{1}{2} \sigma^2$
...
 $k+1$. $l(1, \dots, k+1) = w_{1, \dots, k} l(1, \dots, k) + w_k m_{k+1} = \frac{\frac{1}{\sigma_{1, \dots, k}^2}}{\frac{1}{\sigma_{1, \dots, k}^2} + \frac{1}{\sigma^2}} l(1, \dots, k) + \frac{\frac{1}{\sigma^2}}{\frac{1}{\sigma_{1, \dots, k}^2} + \frac{1}{\sigma^2}} m_{k+1}$
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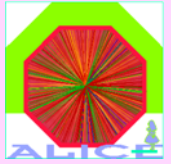
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The final result is the same as the classical !

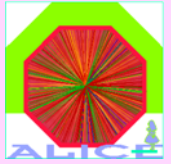


What is so special about the Kalman filter ?





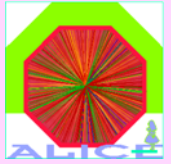
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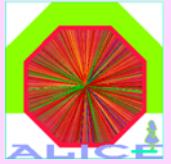
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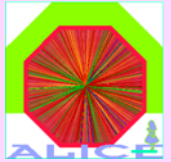


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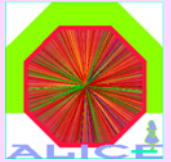
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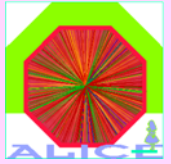
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Surely YES !

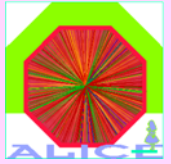


So, why have we chosen the Kalman filter in ALICE ?





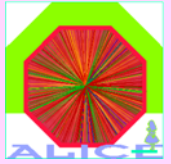
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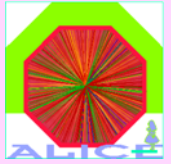


- Computational convenience
(with the conventional, “sequential” hardware)
- Inertia of thinking (after the great success of the famous article by P.Billoir in NIM in 1984)



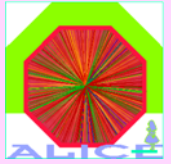
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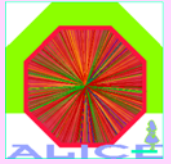


Example: a supervisor choosing a summer student

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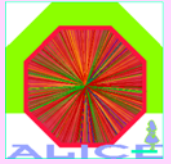


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- The answer depends on:
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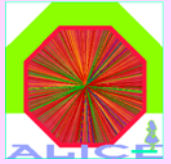


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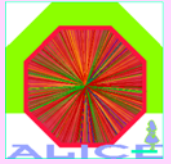
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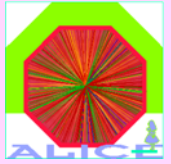


What is so special about the Bayesian approach ?





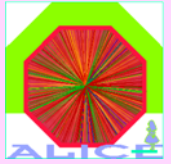
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- It puts together two quite different sources of information
 - The supervisor's preferences are property of the supervisor. They, probably, do not change with time, and so can be precalculated.
 - The numbers of applications by girls/boys is an example of the conditions that are completely external to the supervisor. These may change year-by-year, and so, fundamentally, cannot be calculated once and forever.



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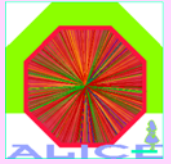


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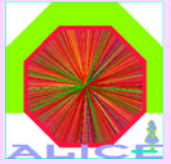
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Yes... Probably...

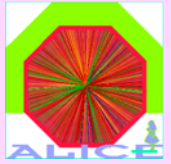


So, why are we doing the Bayesian approach in ALICE ?





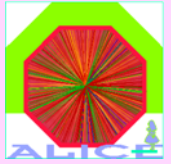
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Already at the level of a single detector.



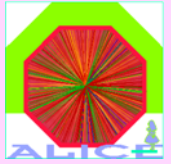
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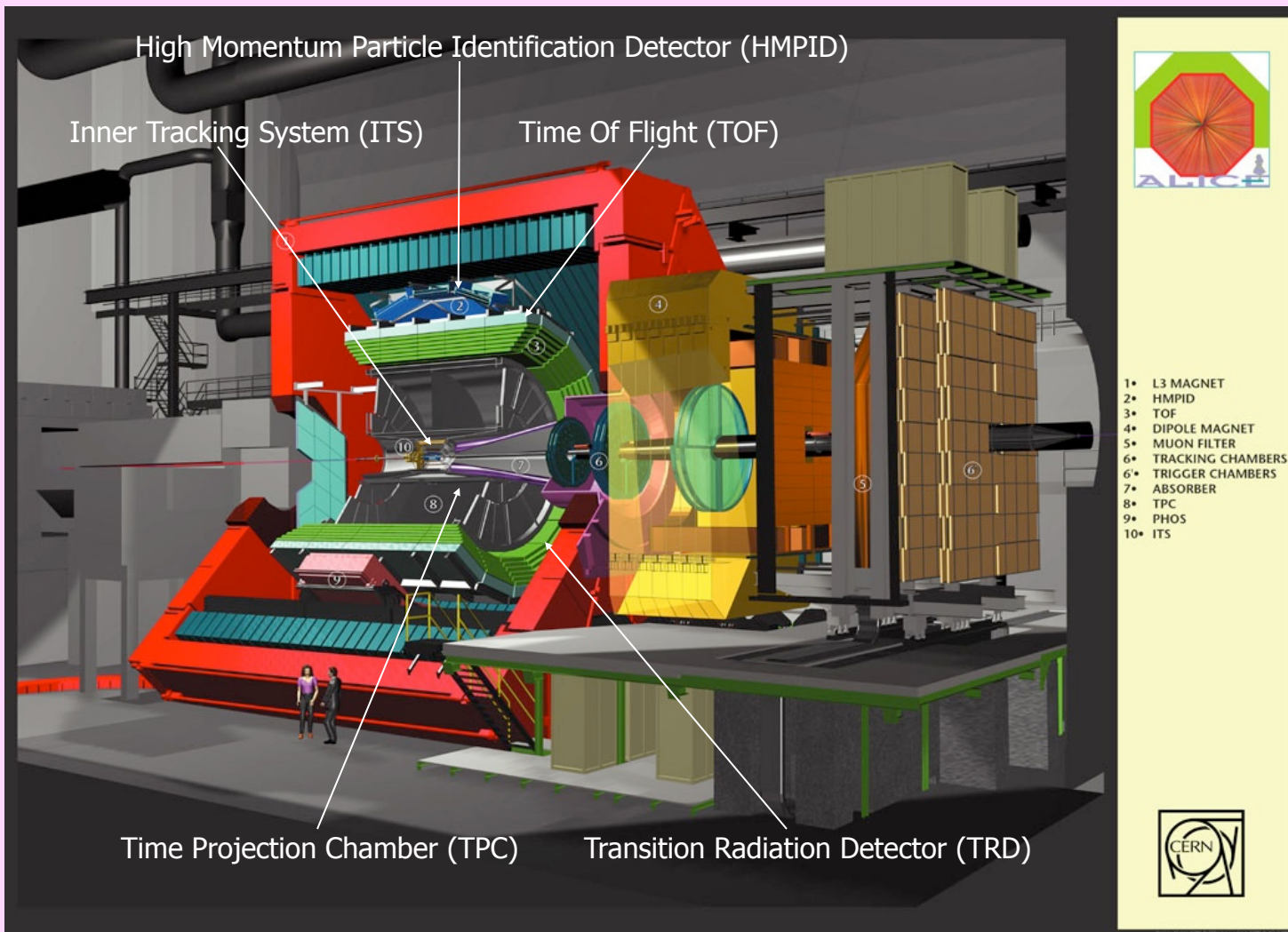
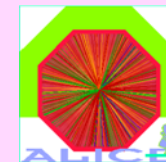


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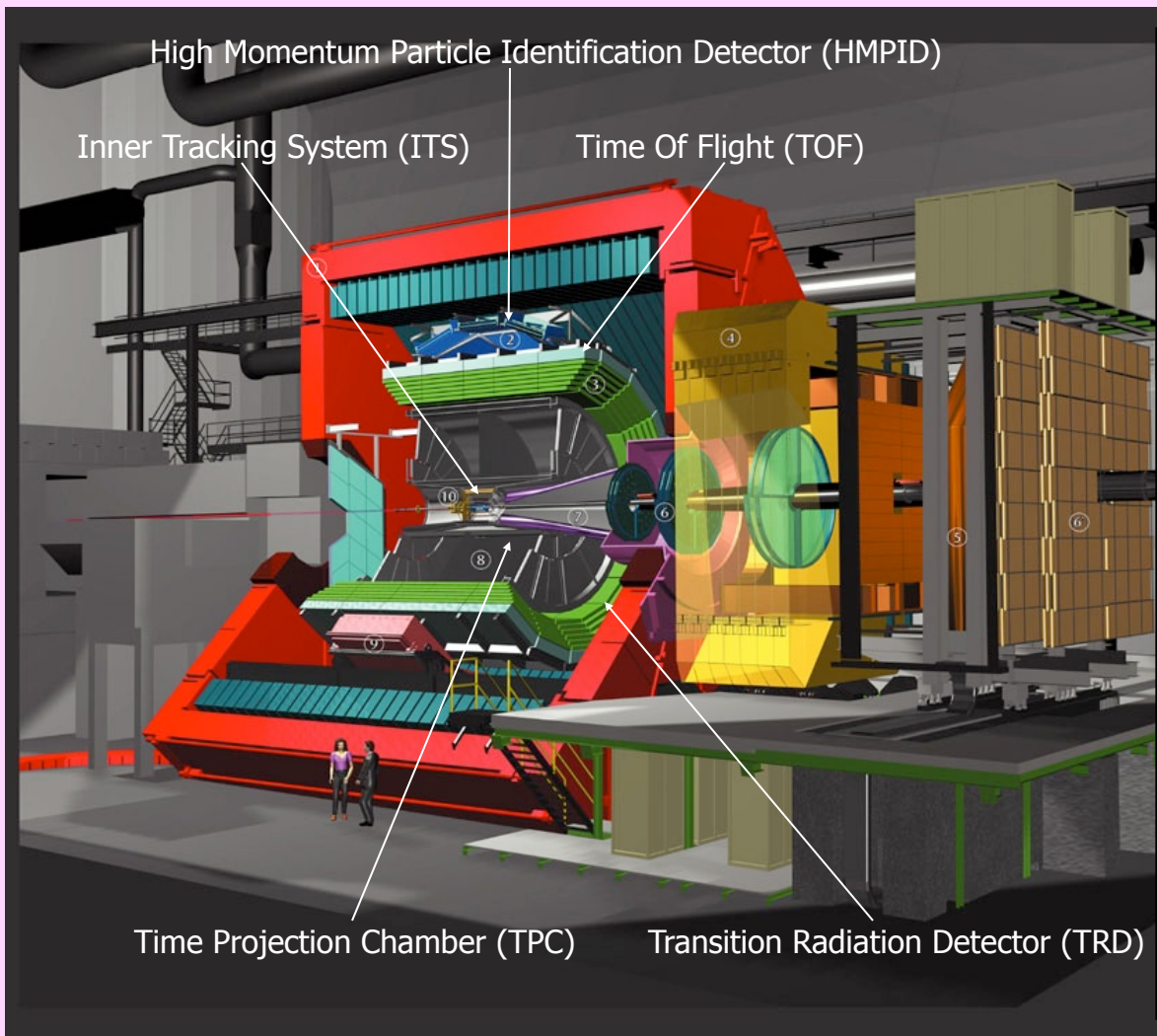
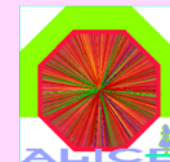


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- Computational convenience, when it comes to combining the PID information over the contributing detectors.
- Gain in the disk space at the level of AOD.

ALICE experiment at LHC



ALICE experiment at LHC



TPC ($-0.9 < \eta < 0.9$) tracking efficiency:

$\sim 80\%$ for $P_t < 0.2$ GeV/c

(limited by decays),

$\sim 90\%$ for $P_t > 1$ GeV/c

(limited by dead zones),

for > 10000 tracks in the TPC.

Momentum resolution ($B=0.5$ T):

$\sim 1\%$ at $P_t = 1$ GeV/c,

$\sim 5\%$ at $P_t = 100$ GeV/c (ITS+TPC+...).

Precise secondary vertexing

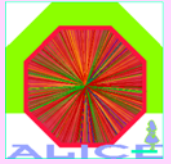
better than $100 \mu\text{m}$ (ITS).

Excellent charged PID capability:

from $P \sim 0.1$ GeV/c upto a few GeV/c,
(upto a few tens GeV/c, TPC rel. rise),
electrons in TRD, $P > 1$ GeV/c
(ITS+TPC+TRD+TOF+HMPID+...).

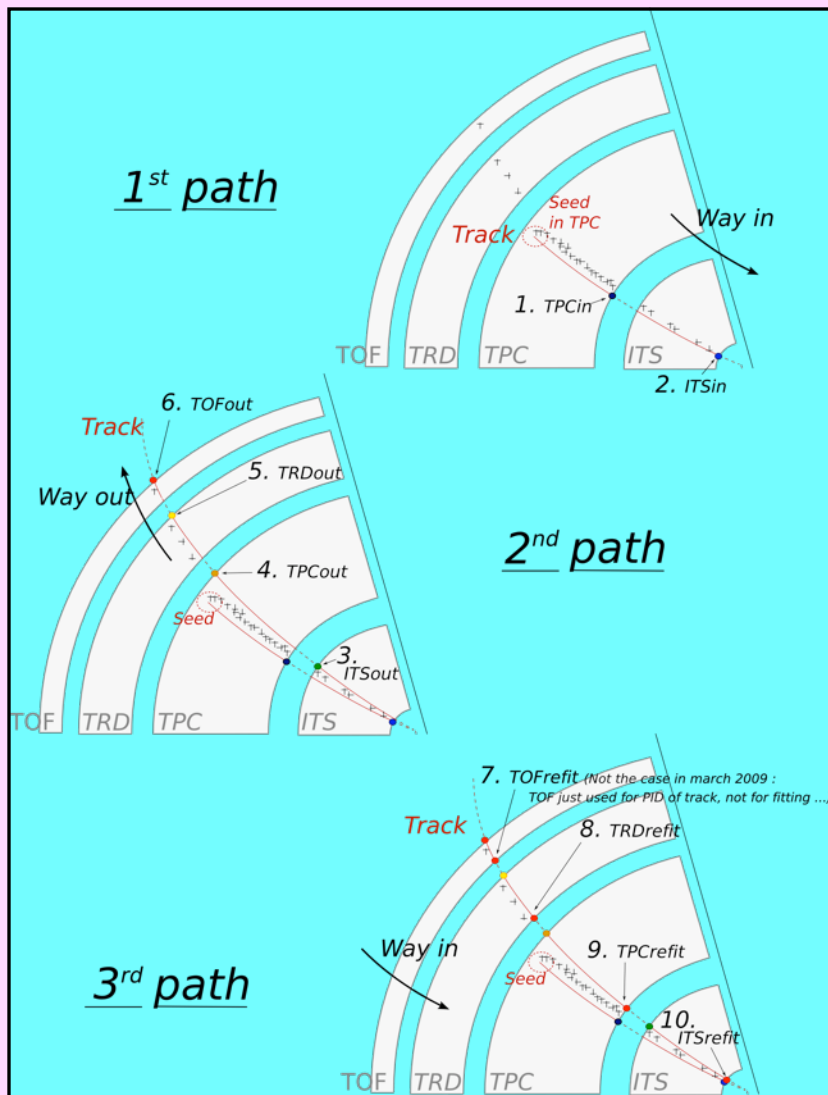
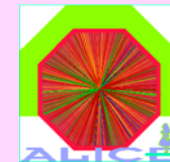


The general reconstruction strategy

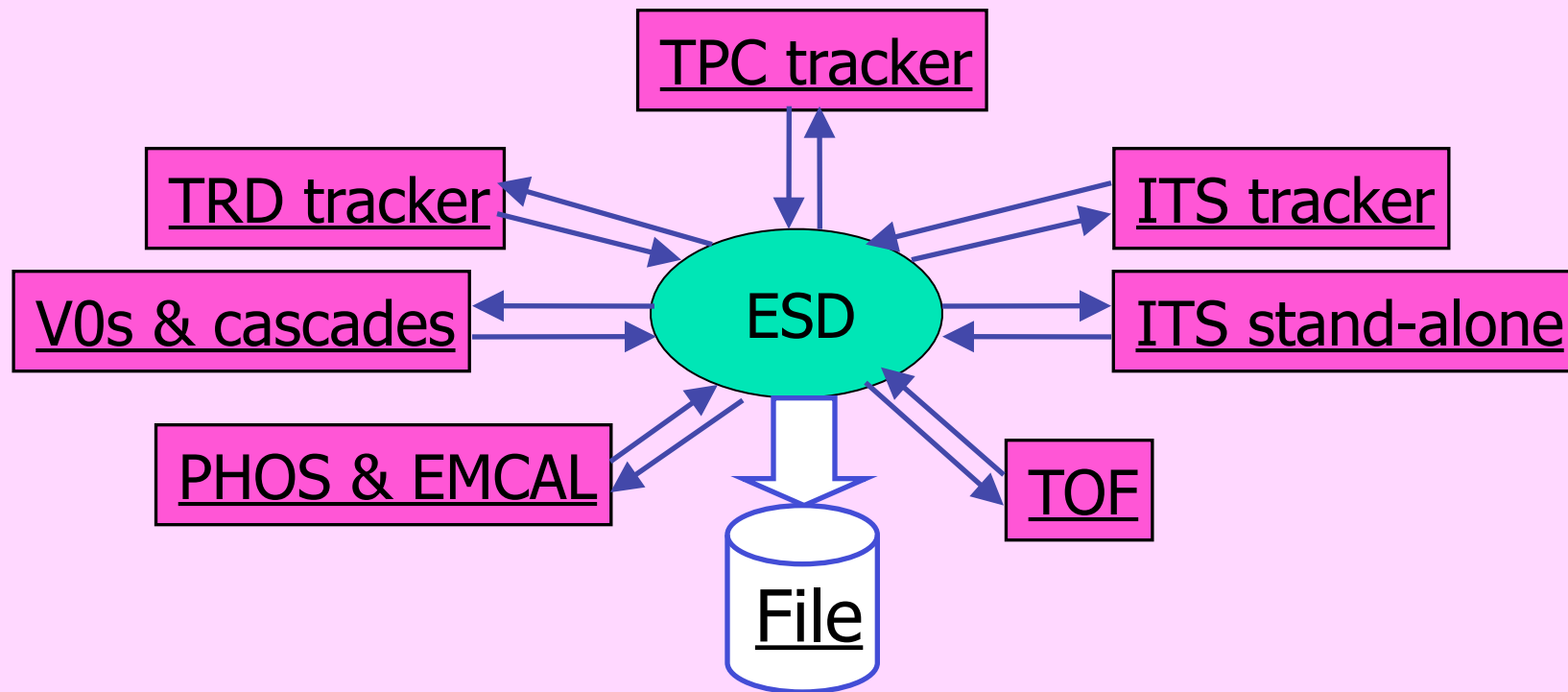


- Cluster finding in the detectors (centre of gravity)
 - Unfolding of overlapped clusters (optional)
- Primary vertex reconstruction using the ITS (SPD)
 - Pileup detection (optional)
- “Seeding” in TPC (with/out the vertex constraint)
 - Later, also the “seeding” in ITS and TRD (optional)
- Combined tracking
 - On-the-fly kink and V0 reconstruction (optional)
- Primary vertex using the tracks
- Secondary vertices using the tracks (V0s, cascades)

The three passes of the combined tracking

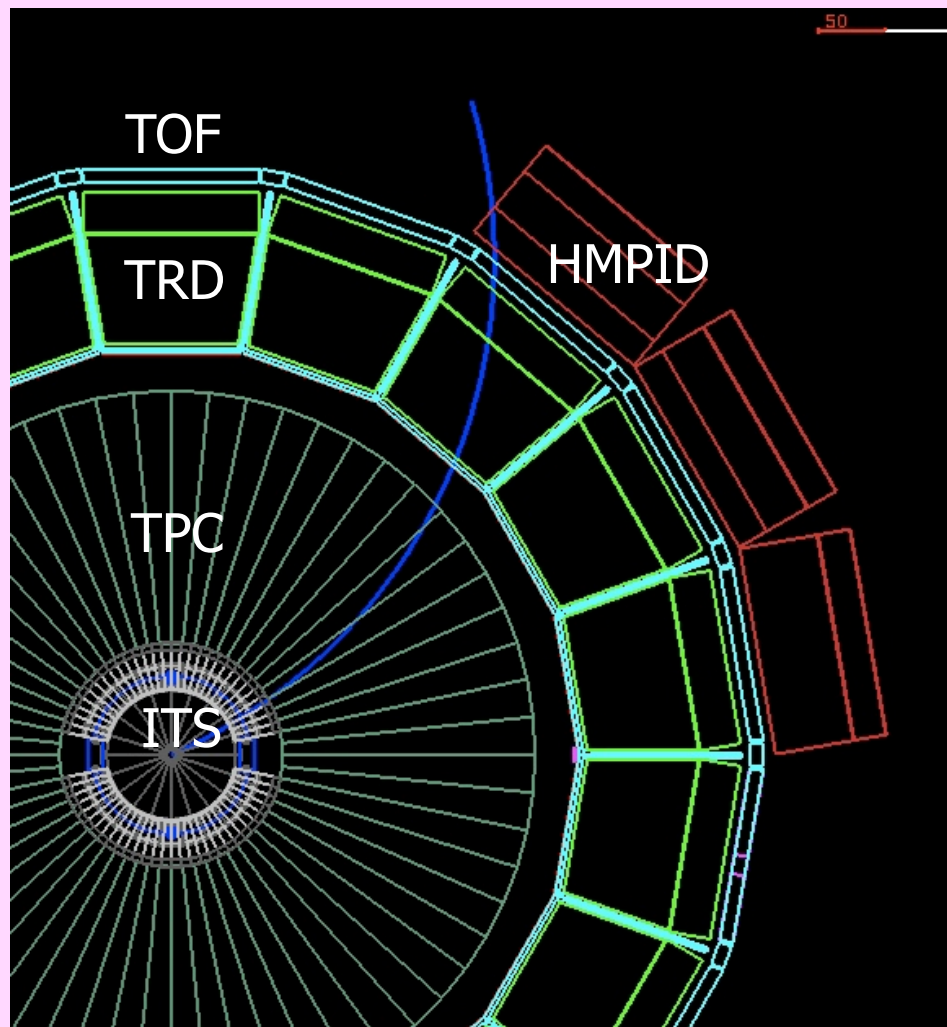
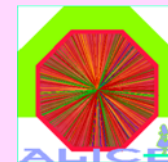


1. "Seeds" in TPC. Tracking from the outer to the inner wall of TPC. The same in ITS.
 - Track parameters are OK
 - PID is not yet OK
2. Tracking from the inner to outer layer of ITS. The same in TPC. The same in TRD. Matching with TOF, HMPID, PHOS/EMCAL
 - PID is OK
 - Track parameters are not OK
3. Tracking from the outer to inner TRD wall. The same in TPC. The same in ITS.
 - PID is OK
 - Track parameters are also OK



- The general initialization and the processing sequence is defined by AliReconstruction.
- The process is configured/triggered by a special macro rec.C

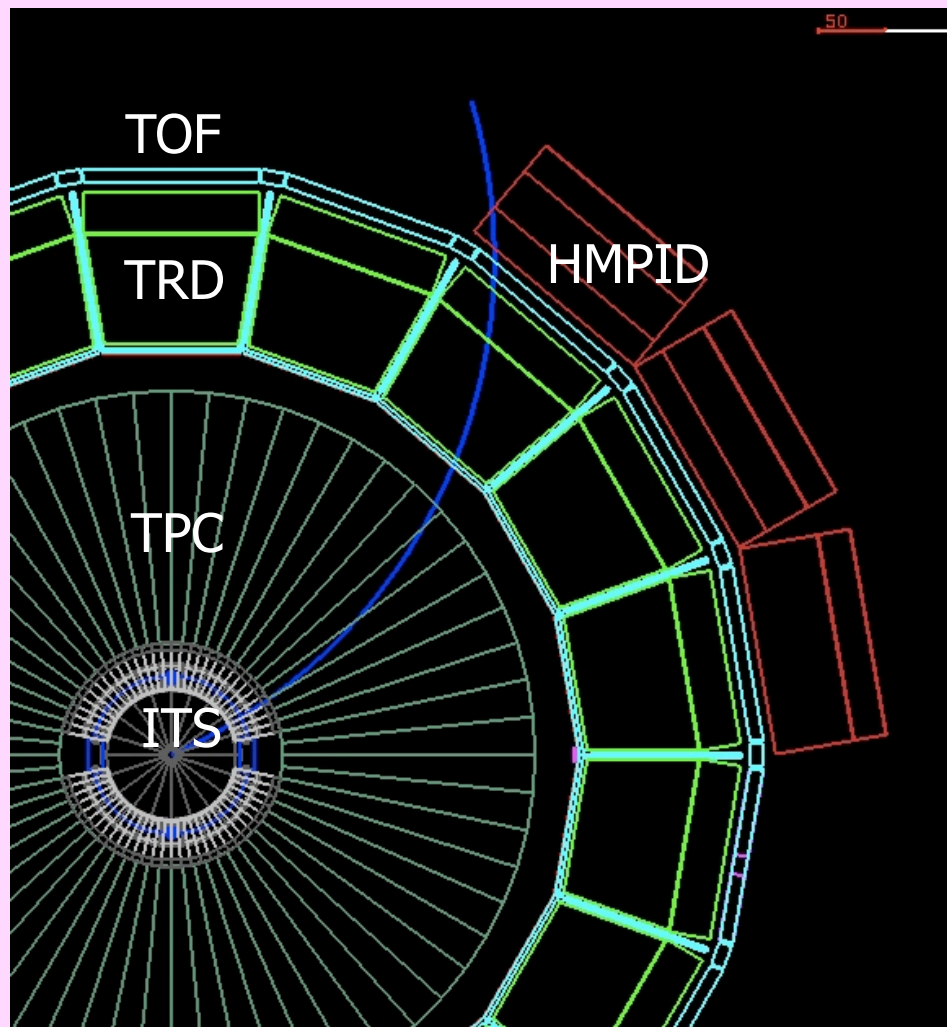
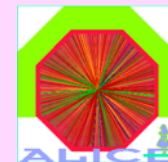
Charged PID with central ALICE



The same track can simultaneously be registered by 5 detectors that

- have quite different PID response,
- are efficient in complementary momentum ranges.

Charged PID with central ALICE

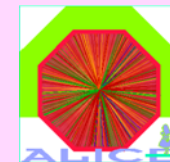


The same track can simultaneously be registered by 5 detectors that

- have quite different PID response,
 - are efficient in complementary momentum ranges.
-
- The PID procedure cannot be Kalman-like (PDFs are not Gaussian).
 - It cannot be Likelihood-like either (the priors cannot be fixed once and forever)...



Bayesian approach in PID



Probability to be a particle of **i**-type (**i** = **e**, μ , π , **K**, **p**, ...),
if the PID signal in the detector is **S**:

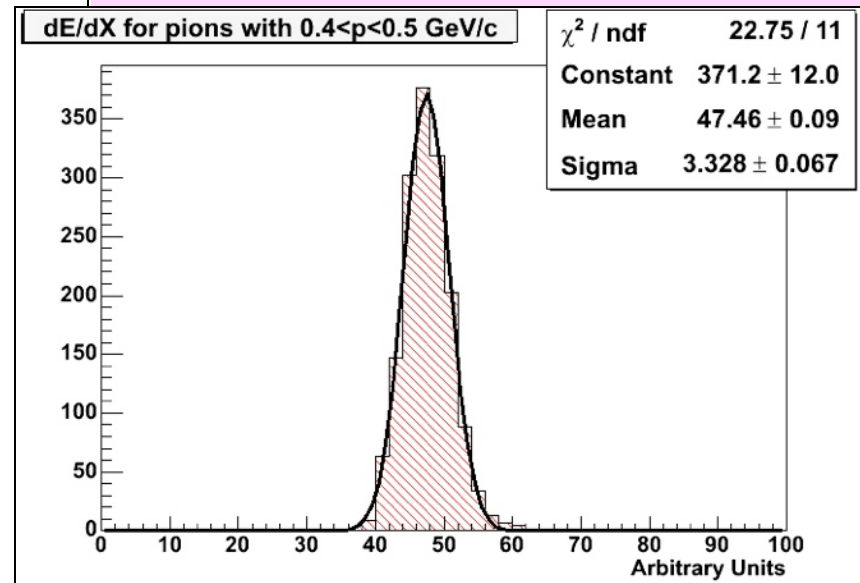
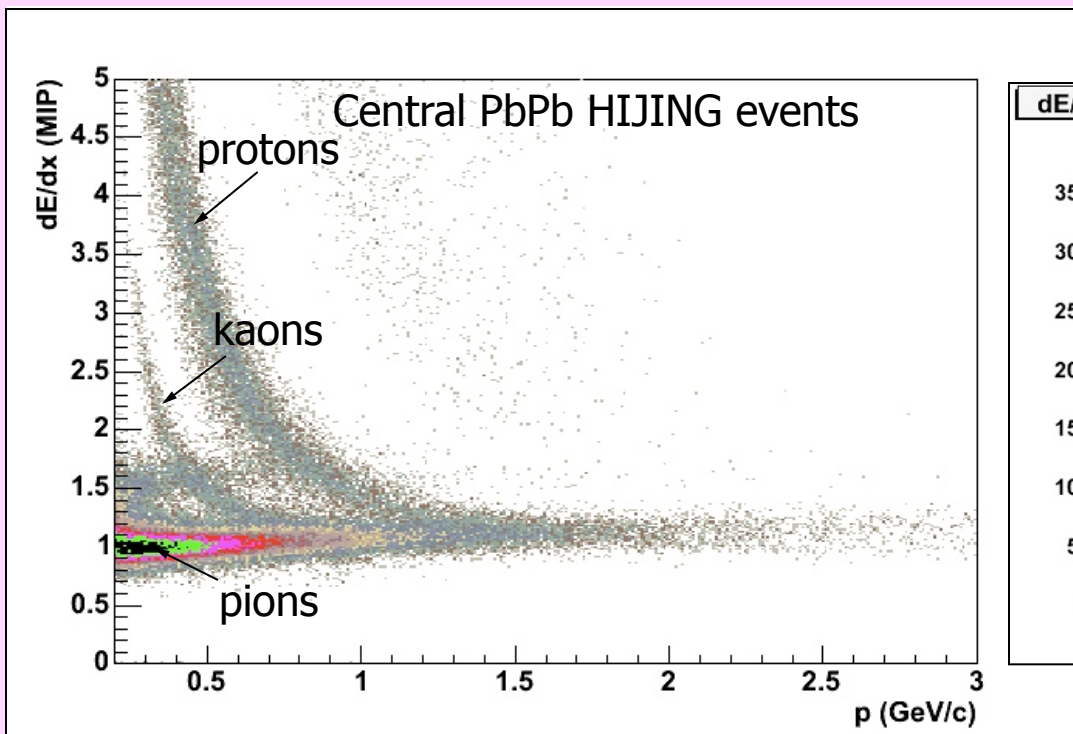
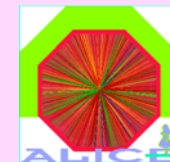
$$w(i | s) = \frac{C_i r(s|i)}{\sum_{k=e,\mu,\pi,\dots} C_k r(s | k)}$$

- **C_i** - a priori probabilities to be a particle of the **i**-type.
“Particle concentrations”, that depend on the event and track selection.
- **r(s|i)** – conditional probability density functions to get the signal **S**, if a particle of **i**-type hits the detector.
“Detector response functions”, depend on properties of the detector.

In the case of N contributing detectors: $r(s_1, \dots, s_N | i) \sim \prod_{d=1}^N r(s_d | i)$

Obtaining the conditional PDFs

Example: "TPC response function"



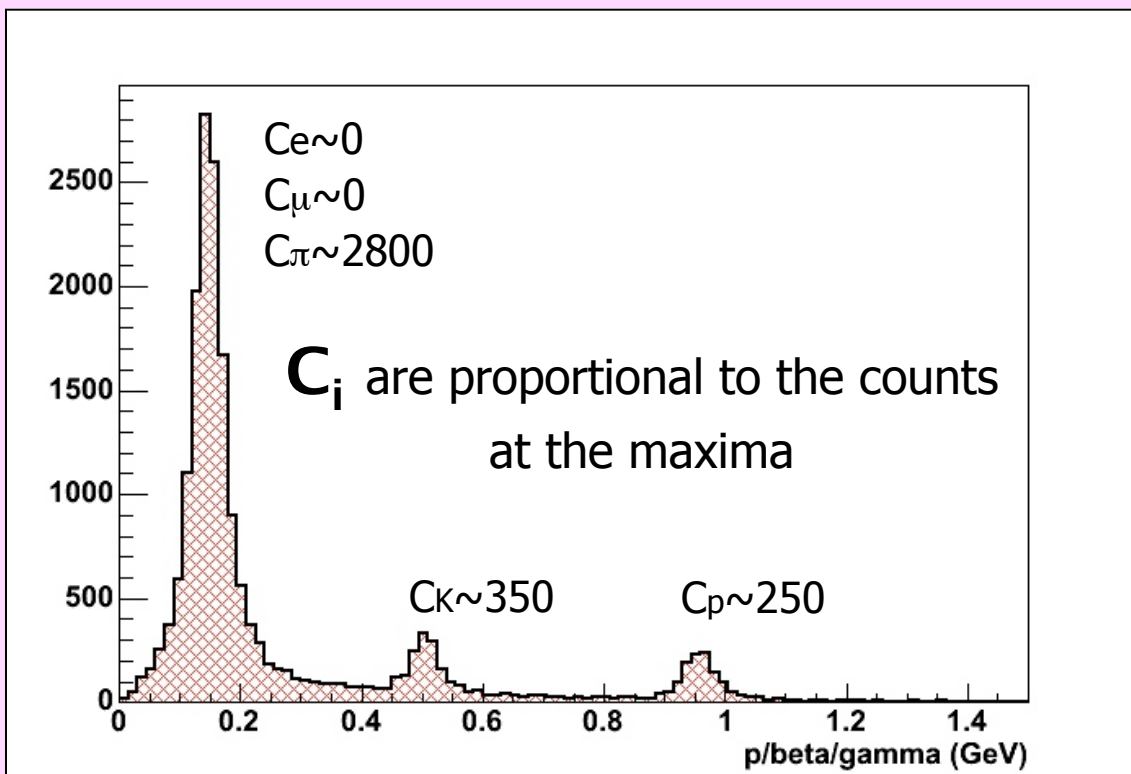
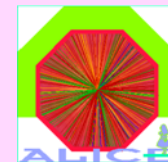
For each momentum $\mathbf{p}$ the function $\mathbf{r}(\mathbf{s}|\mathbf{i})$ is a Gaussian with

- centroid $\langle dE/dx \rangle$ given by the Bethe-Bloch formula and
- sigma $\sigma = 0.08 \langle dE/dx \rangle$

This is a property of the detector (TPC). Can be prepared in advance !

Obtaining the a priori probabilities

("particle concentrations")

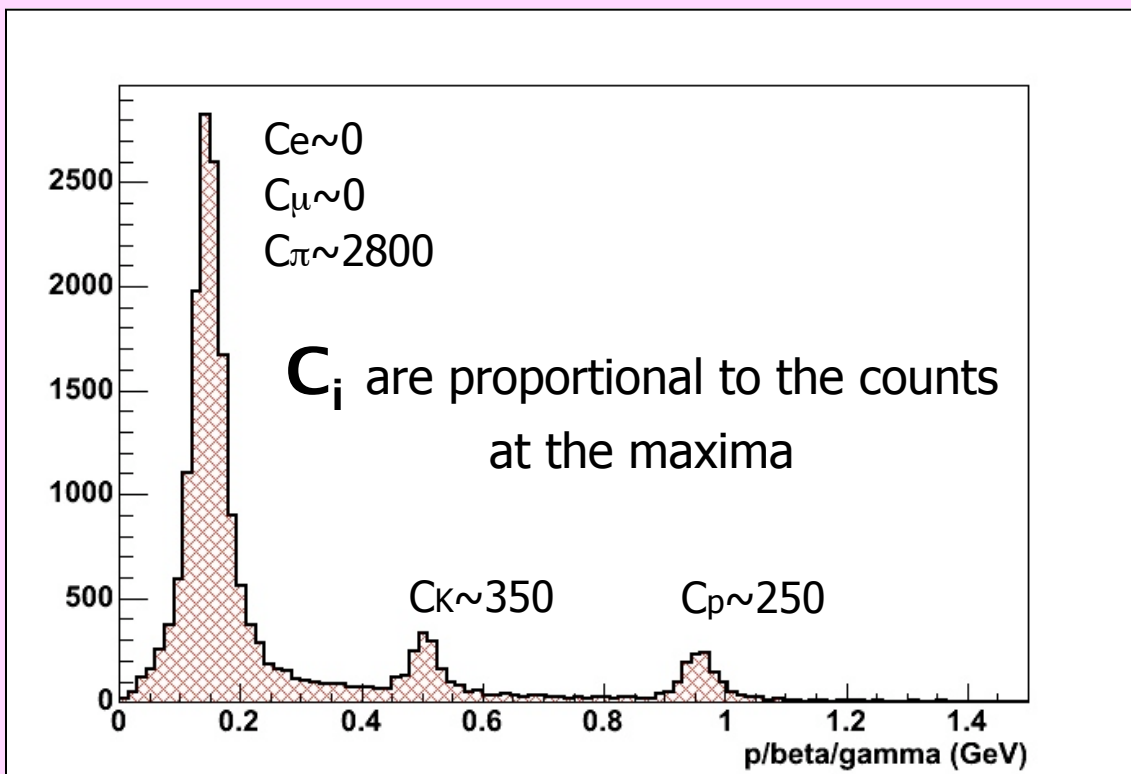
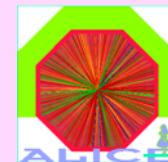


β by TOF, p by TPC

1. Sometimes, we may know the priors (V0s, cascades)
2. Sometimes, we can get the priors by iterating over the data
3. Anytime, we can use the raw PID signals
 - Simple histogramming
 - Complicated fits...

Obtaining the a priori probabilities

("particle concentrations")



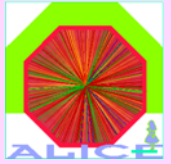
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2. Sometimes, we can get the priors by iterating over the data
3. Anytime, we can use the raw PID signals
 - Simple histogramming
 - Complicated fits...

The "particle concentrations" depend on the event and track selection.
They cannot be prepared once and for all kinds of analysis !

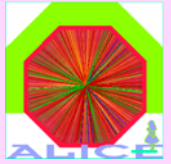


Fine, but what is the advantage ?





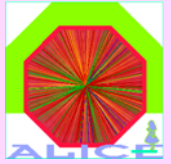
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- The raw PID signals do not have to be stored for all the tracks (big gain in disk space for AOD)



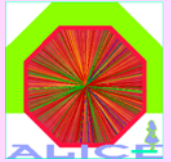
Fine, but what is the advantage ?



- The raw PID signals do not have to be stored for all the tracks (big gain in disk space for AOD)
- Much less parameters to fit at the analysis level
 - In fact, the “amplitudes” only. Because the “centroids and sigmas” are already given by the response functions (precalculated by reconstruction).



The three parts of the PID procedure

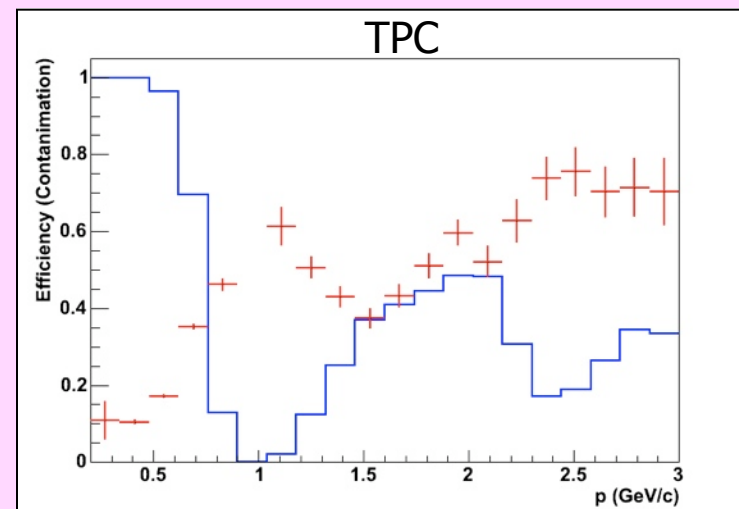
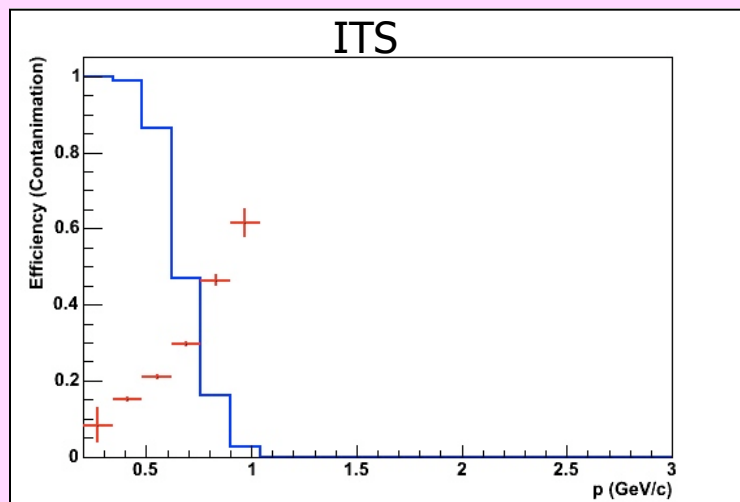
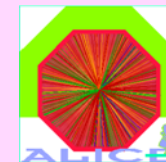


- Calibration part, belongs to the calibration software.
Obtaining the single detector response functions.
Done by detector experts.
- "Constant part", belongs to the reconstruction software.
Calculating (for each track) the values of detector response functions, combining them and writing the result to the Event Summary Data.
Done automatically, in massive reconstruction runs on the Grid.
- "Variable part", belongs to the analysis software.
Estimating (for a subset of tracks selected for a particular analysis) the concentrations of particles of each type, calculating the final PID weights by means of Bayes' formula using these particle concentrations and the combined response stored in the ESD.
Done by physicists involved in this particular analysis.



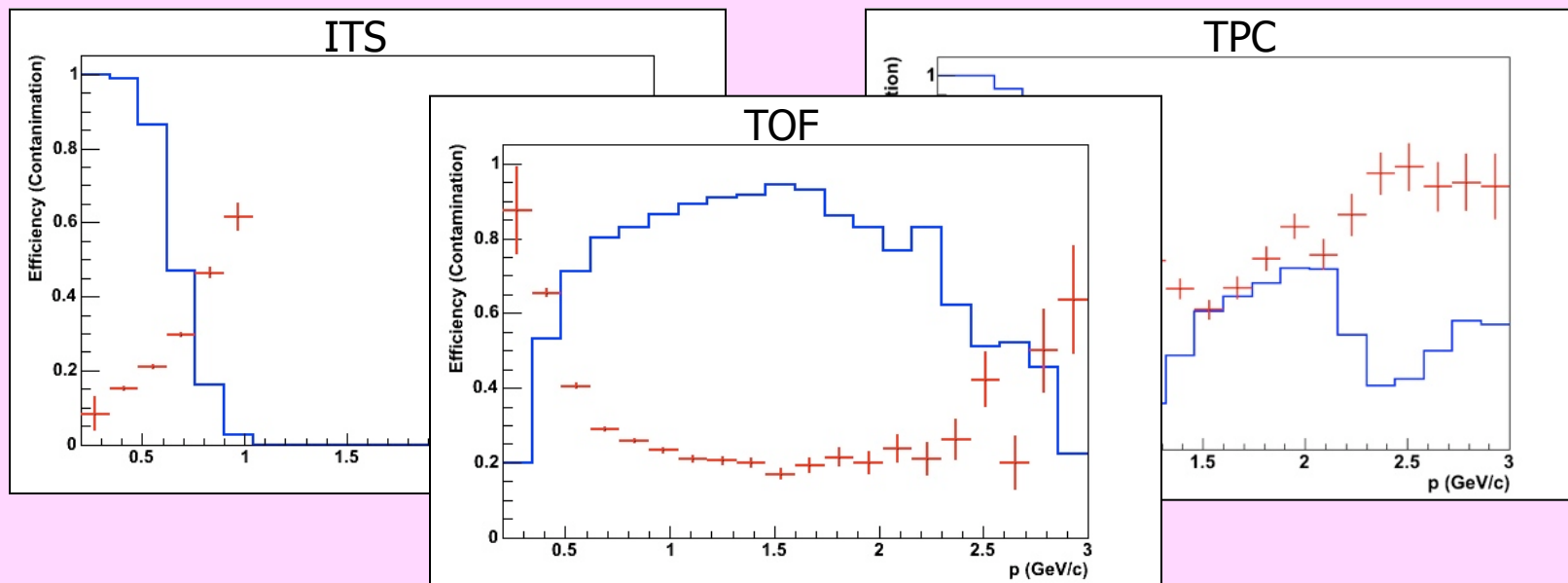
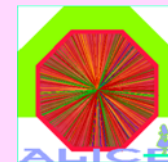
Example: Kaon identification with ITS,TPC and TOF

(central PbPb HIJING events)





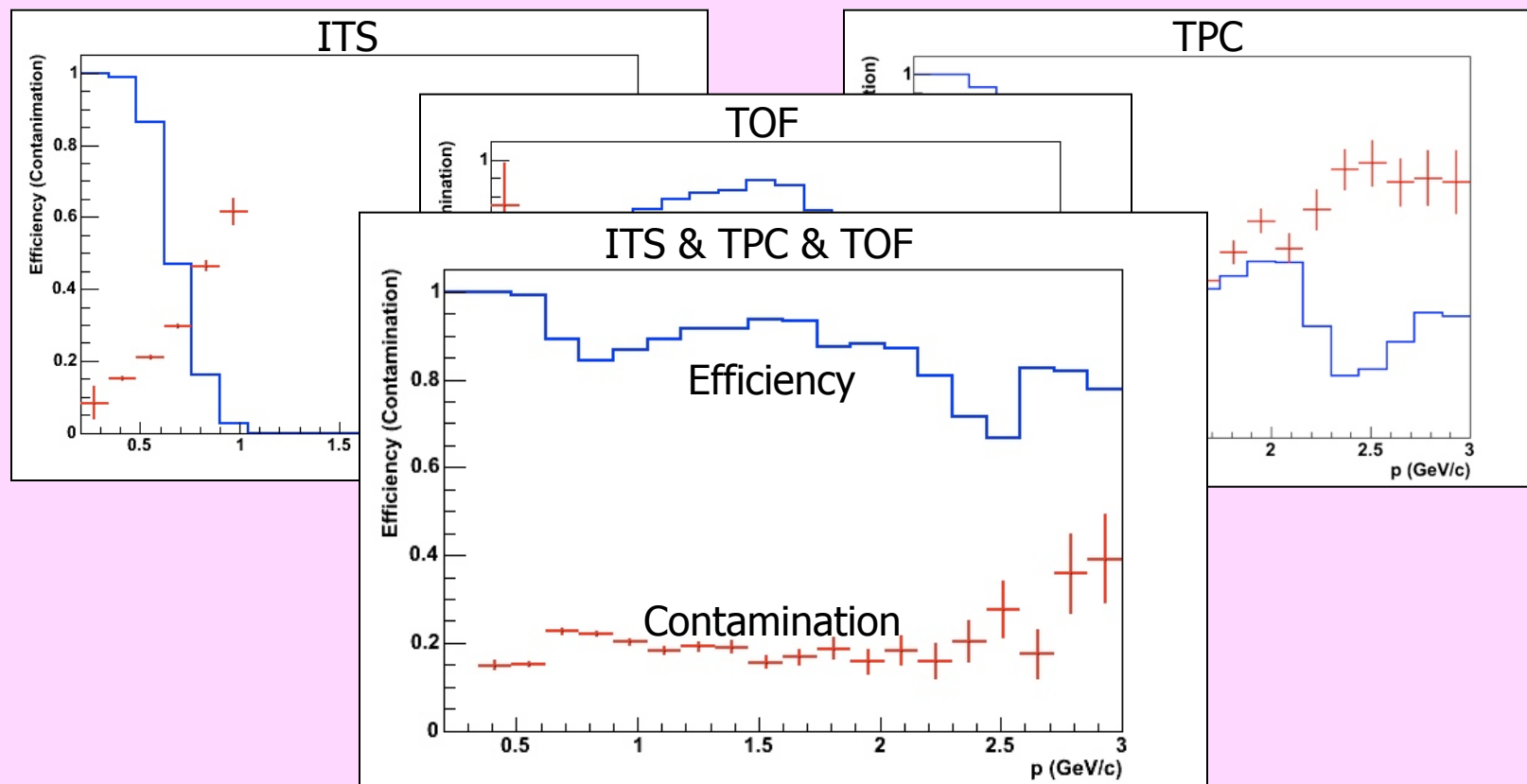
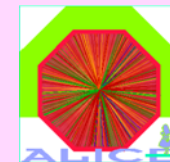
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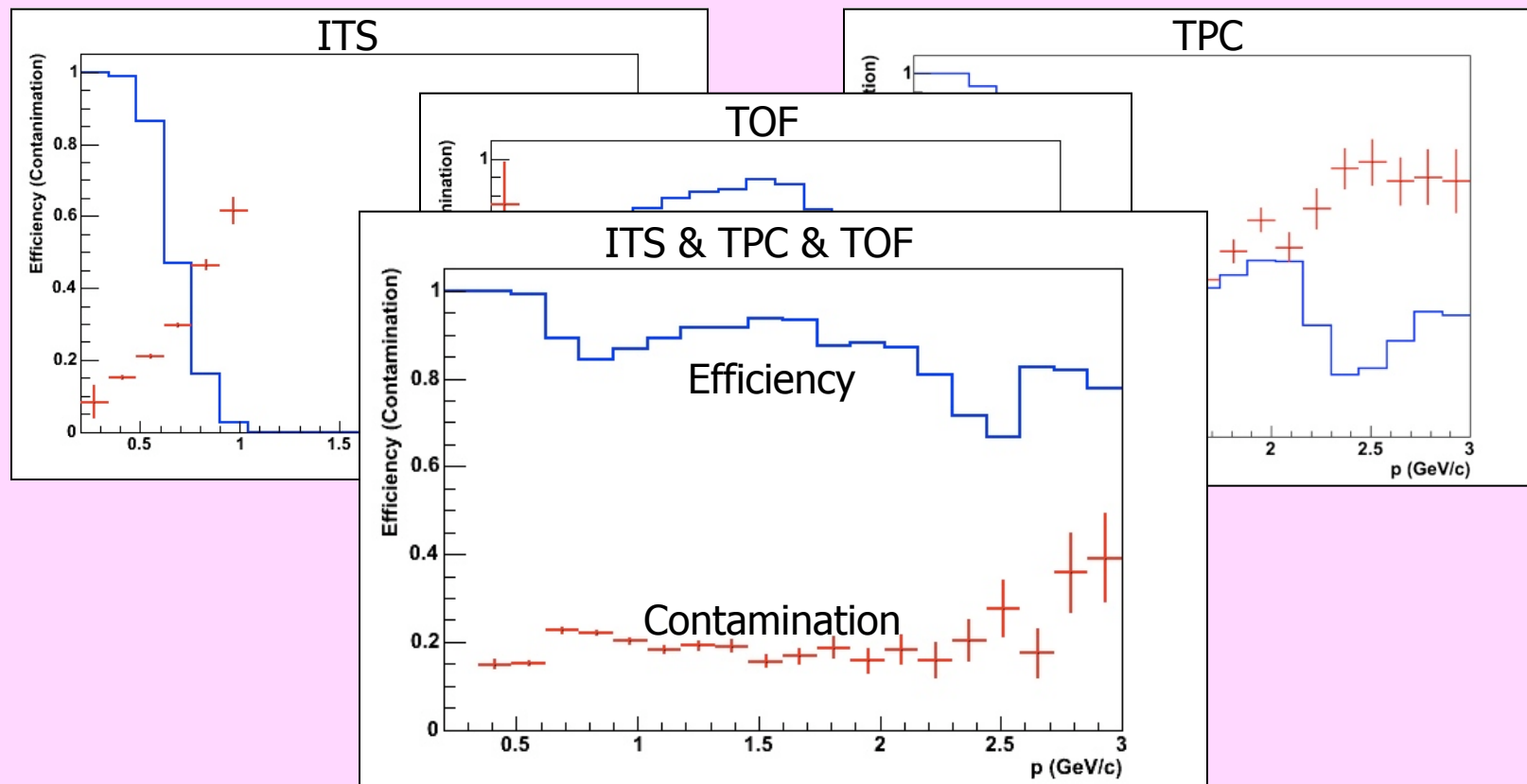
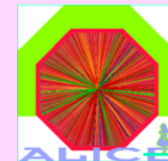
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Example: Kaon identification with ITS,TPC and TOF

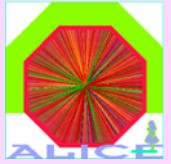
(central PbPb HIJING events)



Efficiency of the combined PID is higher (or equal) and the contamination is lower (or equal) than the ones given by any of the detectors stand-alone.

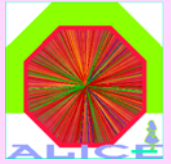


A complementary approach: n-sigma cuts





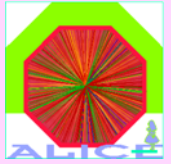
A complementary approach: n-sigma cuts



- Guarantees a definite and constant over the momentum efficiency. Does not deal with the priors !
 - Does not tell anything about the contamination
 - Does not maximize the significance



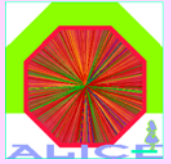
A complementary approach: n-sigma cuts



- Guarantees a definite and constant over the momentum efficiency. Does not deal with the priors !
 - Does not tell anything about the contamination
 - Does not maximize the significance
- Everything that concerns the response functions is the same as for the Bayesian
 - A big piece of software can (and must) be shared by the two approaches.

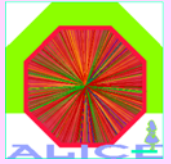


Conclusions





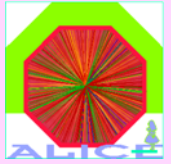
Conclusions



- Reconstruction and PID in ALICE are challenging and quite interesting themselves.



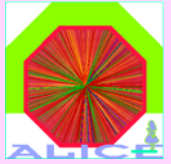
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- However, ALICE physics is even more interesting.



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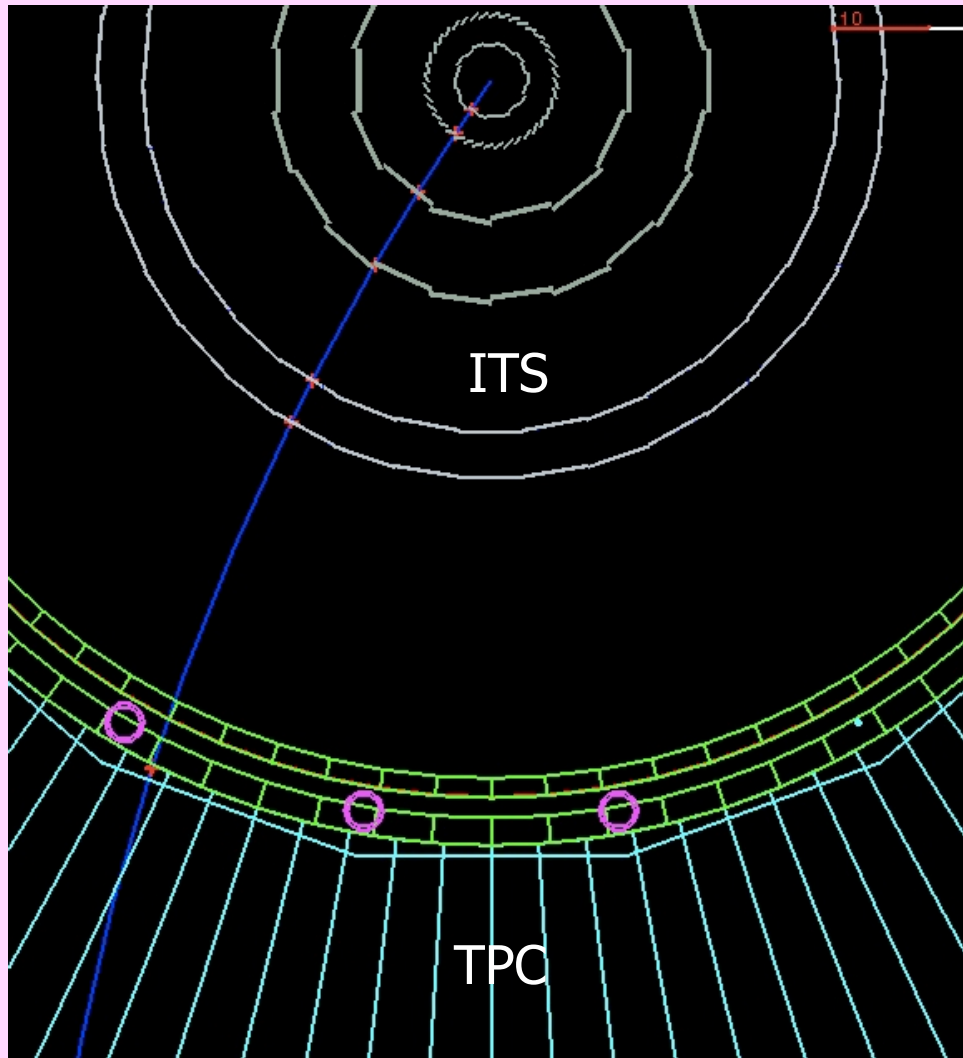
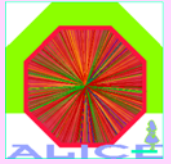


- Reconstruction and PID in ALICE are challenging and quite interesting themselves.
- However, ALICE physics is even more interesting.
- It's about the time to start doing physics ! 😊

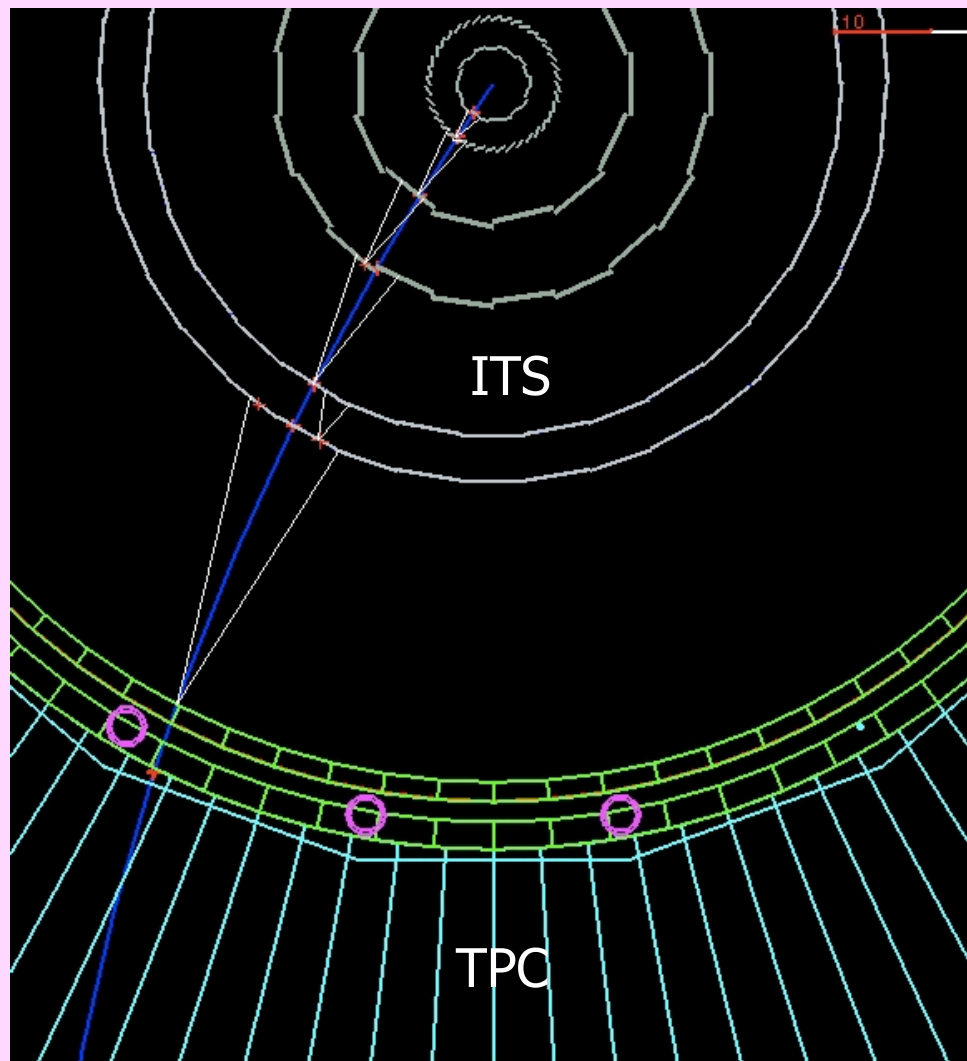
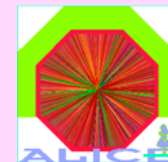


Appendix: A few unclear questions...

Statistical problems with track finding in ITS

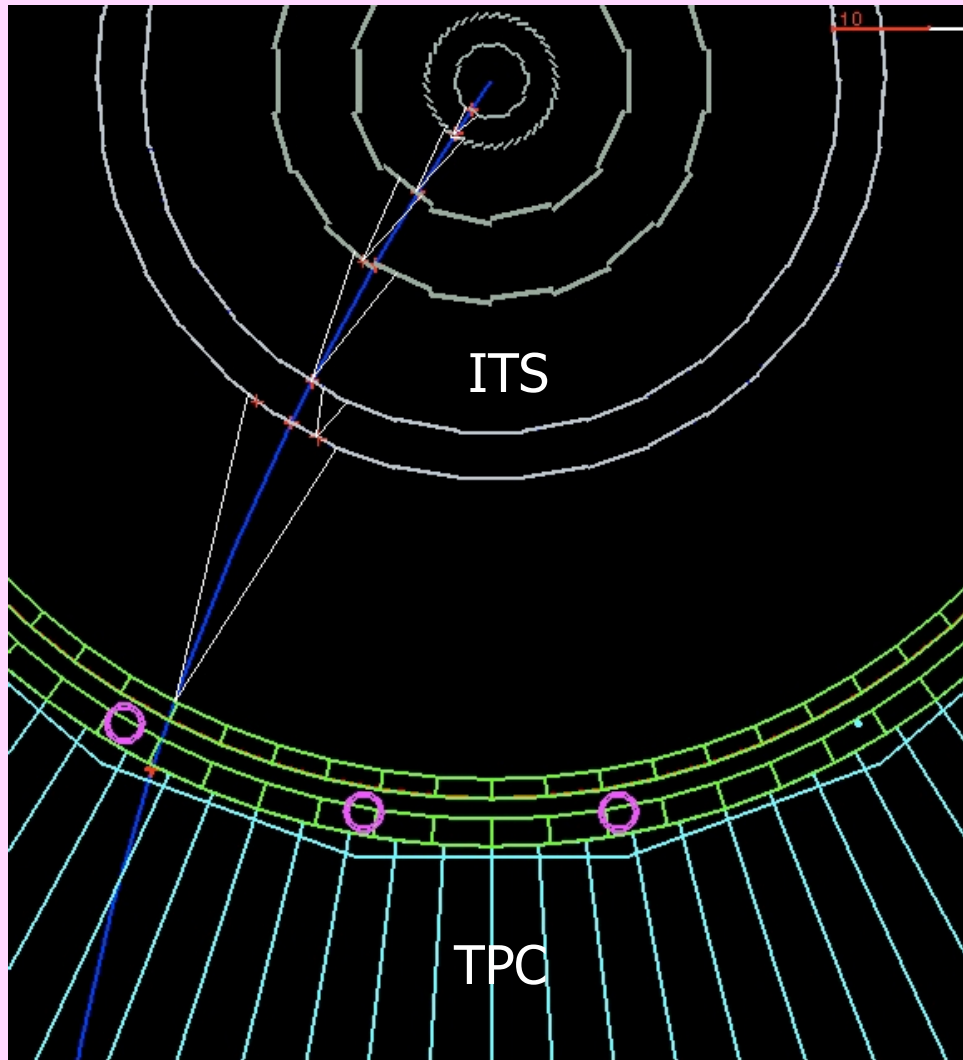


Statistical problems with track finding in ITS



Several clusters within
the “road” defined by
multiple scattering...

Statistical problems with track finding in ITS

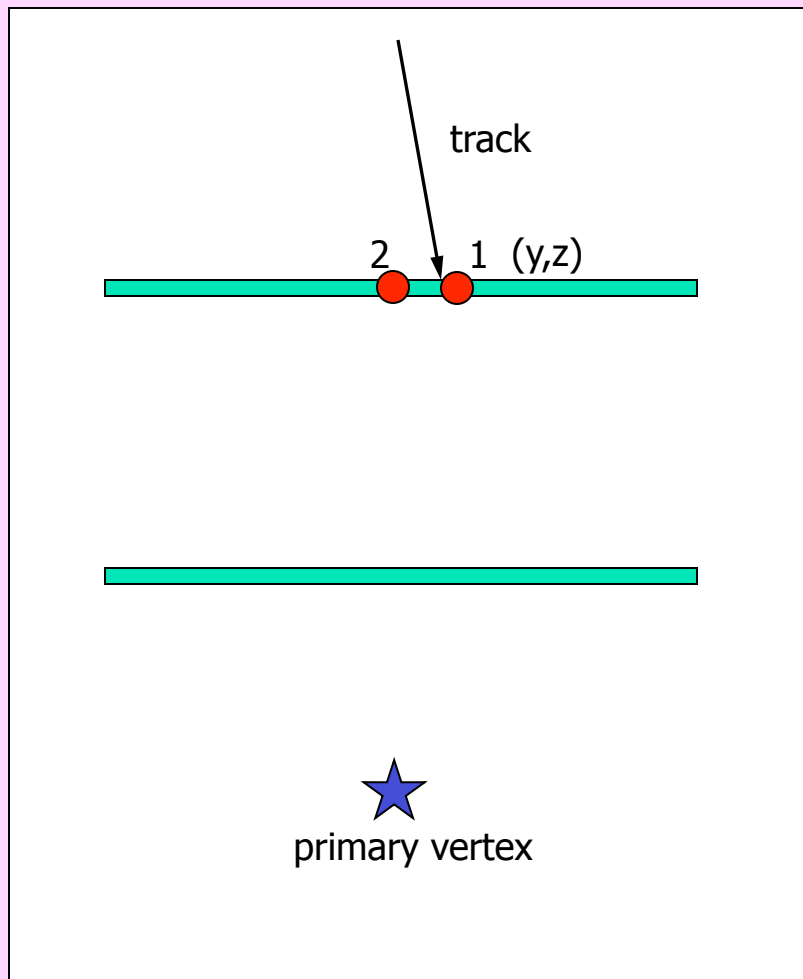
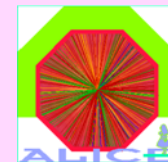


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Suggested solution:

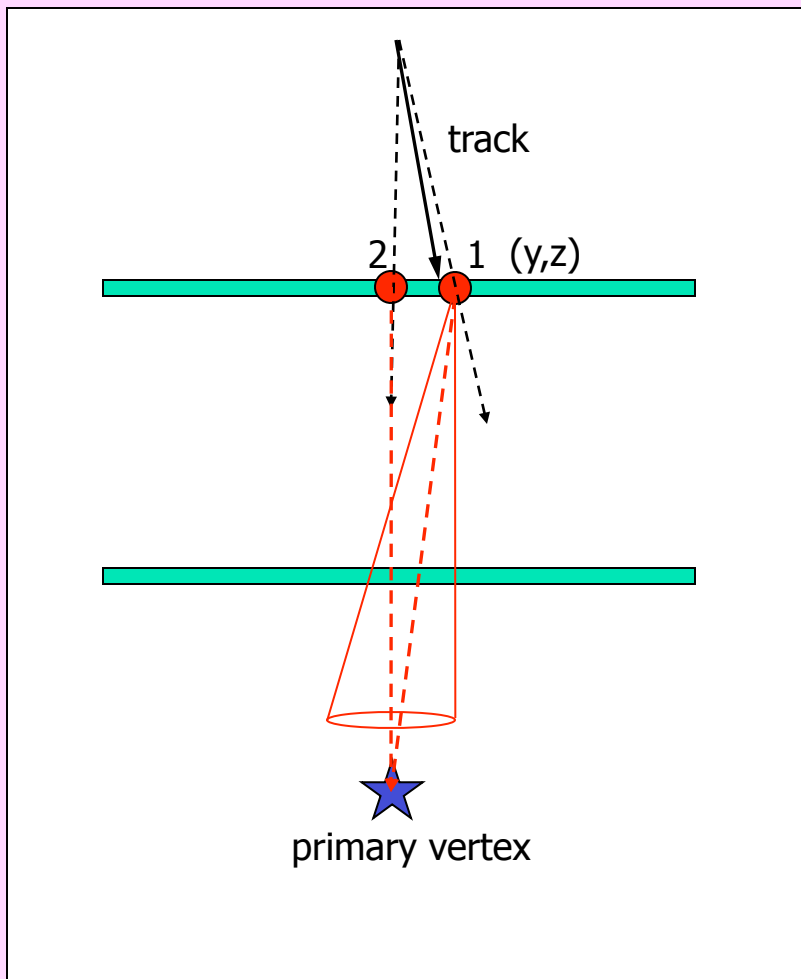
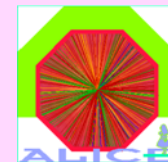
- Investigation of the whole tree of possible prolongations.
- Applying a “vertex constraint” (1st pass).

Ad-hoc "vertex constraint"



Looking at the cluster position only,
the cluster #1 is "better".

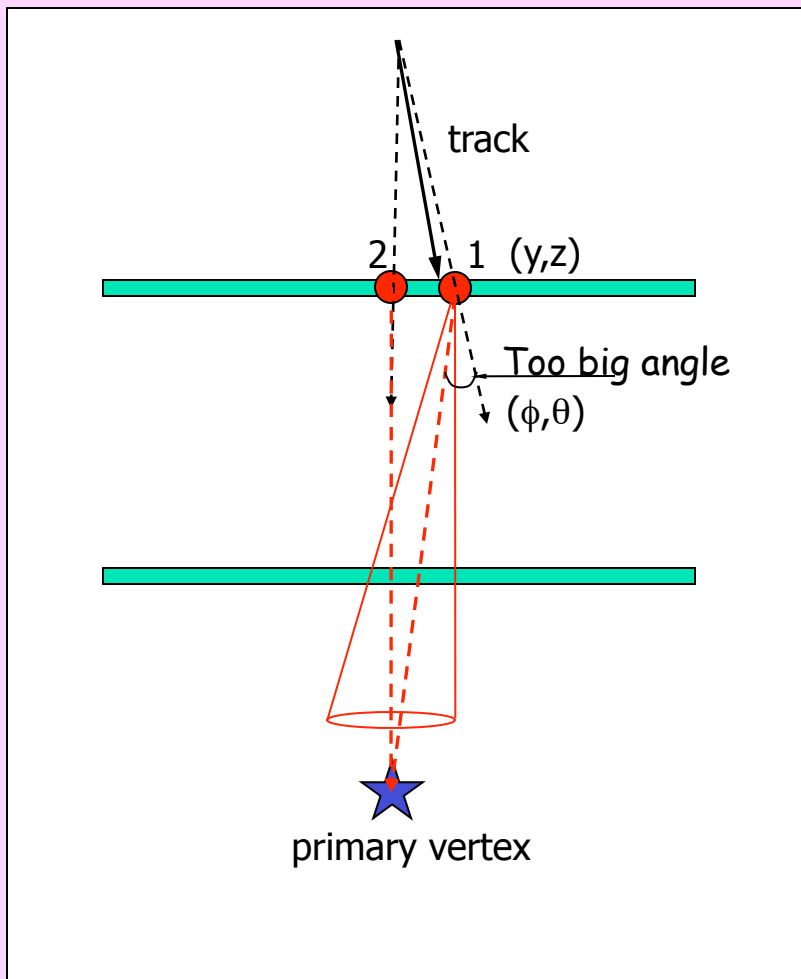
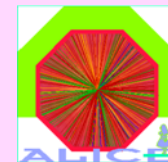
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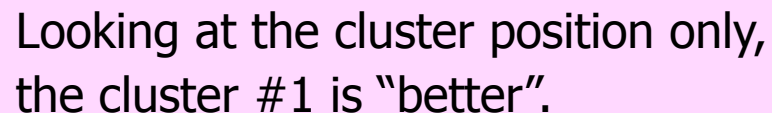
But, if also taking into account the direction towards the primary vertex, the cluster #2 becomes more preferable...

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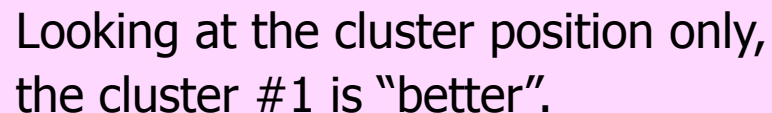
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Technically, this is done by extending the "measurement" $(y,z) \rightarrow (y,z,\phi,\theta)$



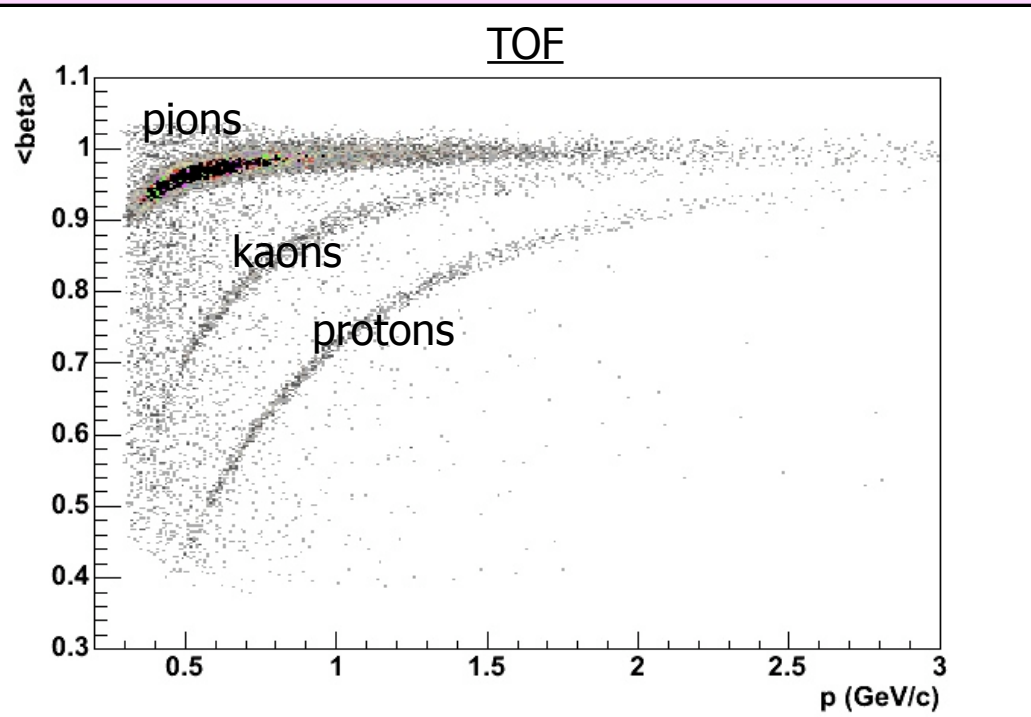
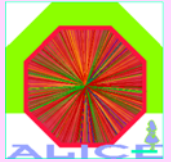
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A question:

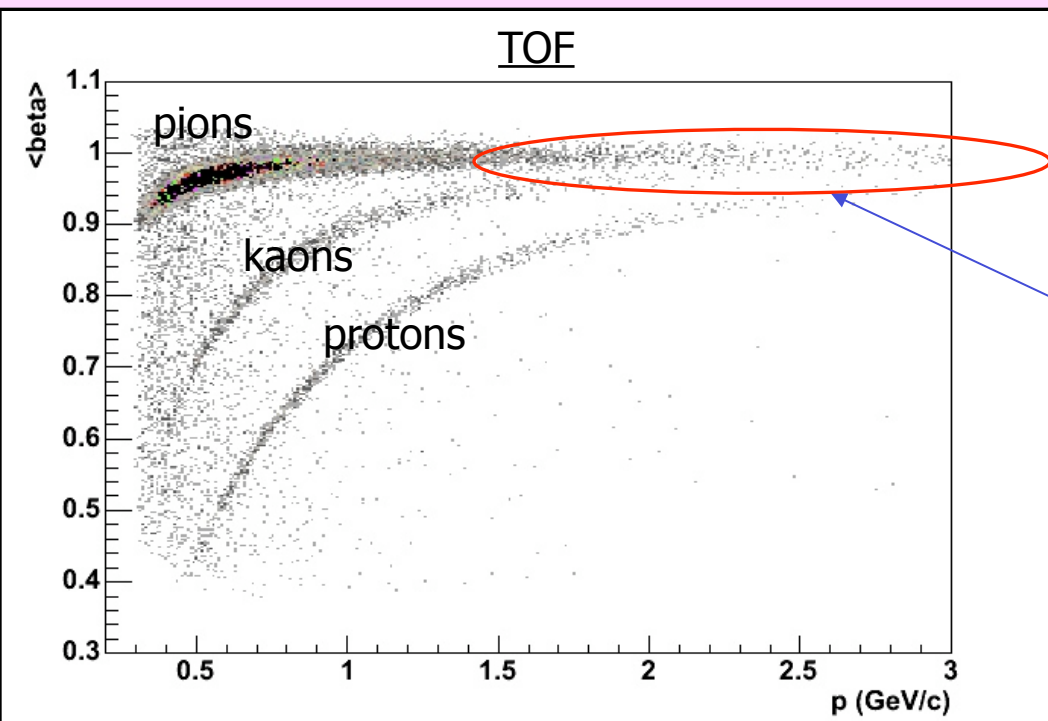
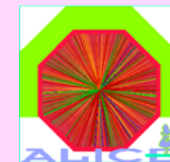
Can all this be justified ? Improved ?
(especially, if applied the same track
repeatedly ?)

The high-momentum limit for PID



The Bayesian calculations nicely glue together the momentum sub-ranges, but, as the momentum goes up, the "separation power" vanishes, and...

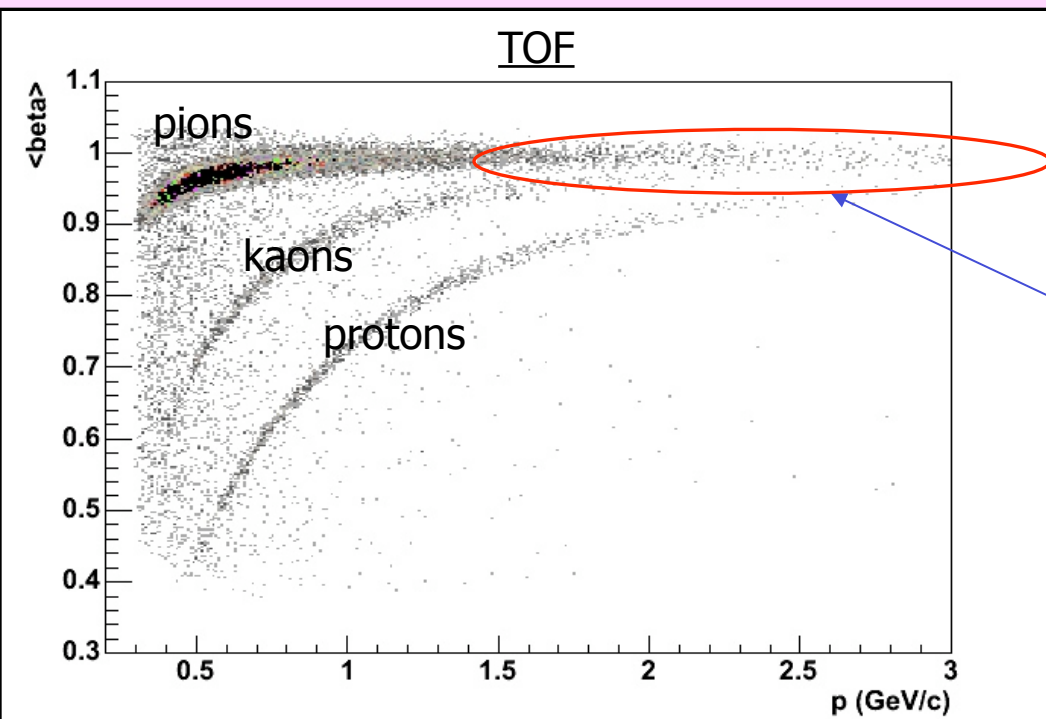
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We are left with the bare priors ☹

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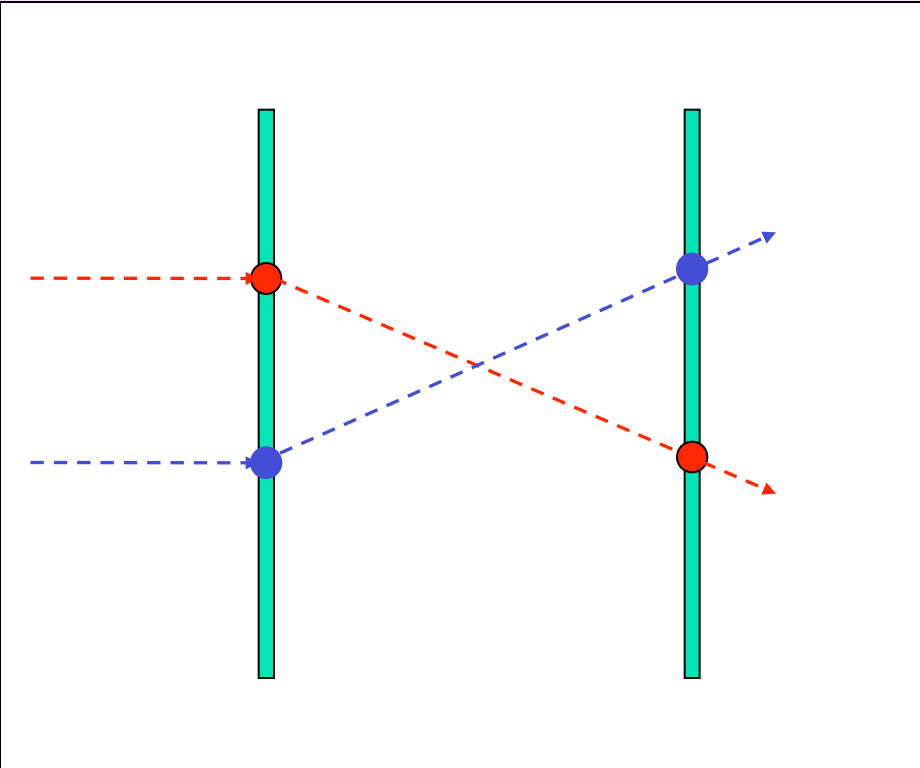
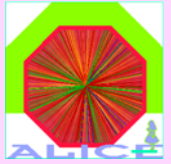
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Questions:

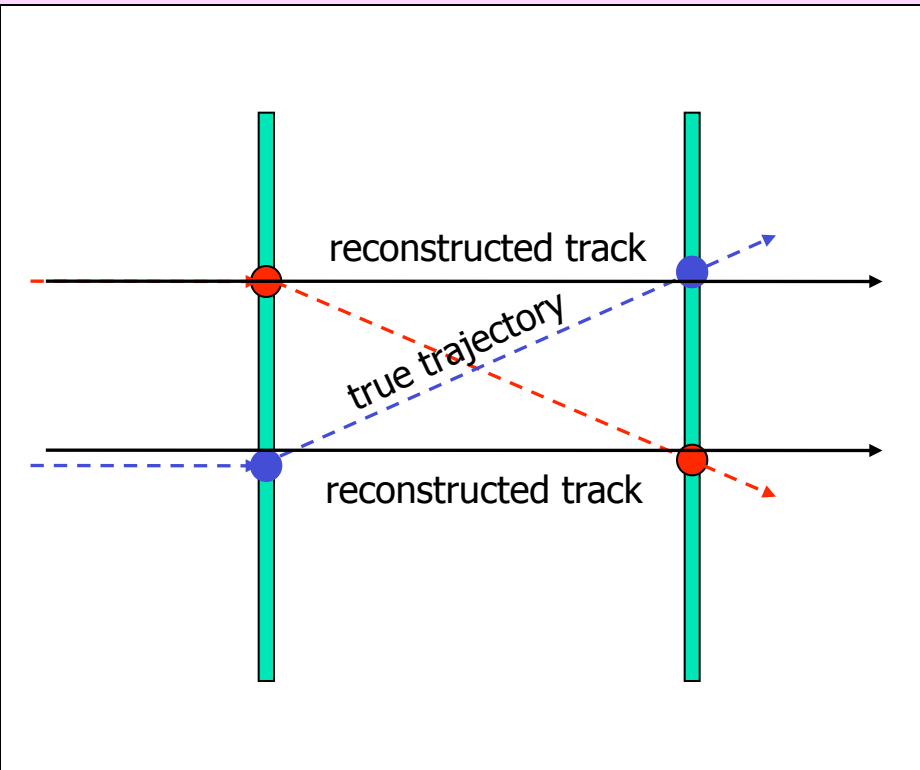
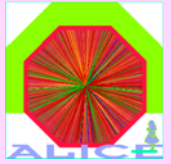
- The influence of the priors on the final result: Can it be somehow quantified ?
- In any approach: at what momentum should we stop doing the PID ?



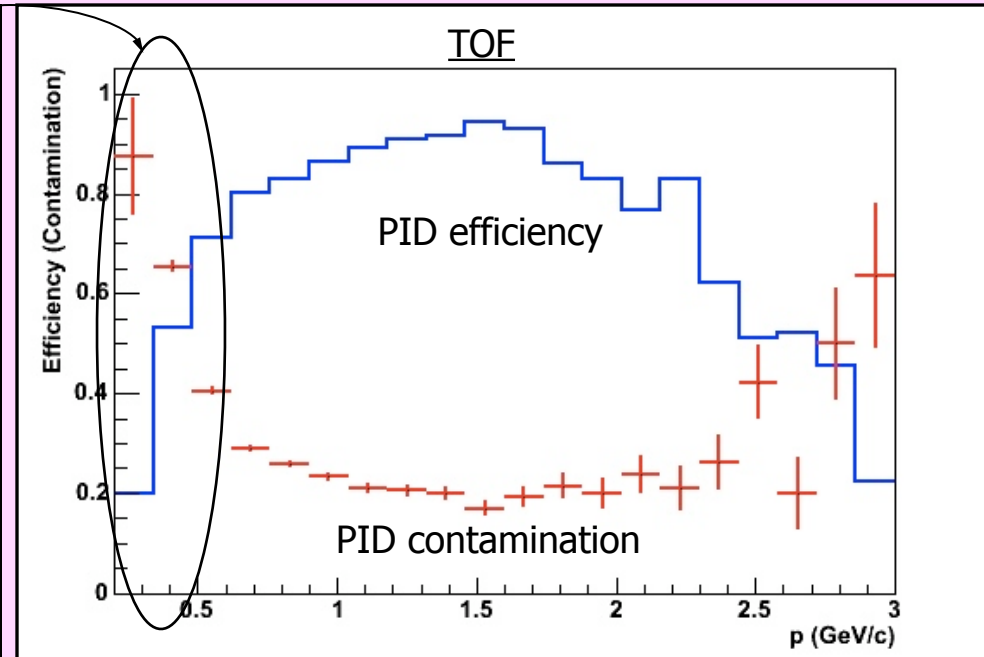
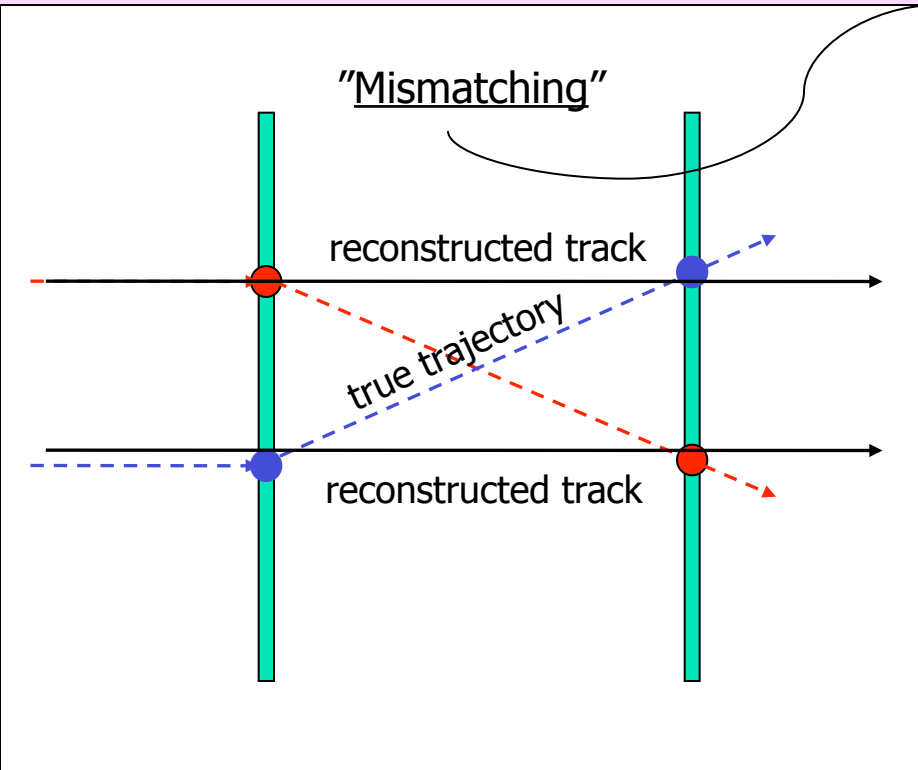
The problem of track mismatching



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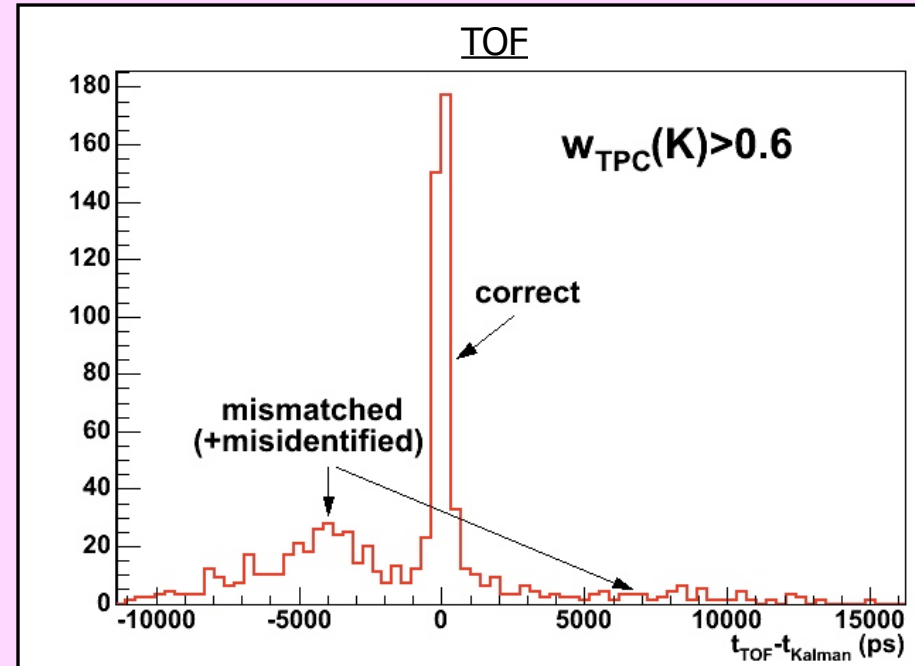
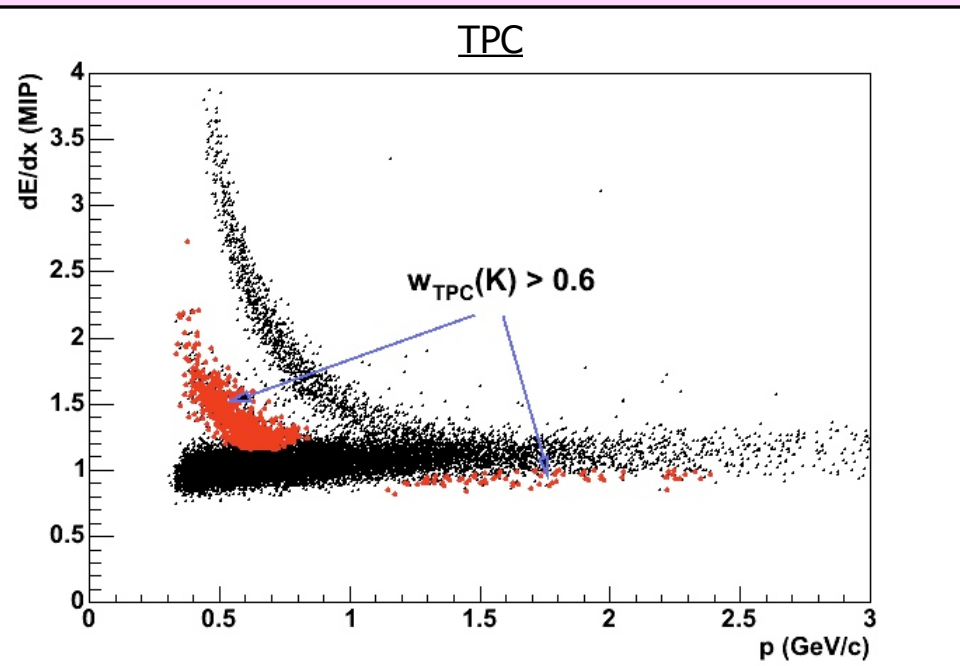


The problem of track mismatching



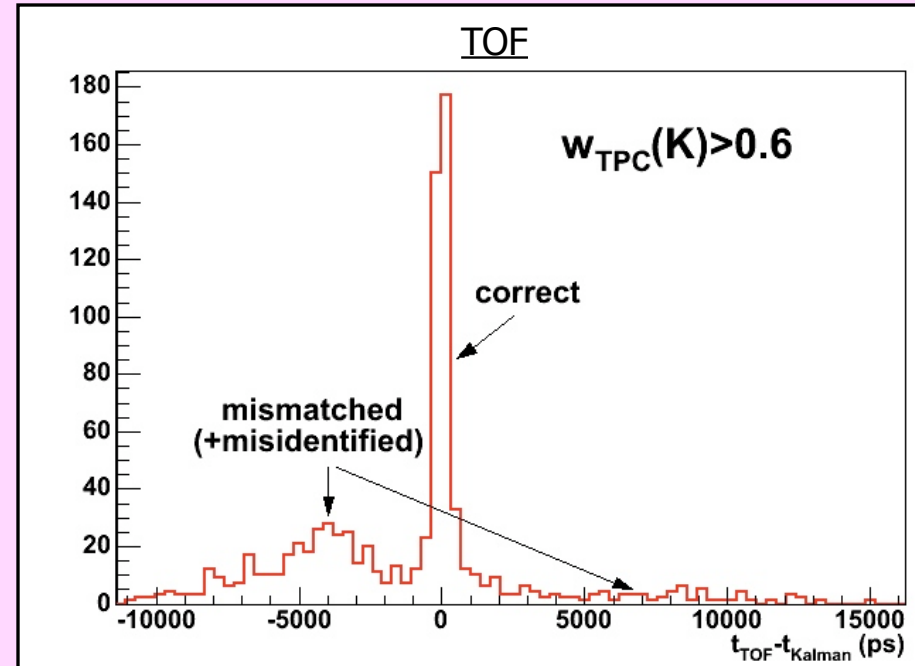
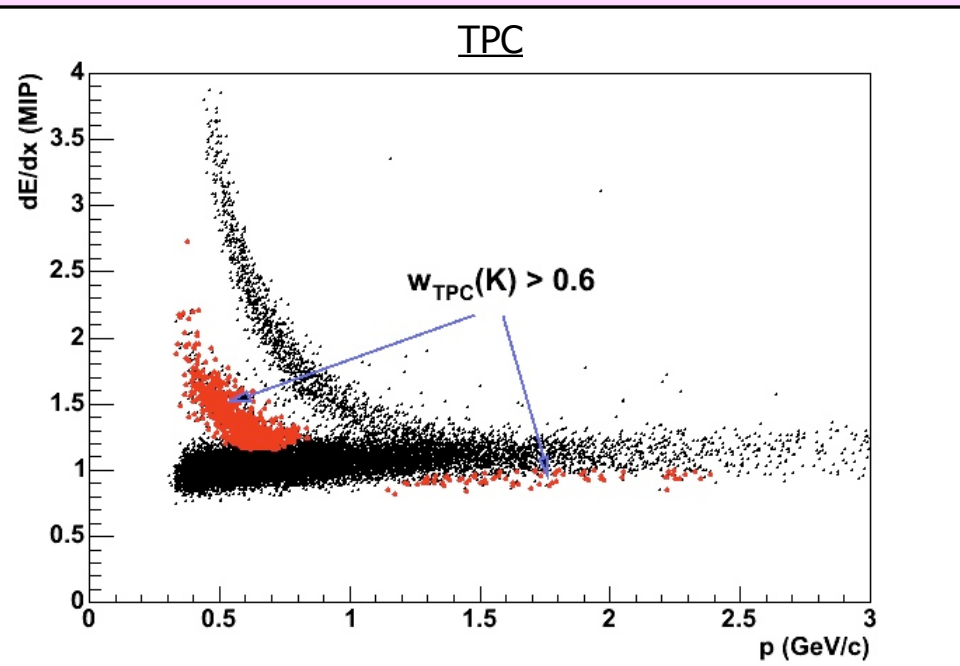
The track mismatching biases the combining (any kind of !) the PID information, because the main assumption that all the detectors register the same particle, is not satisfied...

Ad-hoc treatment for the mismatching in TOF



Observing in one of the detectors the distribution of signals for a clean sample of particles pre-selected in other detectors, we can get the range of signals, where the probability of mismatching is "high" → Veto in the combining...

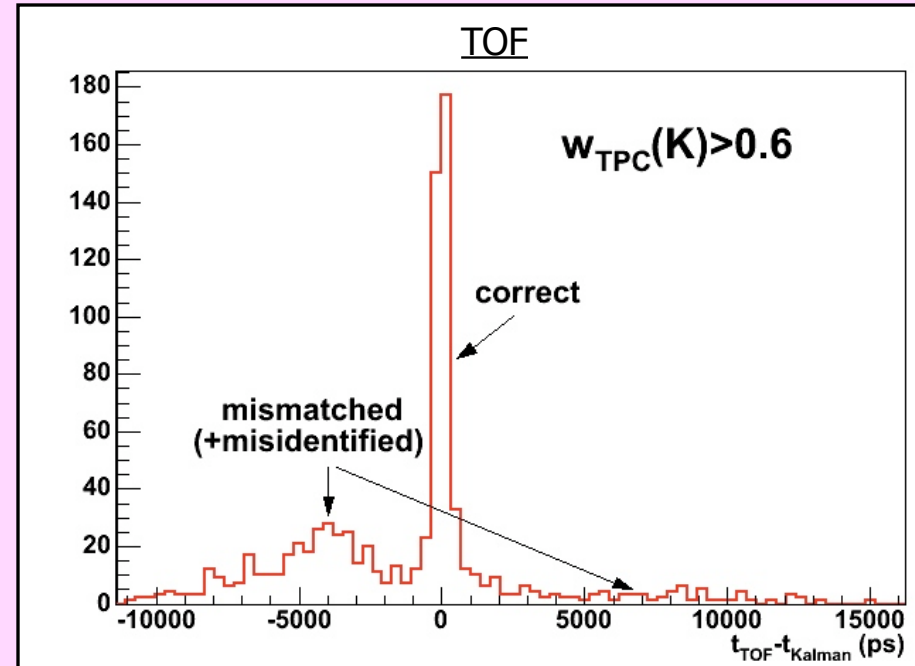
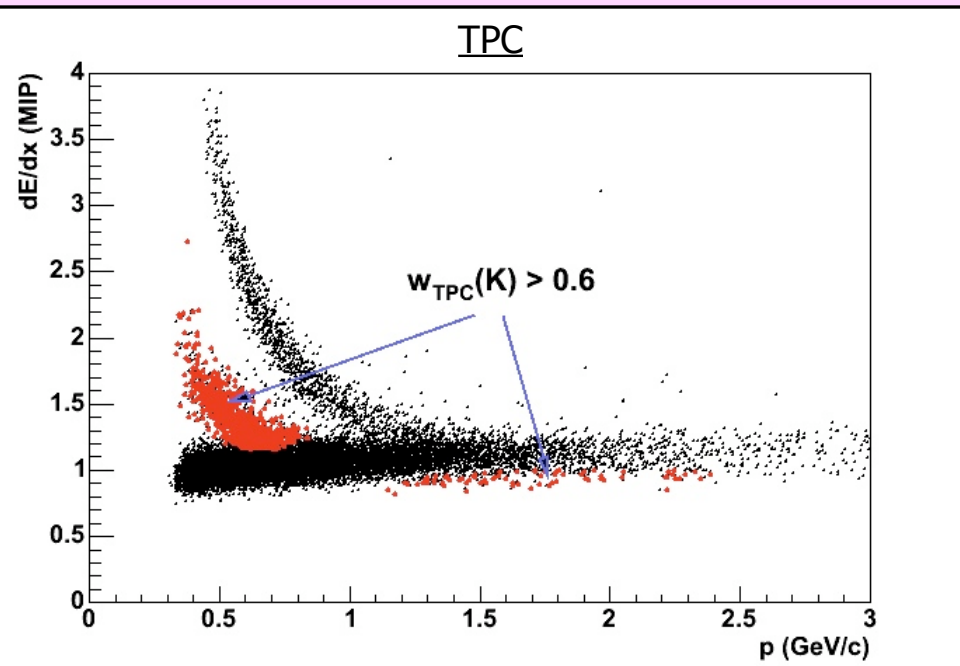
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A question: Can it be somehow generalized? Made "smooth"? Optimized?

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Something like $w = (1-p_{12})w_1 + p_{12}w_{12}$ (p_{12} - prob. of a correct matching)?