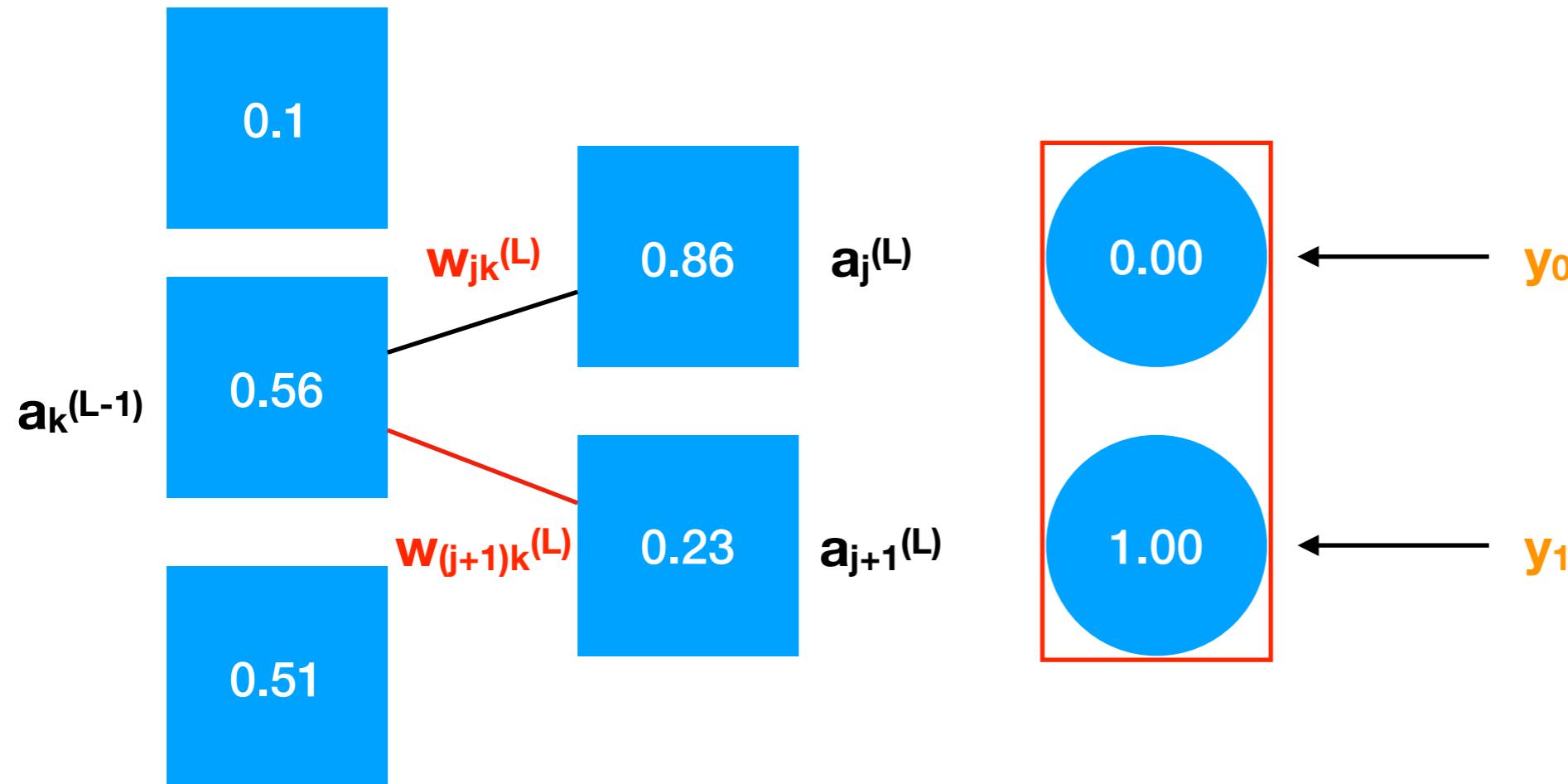


Backpropagation

Bastien Arcelin, Alexandre Boucaud
Workshop GPU - CC IN2P3

Gradient descent

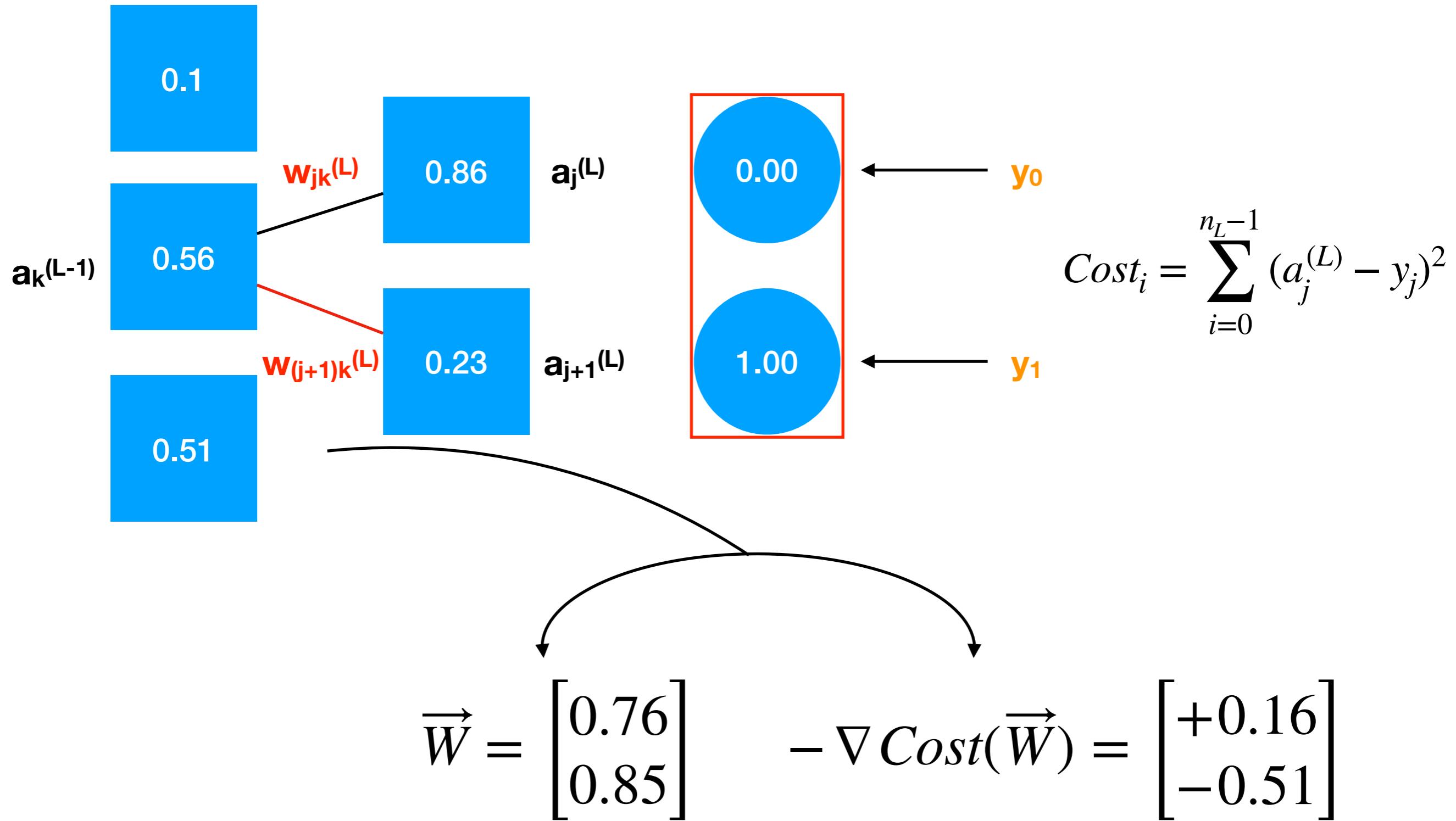


$$Cost_i = \sum_{j=0}^{n_L-1} (a_j^{(L)} - y_j)^2$$

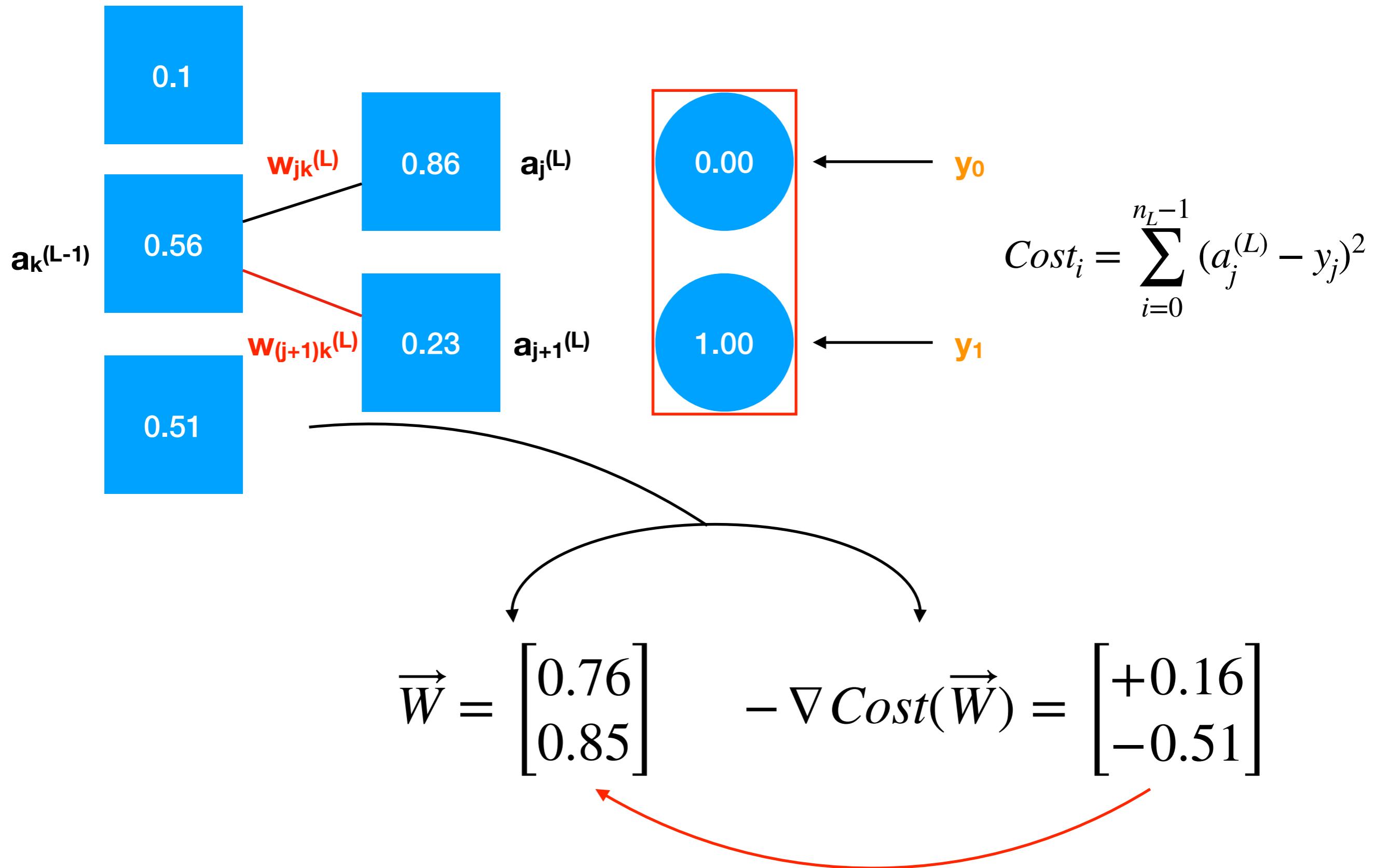
Case:

- training on one element of the training sample
- batch_size = 1

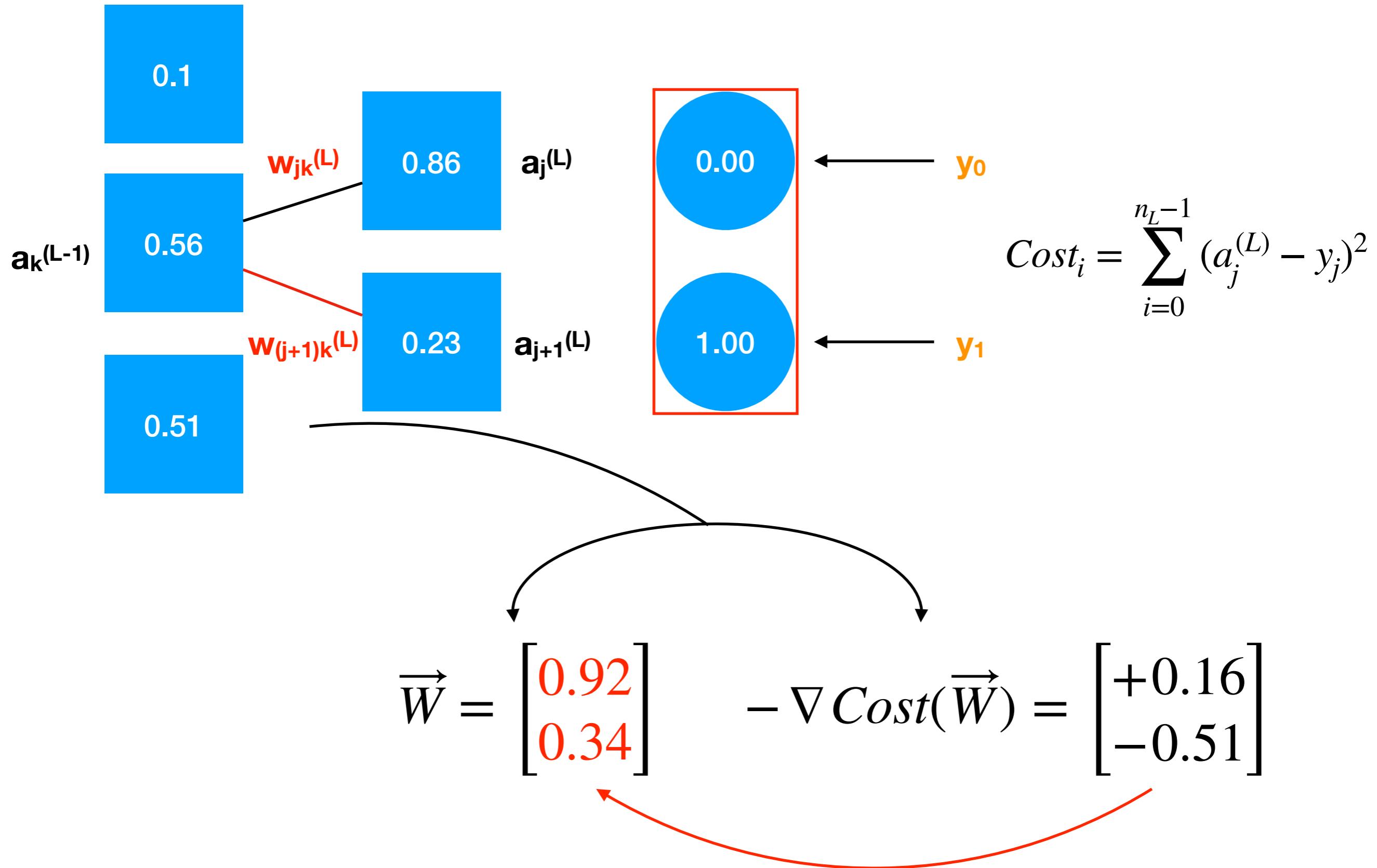
Gradient descent



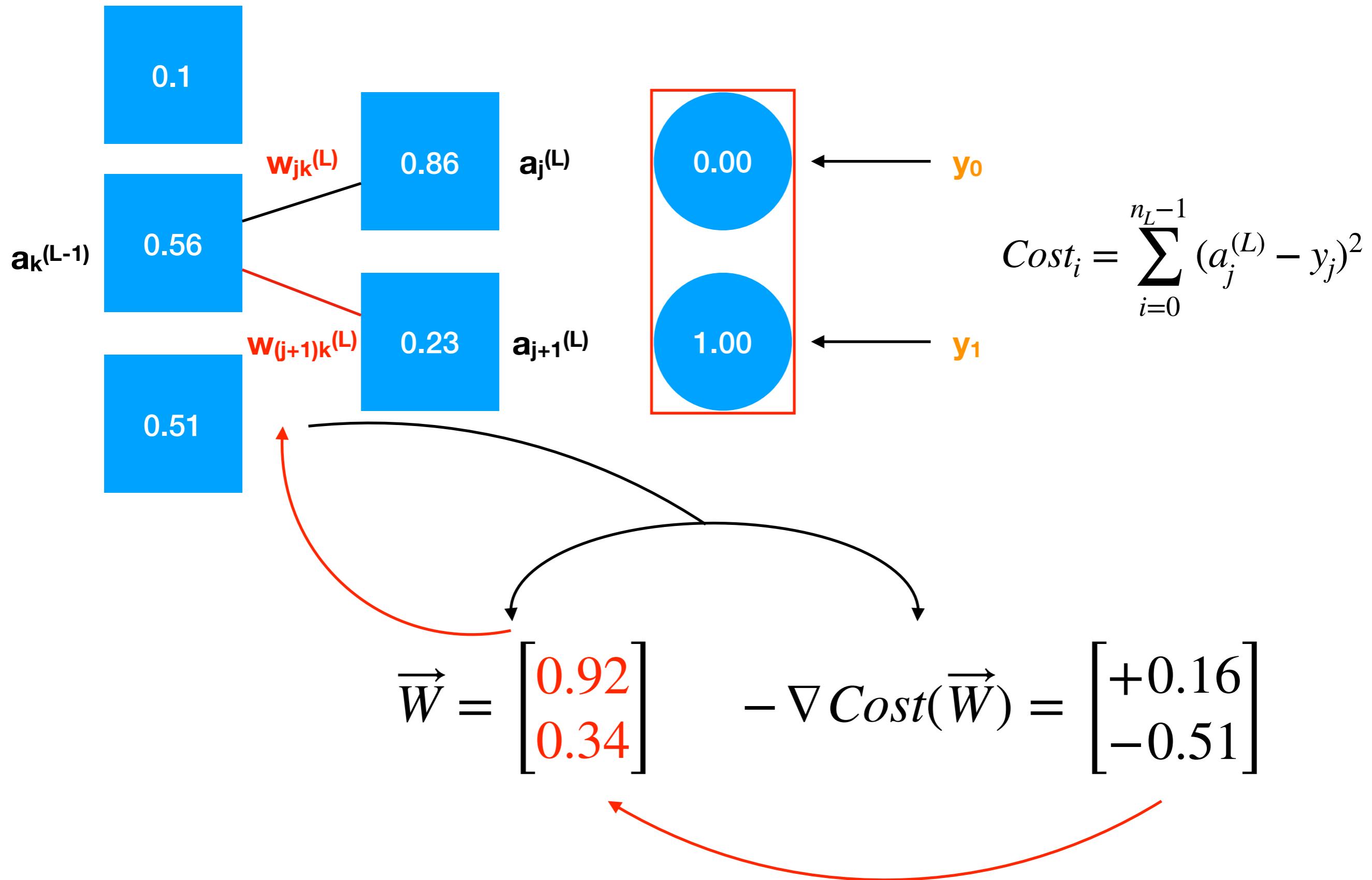
Gradient descent



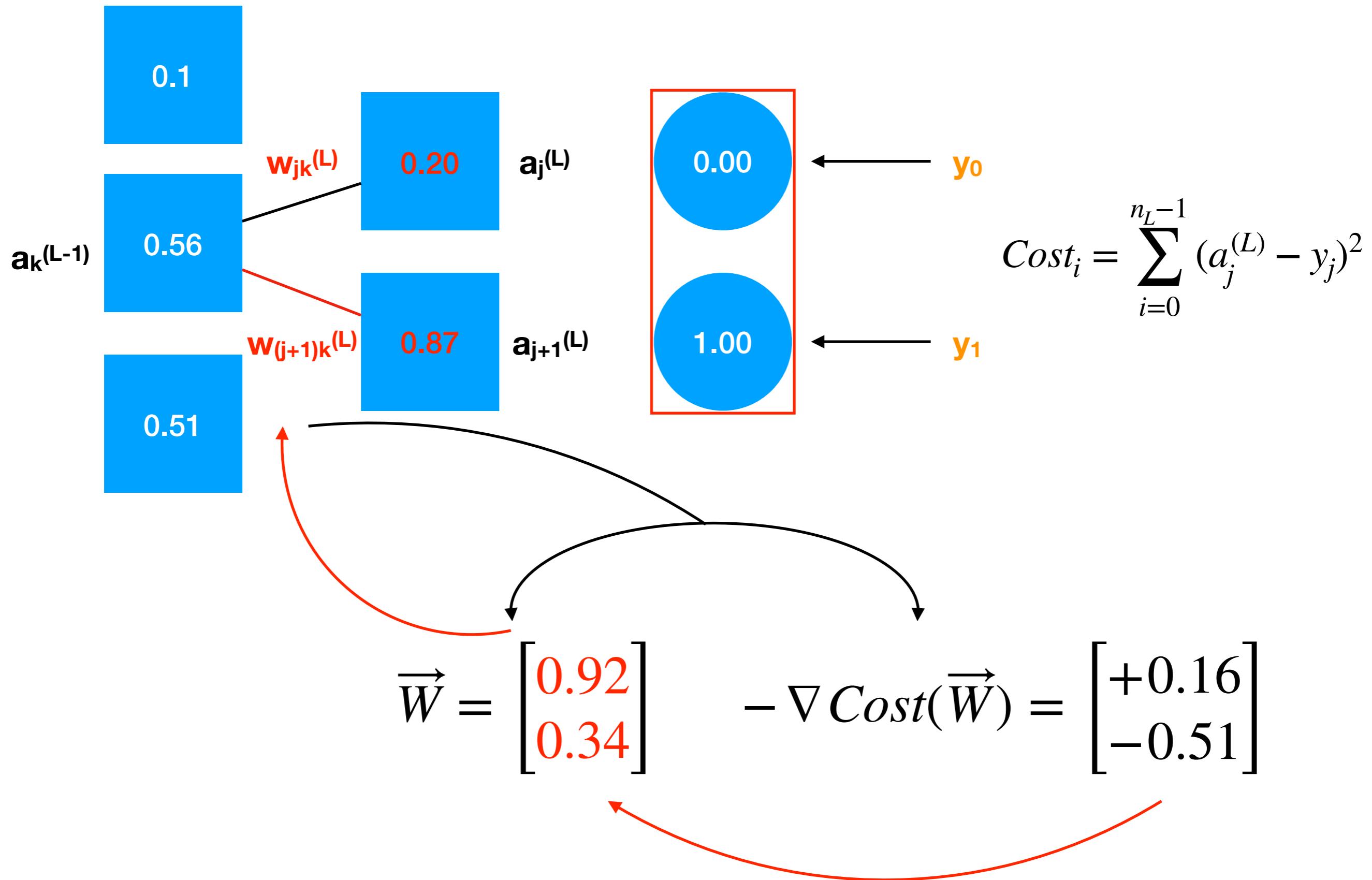
Gradient descent



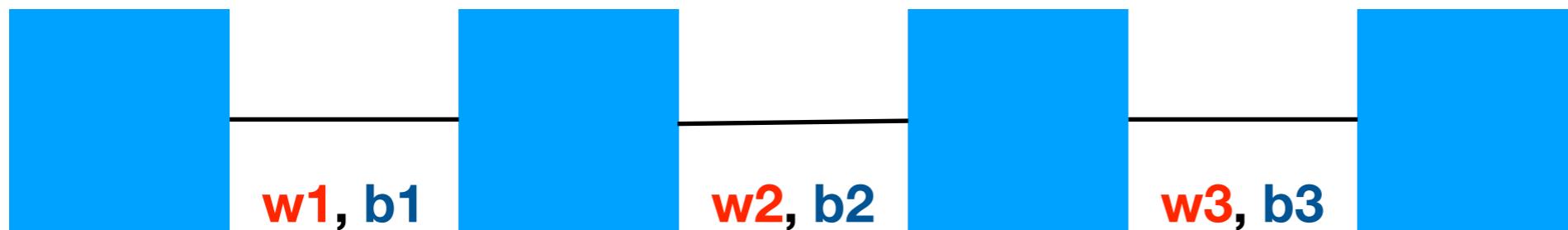
Gradient descent



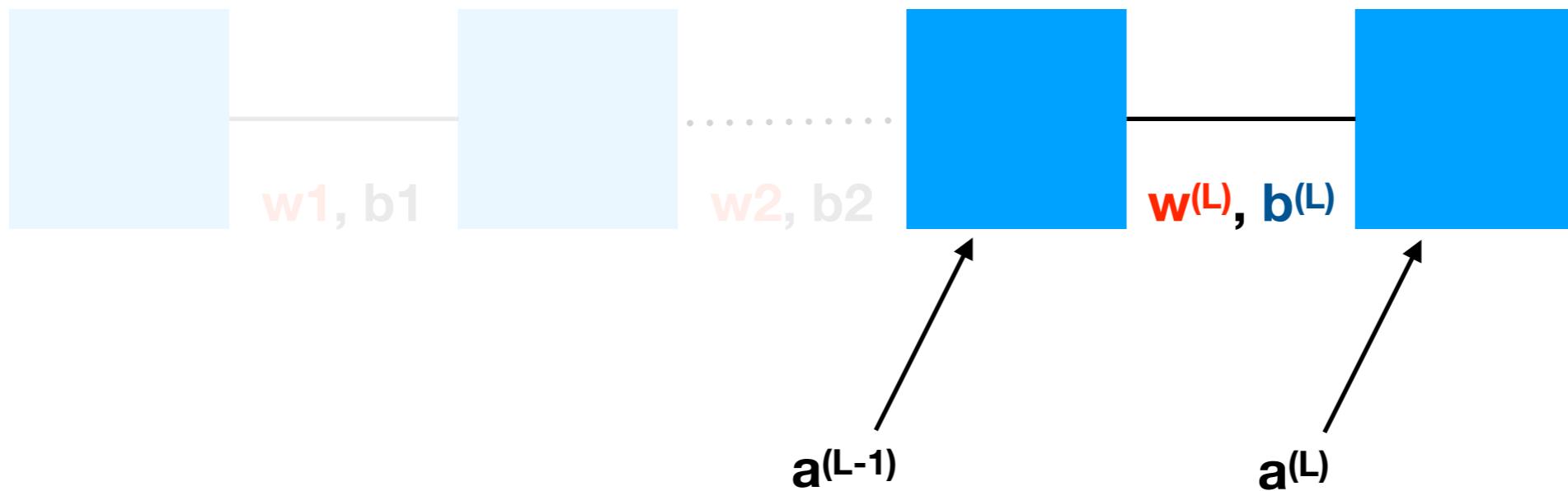
Gradient descent



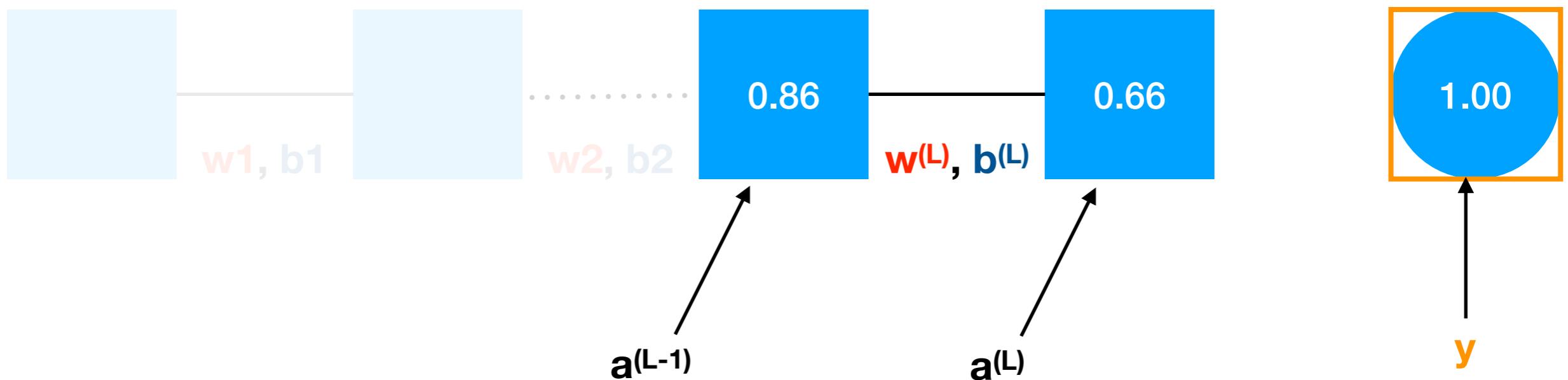
Network where each layer has a single neuron in it



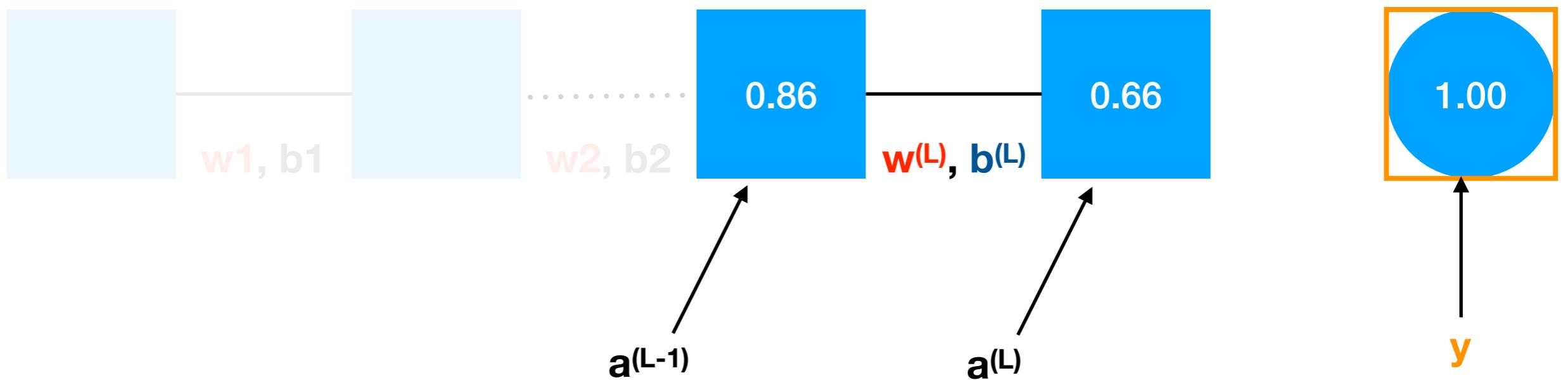
Network where each layer has a single neuron in it



Network where each layer has a single neuron in it

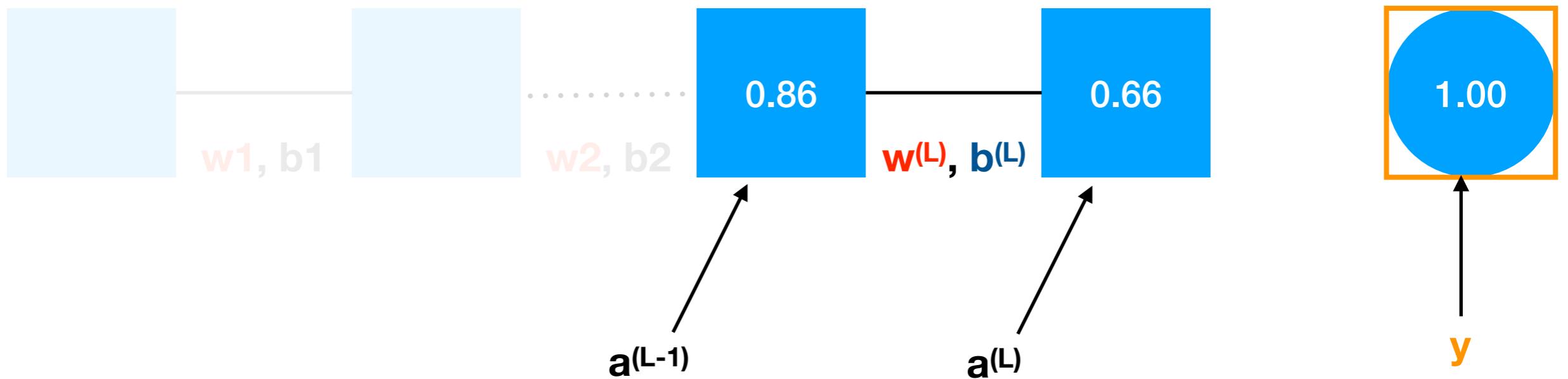


Network where each layer has a single neuron in it



$$\text{Cost } (w_1, \dots, w^{(L)}, b_1, \dots, b^{(L)}) = (a^{(L)} - y)^2$$

Network where each layer has a single neuron in it

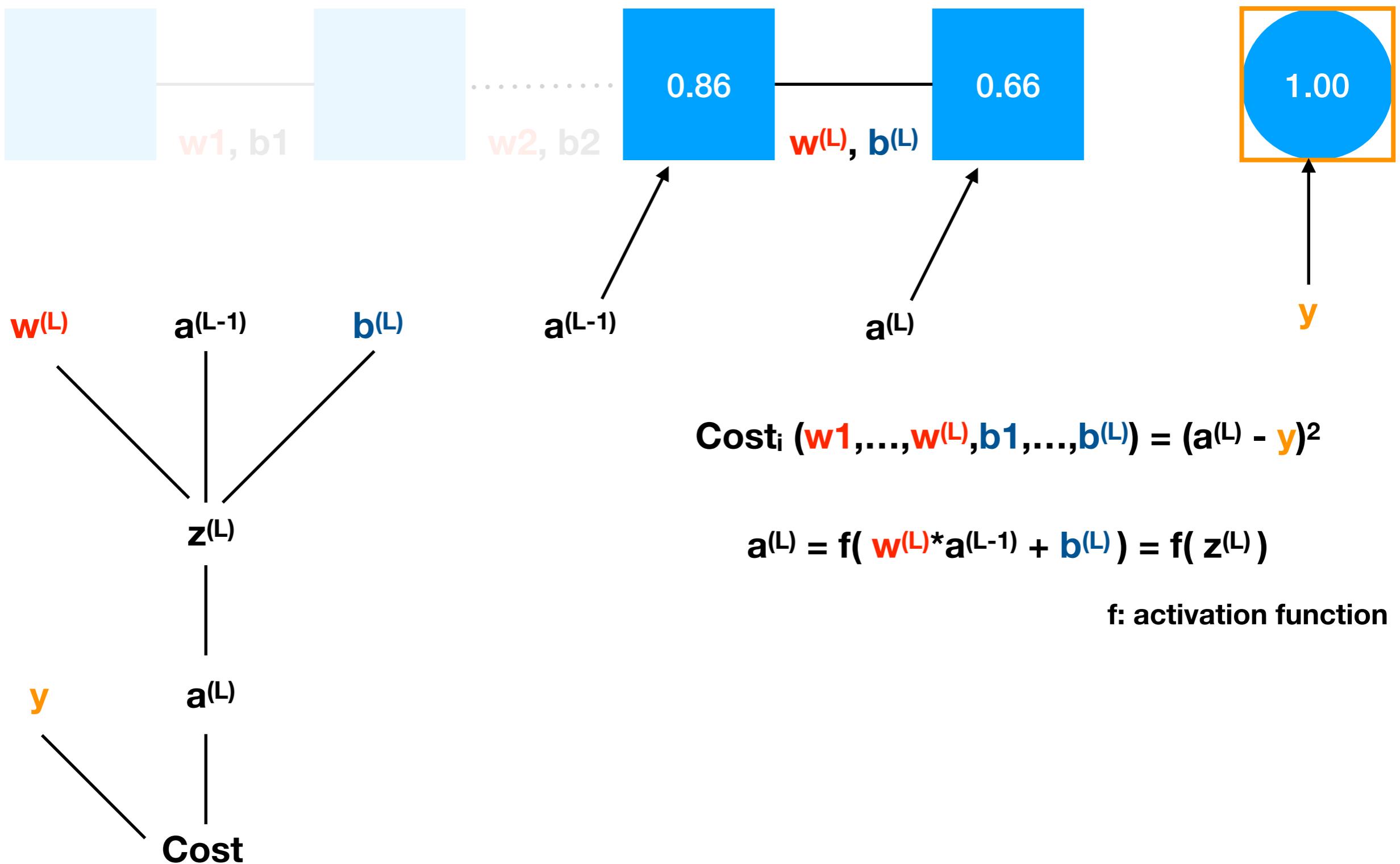


$$\text{Cost } (\mathbf{w}_1, \dots, \mathbf{w}^{(L)}, \mathbf{b}_1, \dots, \mathbf{b}^{(L)}) = (a^{(L)} - y)^2$$

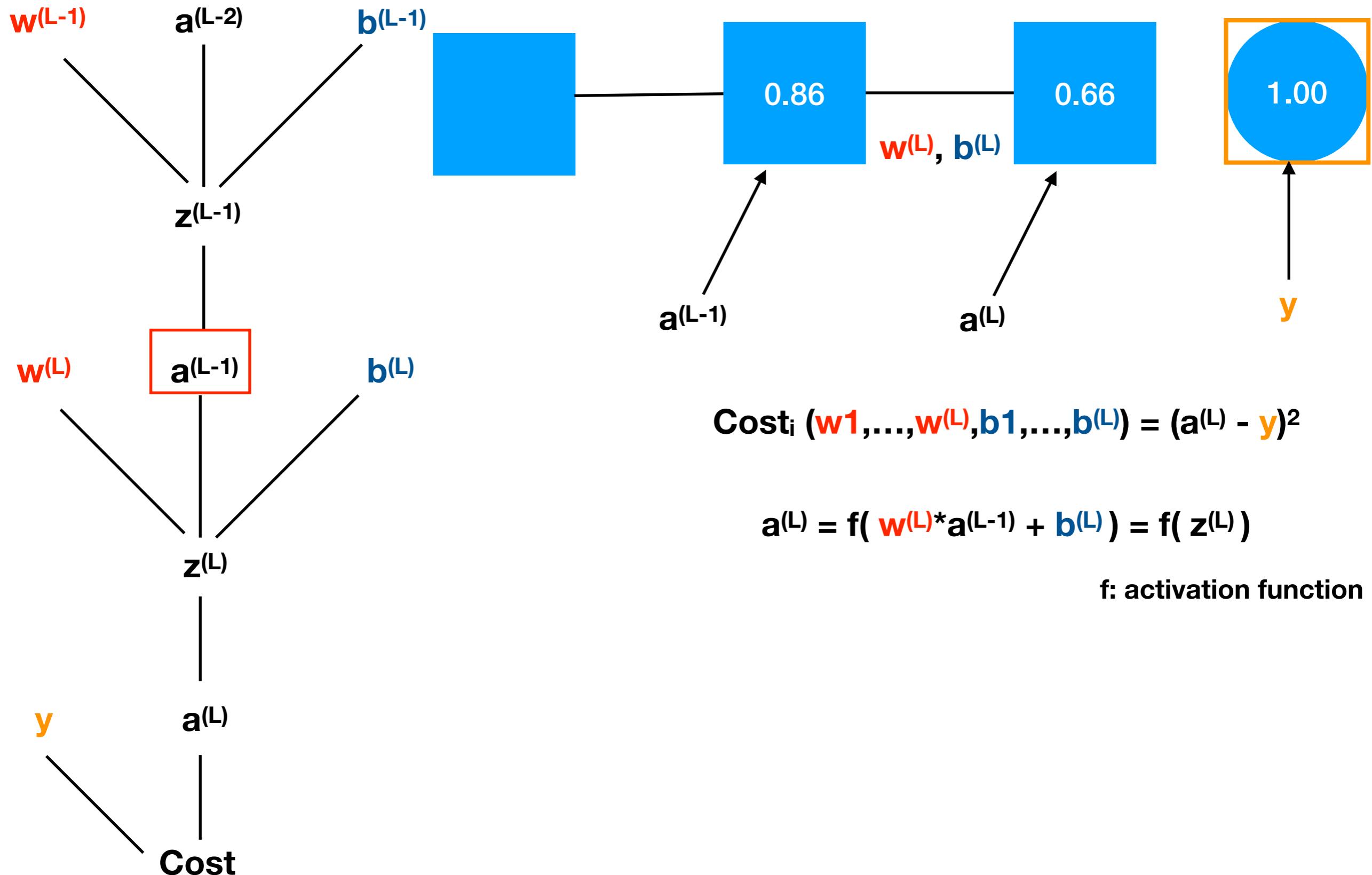
$$a^{(L)} = f(\mathbf{w}^{(L)} * a^{(L-1)} + \mathbf{b}^{(L)}) = f(z^{(L)})$$

f: activation function

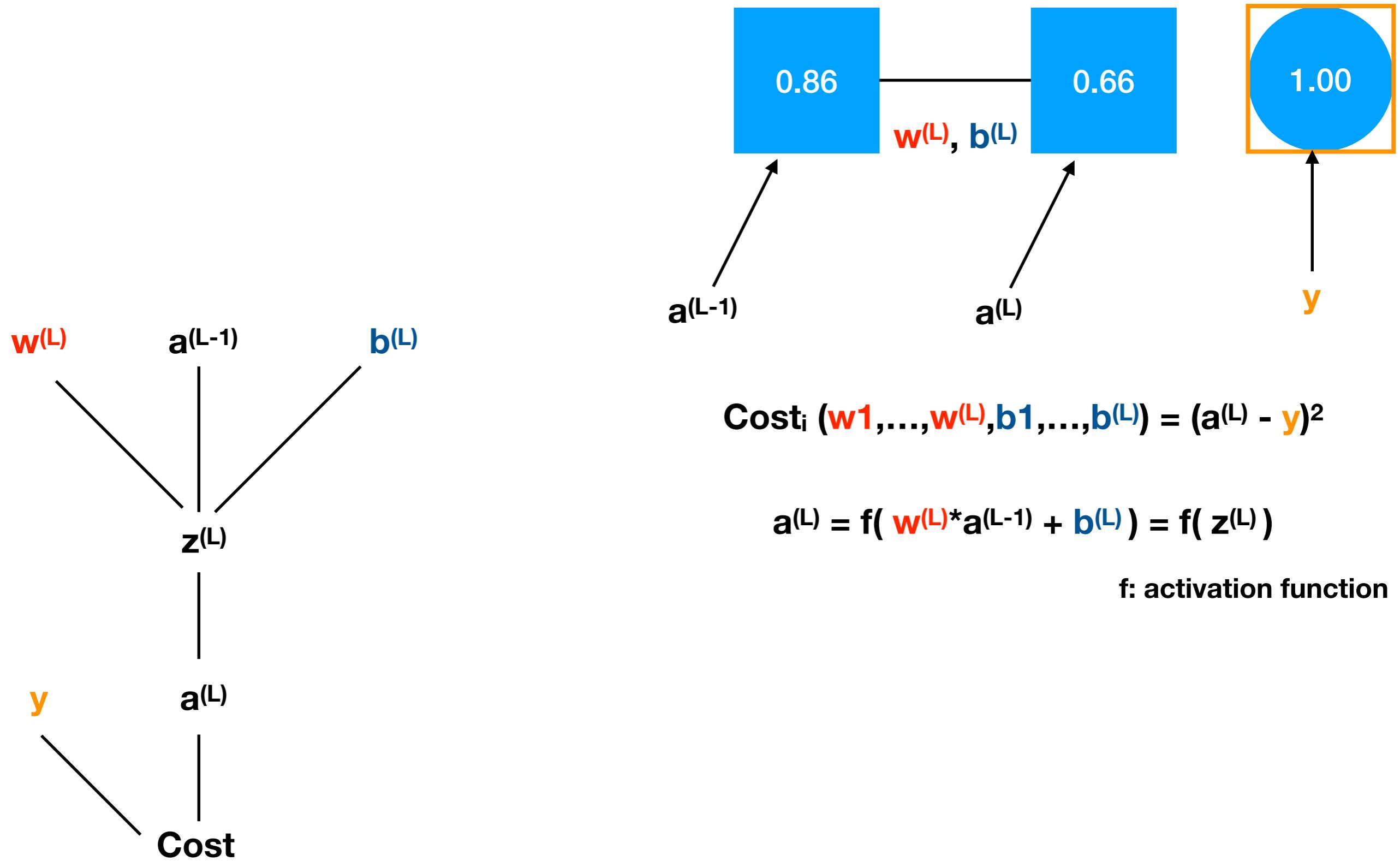
Network where each layer has a single neuron in it



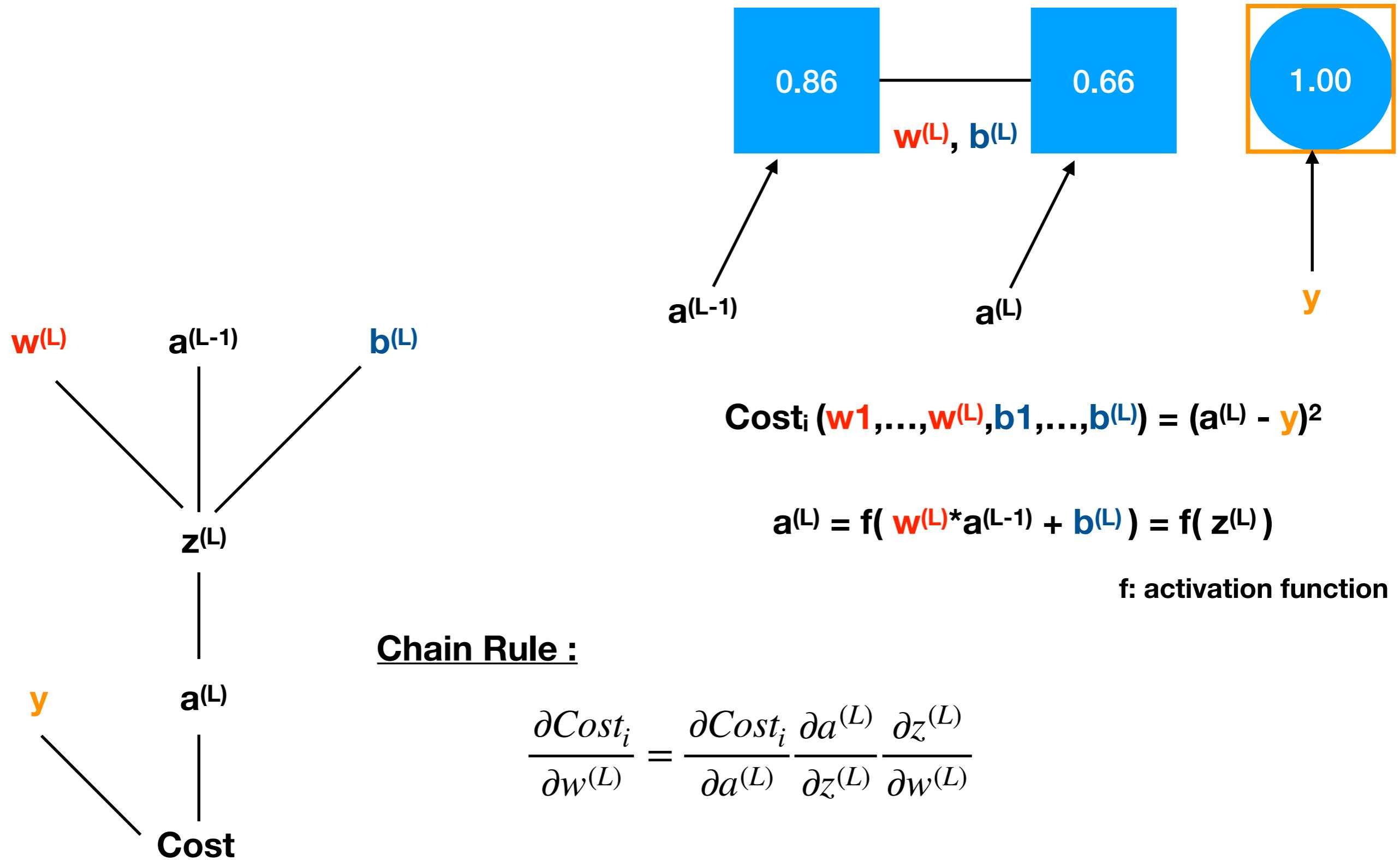
Network where each layer has a single neuron in it



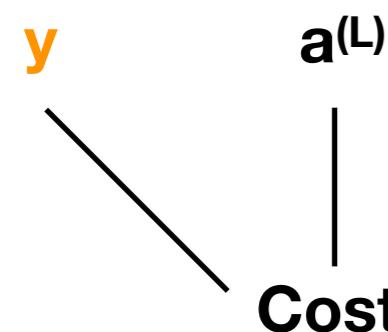
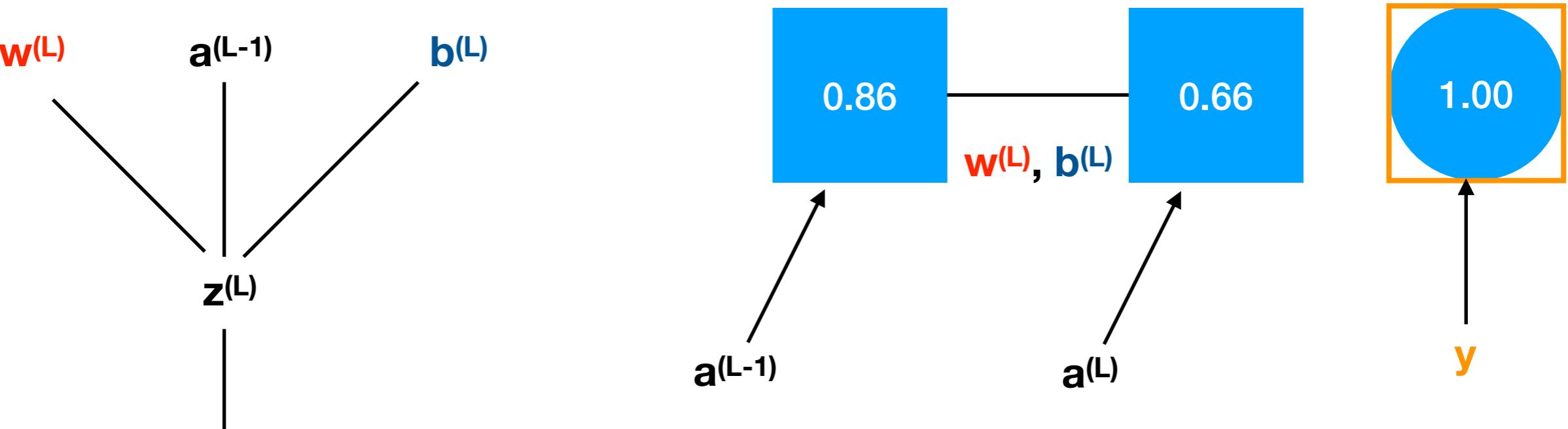
Network where each layer has a single neuron in it



Network where each layer has a single neuron in it



Network where each layer has a single neuron in it



$$\text{Cost}_i(w_1, \dots, w^{(L)}, b_1, \dots, b^{(L)}) = (a^{(L)} - y)^2$$

$$a^{(L)} = f(w^{(L)} * a^{(L-1)} + b^{(L)}) = f(z^{(L)})$$

$$\frac{\partial \text{Cost}_i}{\partial a^{(L)}} = 2(a^{(L)} - y)$$

$$\frac{\partial a^{(L)}}{\partial z^{(L)}} = f'(z^{(L)})$$

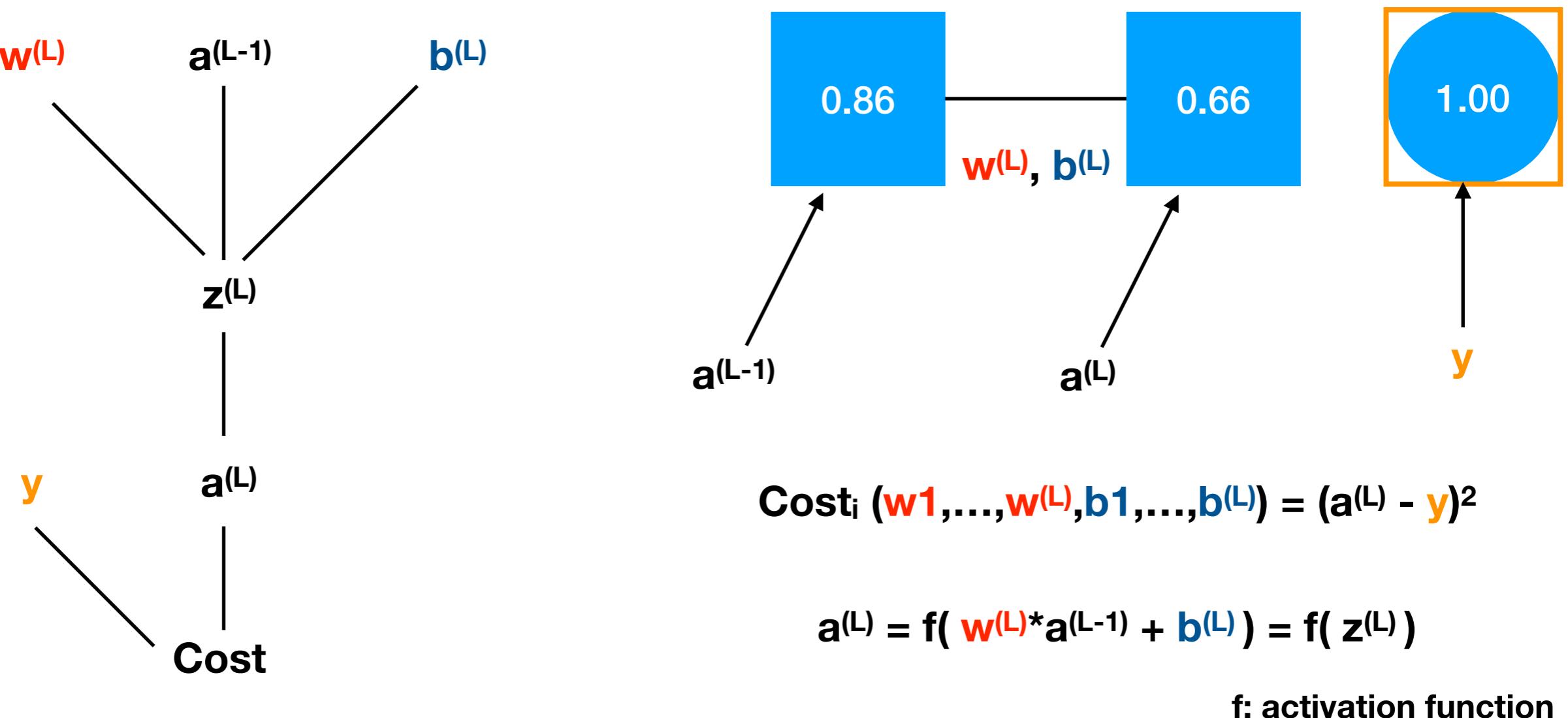
$$\frac{\partial z^{(L)}}{\partial w^{(L)}} = a^{(L-1)}$$

f: activation function

Chain Rule :

$$\frac{\partial \text{Cost}_i}{\partial w^{(L)}} = \frac{\partial \text{Cost}_i}{\partial a^{(L)}} \frac{\partial a^{(L)}}{\partial z^{(L)}} \frac{\partial z^{(L)}}{\partial w^{(L)}}$$

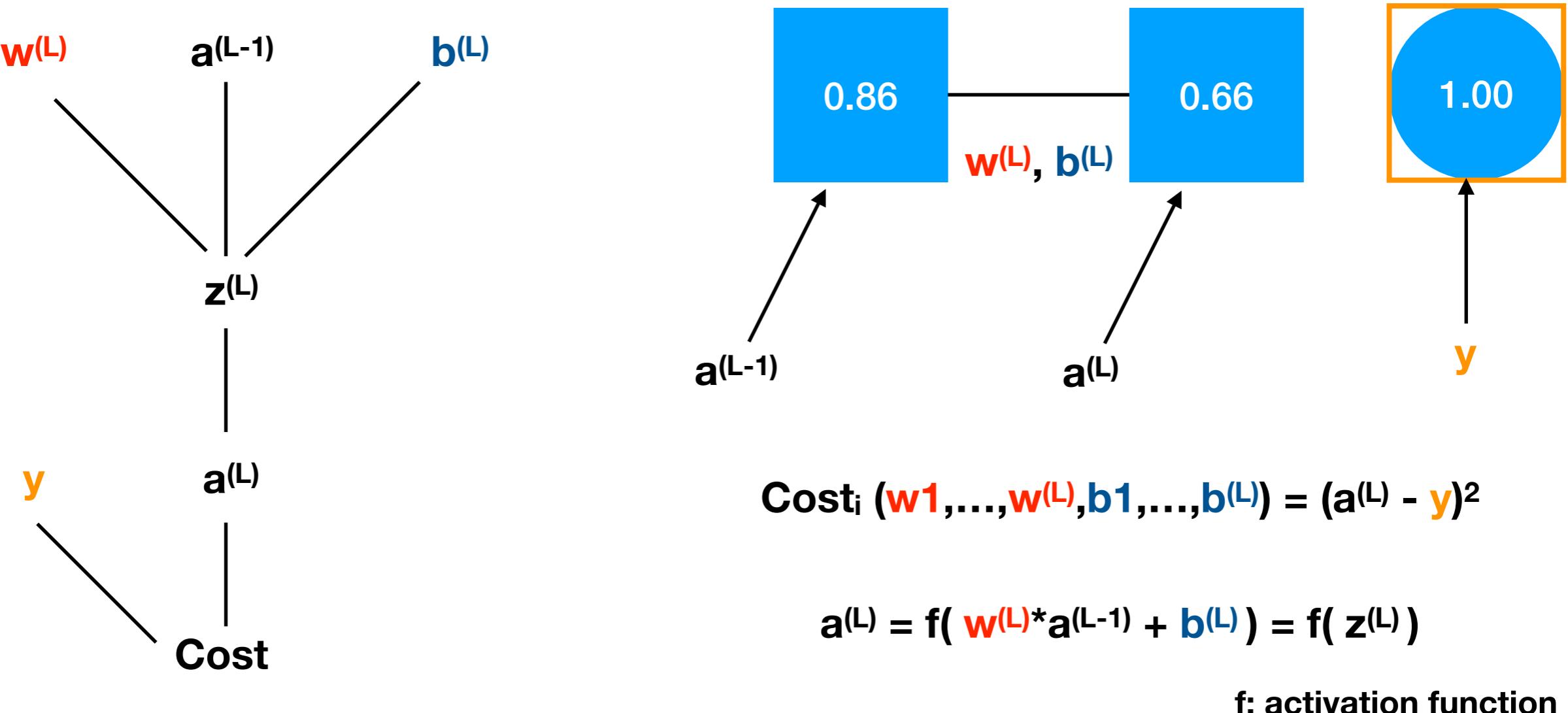
Network where each layer has a single neuron in it



Chain Rule :

$$\frac{\partial \text{Cost}_i}{\partial w^{(L)}} = \frac{\partial \text{Cost}_i}{\partial a^{(L)}} \frac{\partial a^{(L)}}{\partial z^{(L)}} \frac{\partial z^{(L)}}{\partial w^{(L)}} = 2(a^{(L)} - y)f'(z^{(L)})a^{(L-1)}$$

Network where each layer has a single neuron in it

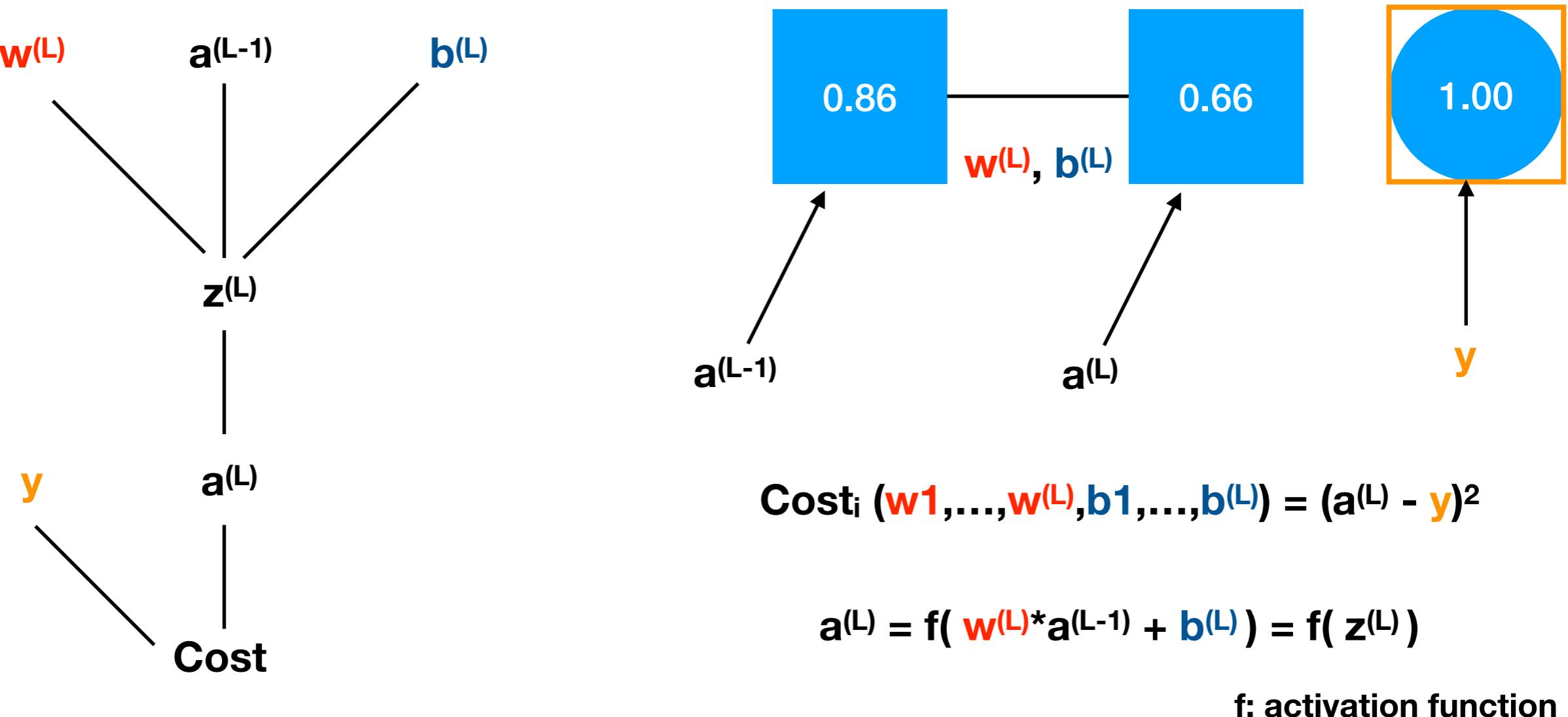


Chain Rule :

$$\frac{\partial \text{Cost}_i}{\partial w^{(L)}} = \frac{\partial \text{Cost}_i}{\partial a^{(L)}} \frac{\partial a^{(L)}}{\partial z^{(L)}} \frac{\partial z^{(L)}}{\partial w^{(L)}} = 2(a^{(L)} - y)f'(z^{(L)})a^{(L-1)} \longrightarrow \frac{\partial \text{Cost}}{\partial w^{(L)}} = \frac{1}{n} \sum_{i=0}^{n-1} \left(\frac{\partial \text{Cost}_i}{\partial w^{(L)}} \right)$$

For n training examples

Network where each layer has a single neuron in it

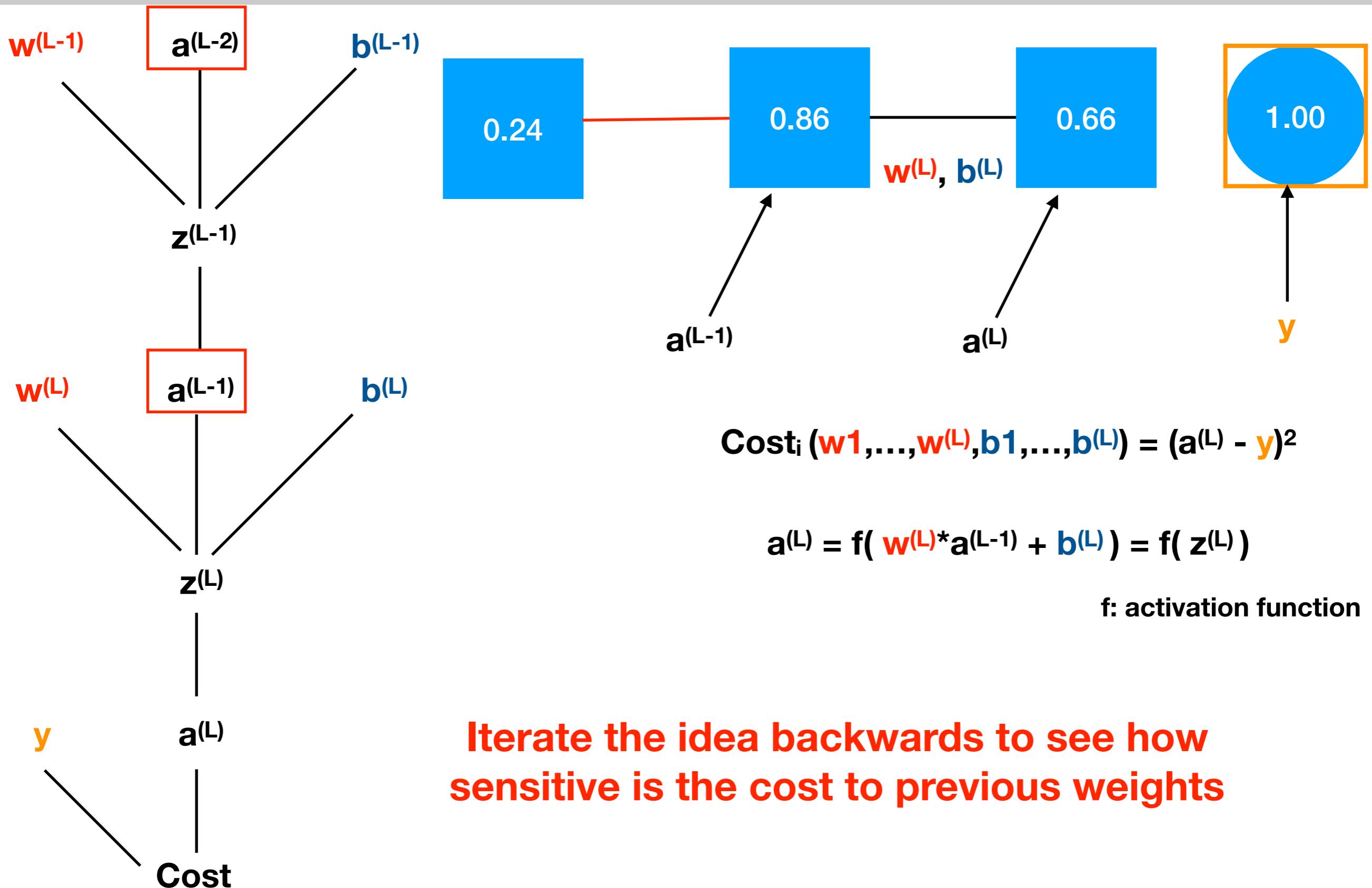


Same use of chain rule for $b^{(L)}$, and $a^{(L-1)}$: backpropagation

$$\frac{\partial Cost_i}{\partial b^{(L)}} = 2(a^{(L)} - y)f'(z^{(L)})$$

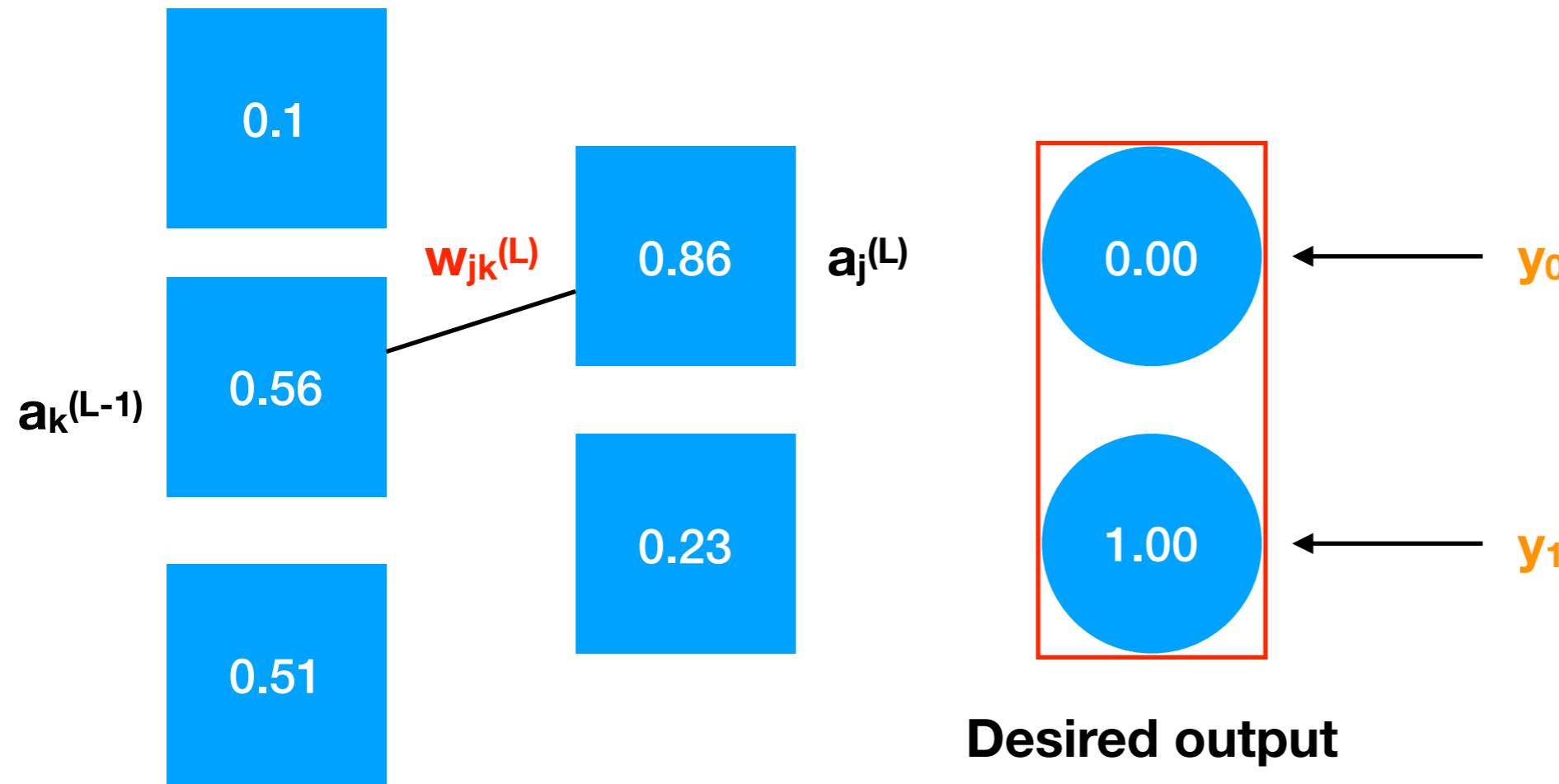
$$\frac{\partial Cost_i}{\partial a^{(L-1)}} = 2(a^{(L)} - y)f'(z^{(L)})w^{(L)}$$

Network where each layer has a single neuron in it



Network where each layer has **more than** neuron in it

$$Cost_i = \sum_{j=0}^{n_L-1} (a_j^{(L)} - y_j)^2$$

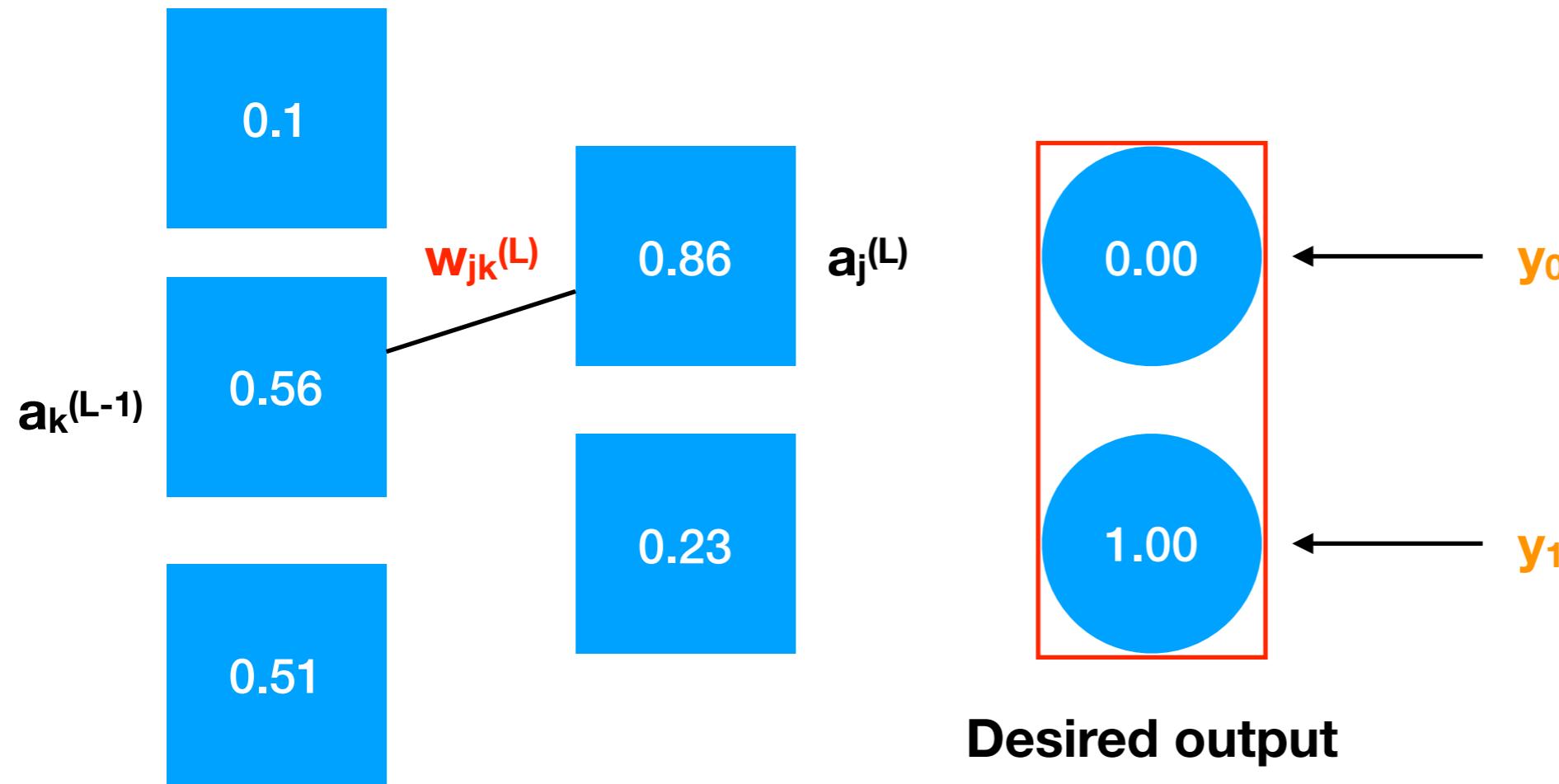


Network where each layer has **more than** neuron in it

$$z_j^{(L)} = w_{j0}^{(L)}a_0^{(L-1)} + w_{j1}^{(L)}a_1^{(L-1)} + w_{j2}^{(L)}a_2^{(L-1)} + b_j^{(L)}$$

$$a_j^{(L)} = f(z_j^{(L)})$$

$$Cost_i = \sum_{i=0}^{n_L-1} (a_j^{(L)} - y_j)^2$$



Network where each layer has **more than** neuron in it

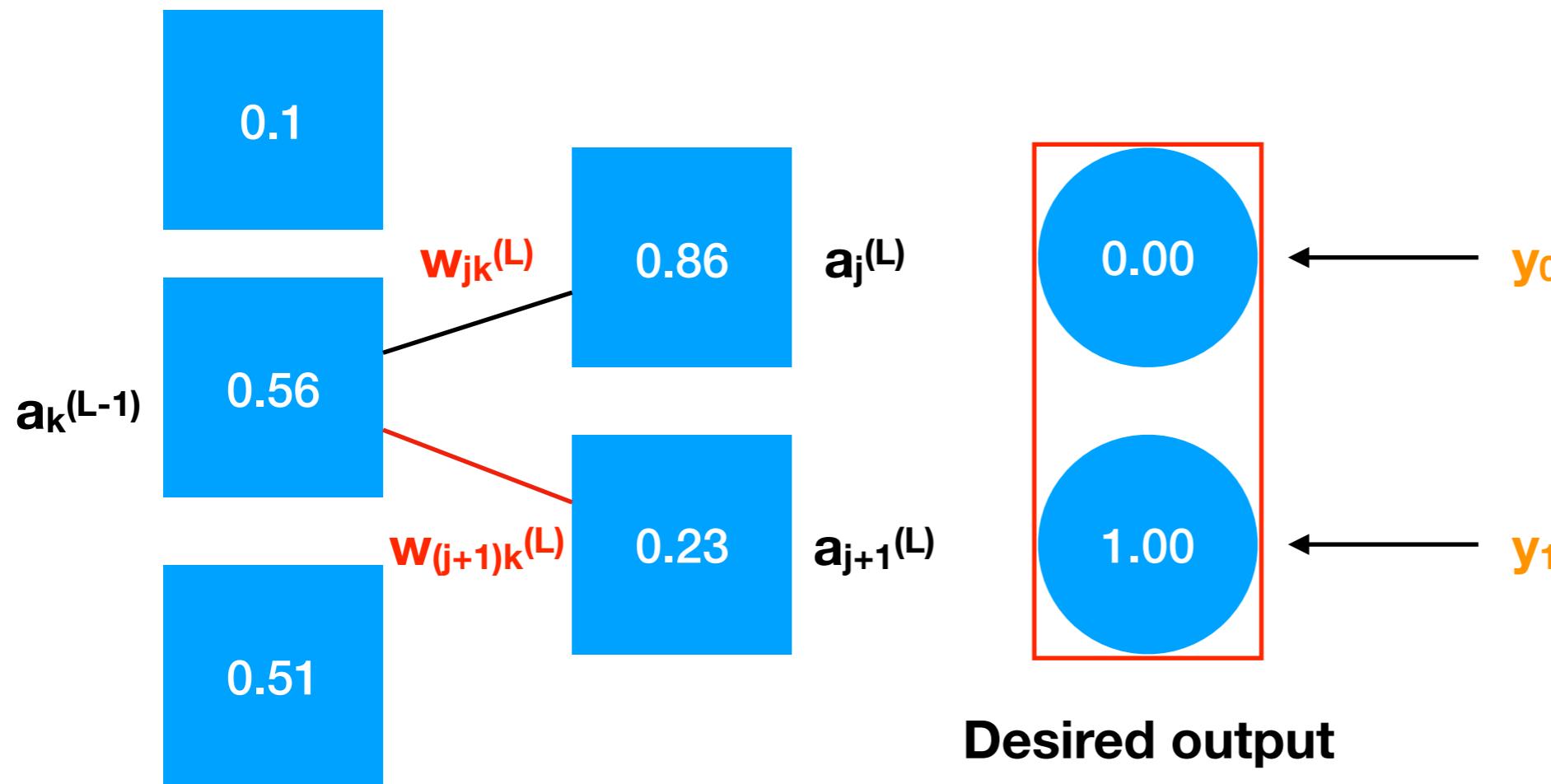
$$\frac{\partial Cost_i}{\partial w_{jk}^{(L)}} = \frac{\partial Cost_i}{\partial a_j^{(L)}} \frac{\partial a_j^{(L)}}{\partial z_j^{(L)}} \frac{\partial z_j^{(L)}}{\partial w_{jk}^{(L)}}$$

$$\frac{\partial Cost_i}{\partial a_k^{(L-1)}} = \sum_{j=0}^{n_L-1} \frac{\partial Cost_i}{\partial a_j^{(L)}} \frac{\partial a_j^{(L)}}{\partial z_j^{(L)}} \frac{\partial z_j^{(L)}}{\partial a_k^{(L-1)}}$$

$$z_j^{(L)} = w_{j0}^{(L)} a_0^{(L-1)} + w_{j1}^{(L)} a_1^{(L-1)} + w_{j2}^{(L)} a_2^{(L-1)} + b_j^{(L)}$$

$$a_j^{(L)} = f(z_j^{(L)})$$

→ **Sum over layer L**



$$Cost_i = \sum_{j=0}^{n_L-1} (a_j^{(L)} - y_j)^2$$

Network where each layer has **more than** neuron in it

$$\frac{\partial Cost_i}{\partial w_{jk}^{(L)}} = \frac{\partial Cost_i}{\partial a_j^{(L)}} \frac{\partial a_j^{(L)}}{\partial z_j^{(L)}} \frac{\partial z_j^{(L)}}{\partial w_{jk}^{(L)}}$$

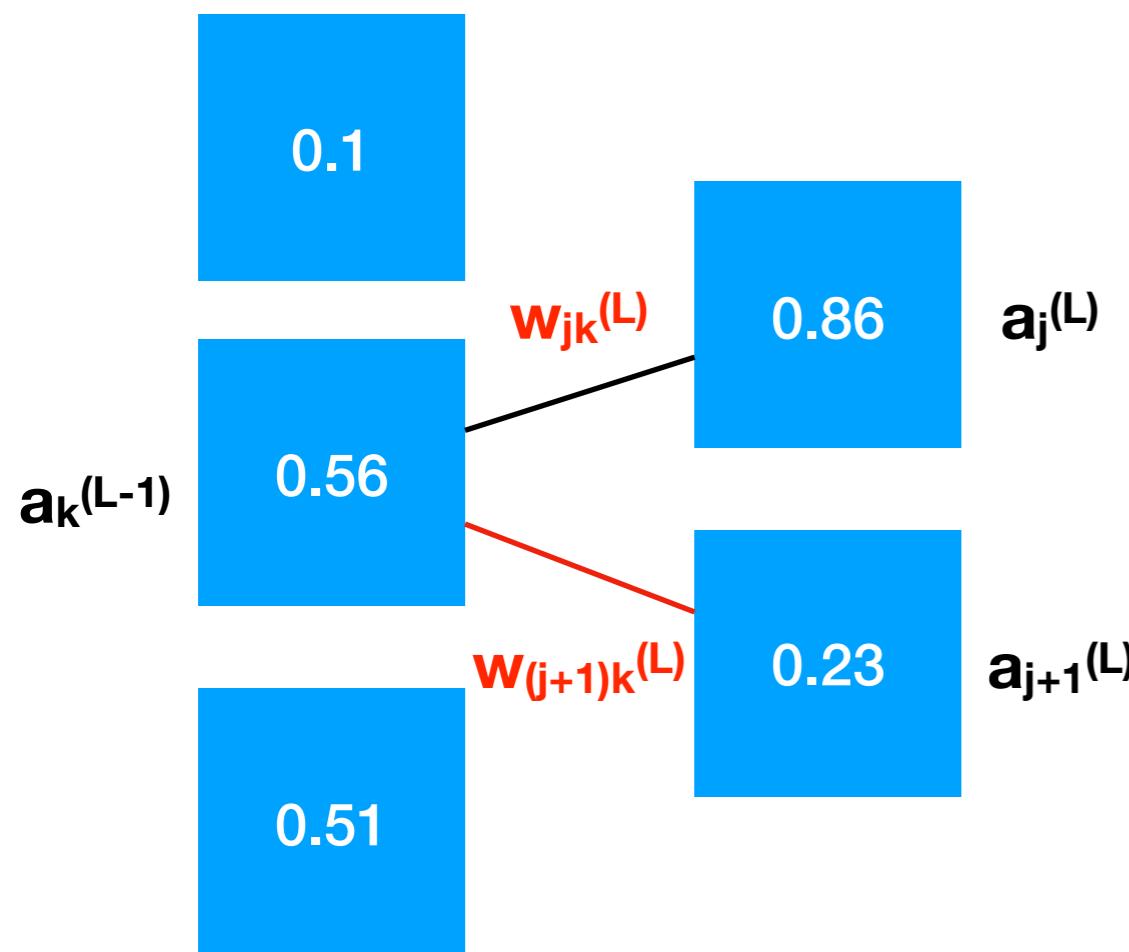
$$\frac{\partial Cost_i}{\partial a_k^{(L-1)}} = \sum_{j=0}^{n_L-1} \frac{\partial Cost_i}{\partial a_j^{(L)}} \frac{\partial a_j^{(L)}}{\partial z_j^{(L)}} \frac{\partial z_j^{(L)}}{\partial a_k^{(L-1)}}$$

$$z_j^{(L)} = w_{j0}^{(L)} a_0^{(L-1)} + w_{j1}^{(L)} a_1^{(L-1)} + w_{j2}^{(L)} a_2^{(L-1)} + b_j^{(L)}$$

$$a_j^{(L)} = f(z_j^{(L)})$$

→ **Sum over layer L**

You can now compute each component of the gradient !



$$Cost_i = \sum_{j=0}^{n_L-1} (a_j^{(L)} - y_j)^2$$

And how do I use this to update my bias and weights ?

Easy: use the **learning rate to update :**

$$w_{jk}^{(L)+} = w_{jk}^{(L)} - l_r * \frac{\partial Cost_i}{\partial w_{jk}^{(L)}}$$

$$b_{jk}^{(L)+} = b_{jk}^{(L)} - l_r * \frac{\partial Cost_i}{\partial b_{jk}^{(L)}}$$

Sources :

- https://www.youtube.com/watch?v=tLeHLnjs5U8&list=PLZHQB0WTQDNU6R1_67000Dx_ZCJB-3pi&index=4
- <https://mattmazur.com/2015/03/17/a-step-by-step-backpropagation-example/>