



ARC Centre of Excellence for Gravitational Wave Discovery

# TorPeDO

David McManus,<sup>1</sup> Perry Forsyth,<sup>1</sup> Giles Hammond,<sup>2</sup> Ayaka Shoda,<sup>3</sup>  
Robert Ward,<sup>1</sup> Daniel Shaddock,<sup>1</sup> David McClelland,<sup>1</sup> Bram Slagmolen<sup>1</sup>

1 Department of Quantum Science, Australian National University

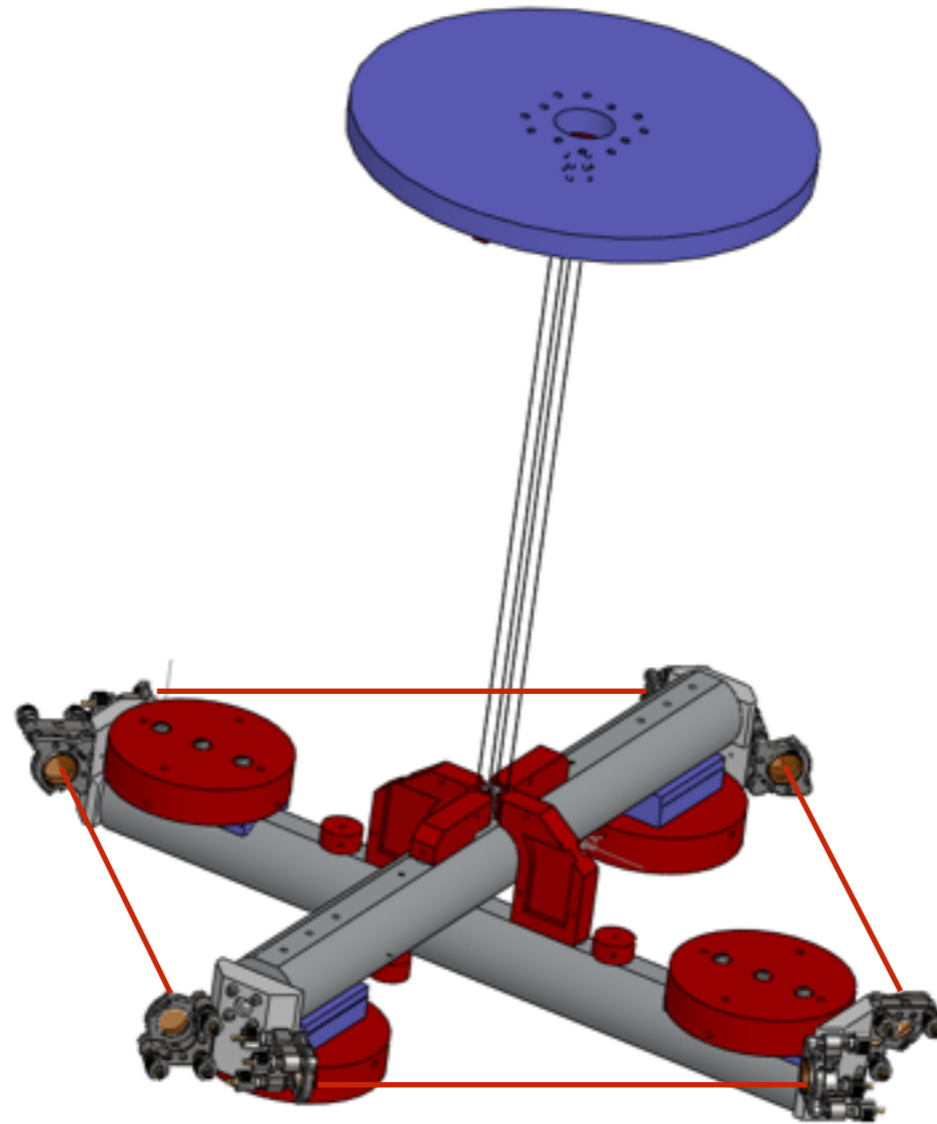
2 School of Physics and Astronomy, University of Glasgow

3 National Astronomical Observatory of Japan

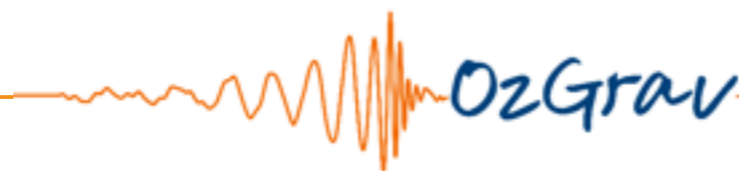


# TorPeDO

Torsion Pendulum Dual Oscillator



TorPeDO is a gravitational force sensor



# TorPeDO

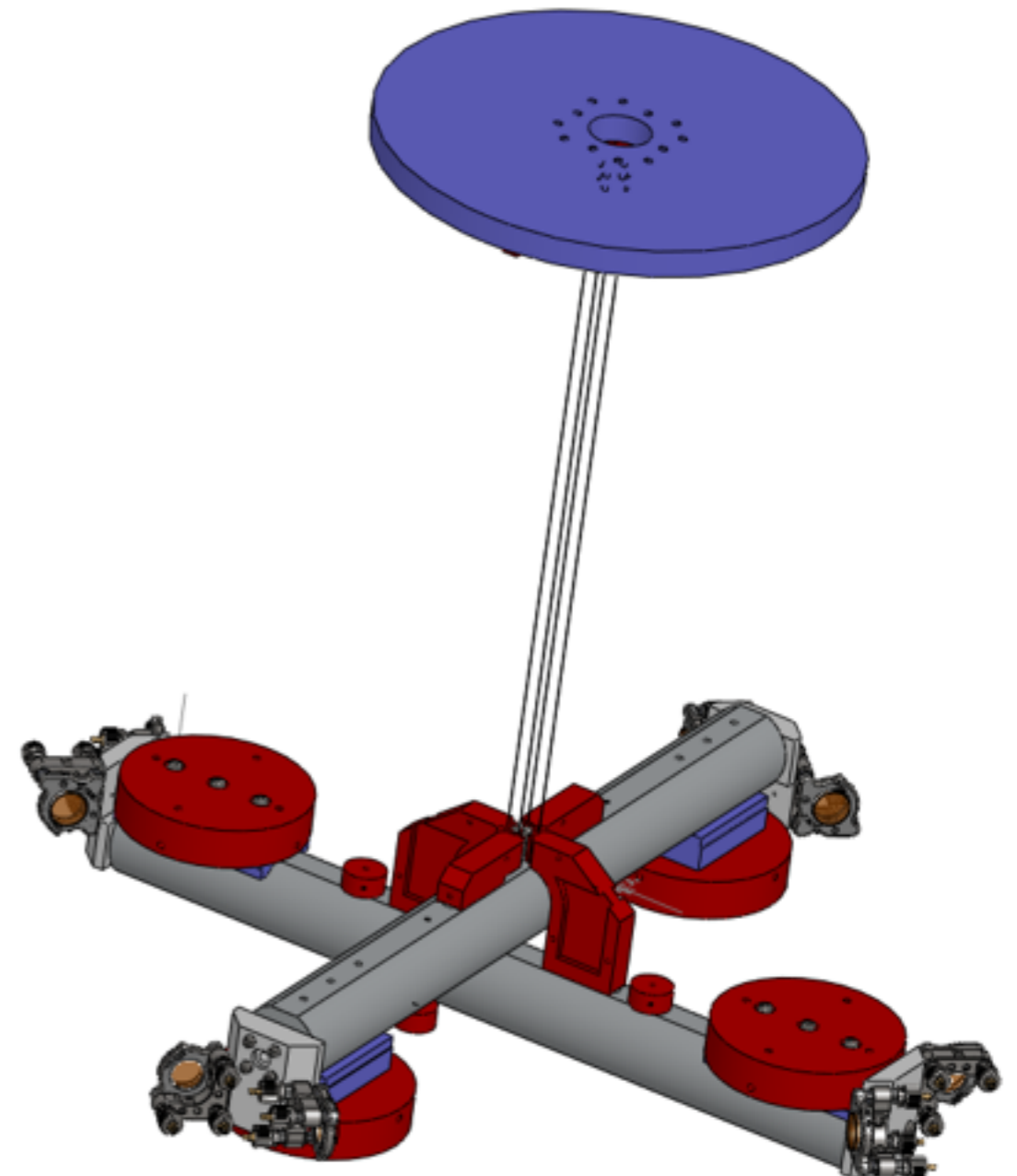
## Torsion Pendulum Dual Oscillator

*Based on the TOBA concept by Ando et. al*

TorPeDO measures gravitational forces by accurately measuring the differential rotation between two torsion pendulums.

### **Applications:**

- Measuring Newtonian noise
- Early earthquake detection
- Measuring Quantum Radiation Pressure Noise
- Testing semi-classical gravity
- Low Frequency Gravitational Wave Detector



# TorPeDO

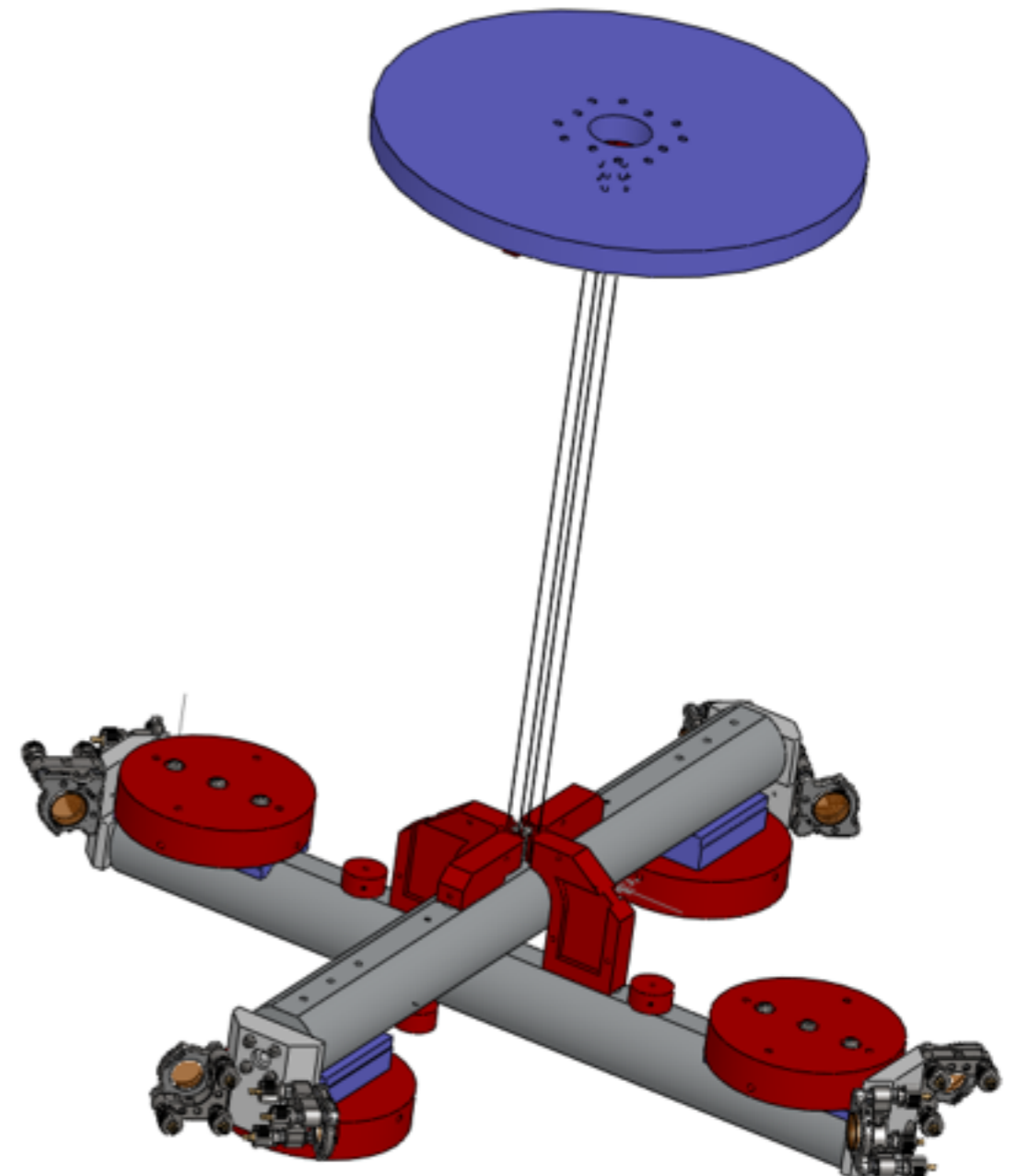
## Torsion Pendulum Dual Oscillator

*Based on the TOBA concept by Ando et. al*

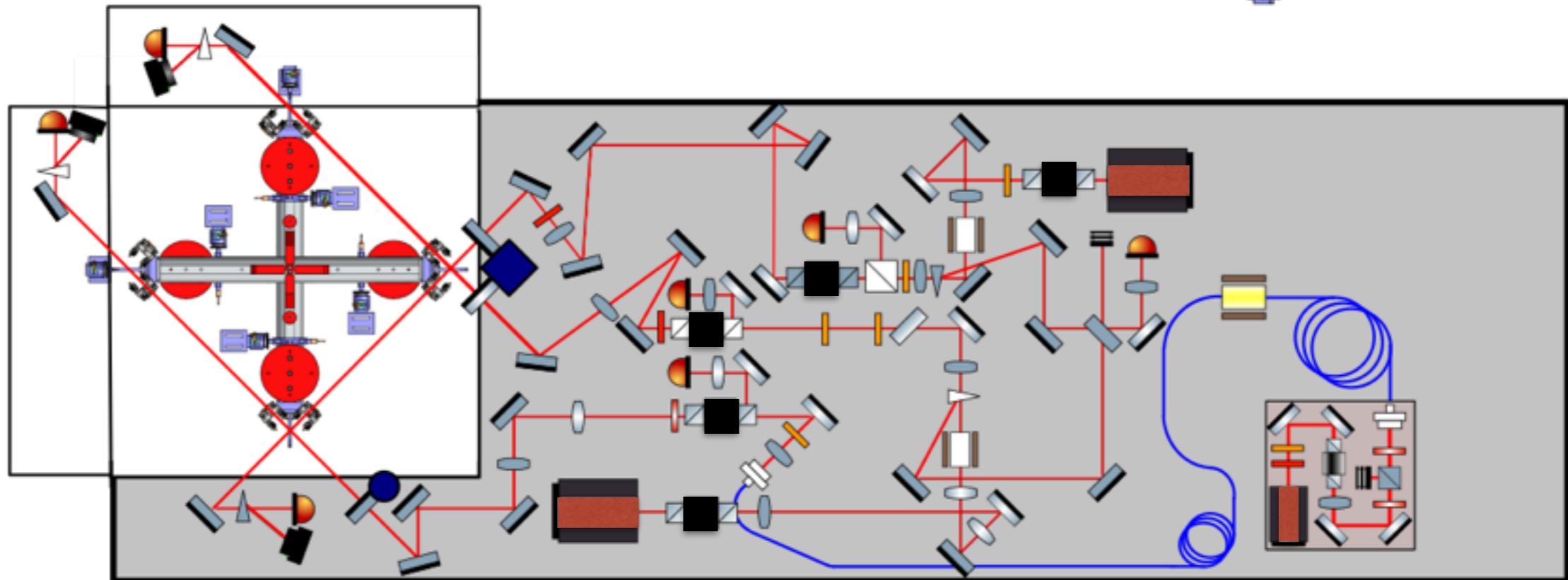
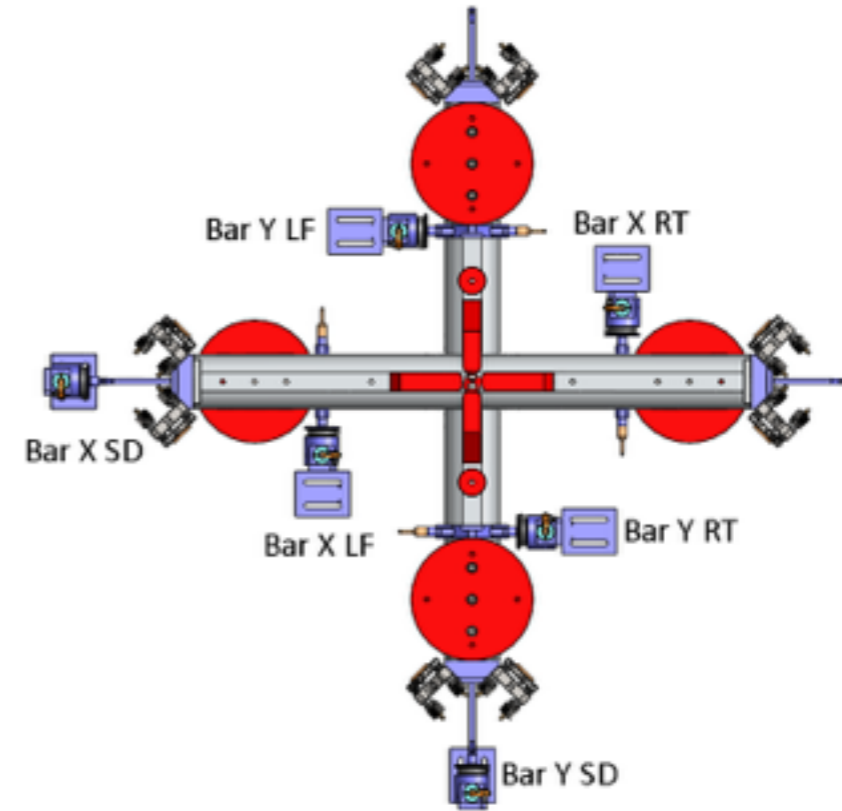
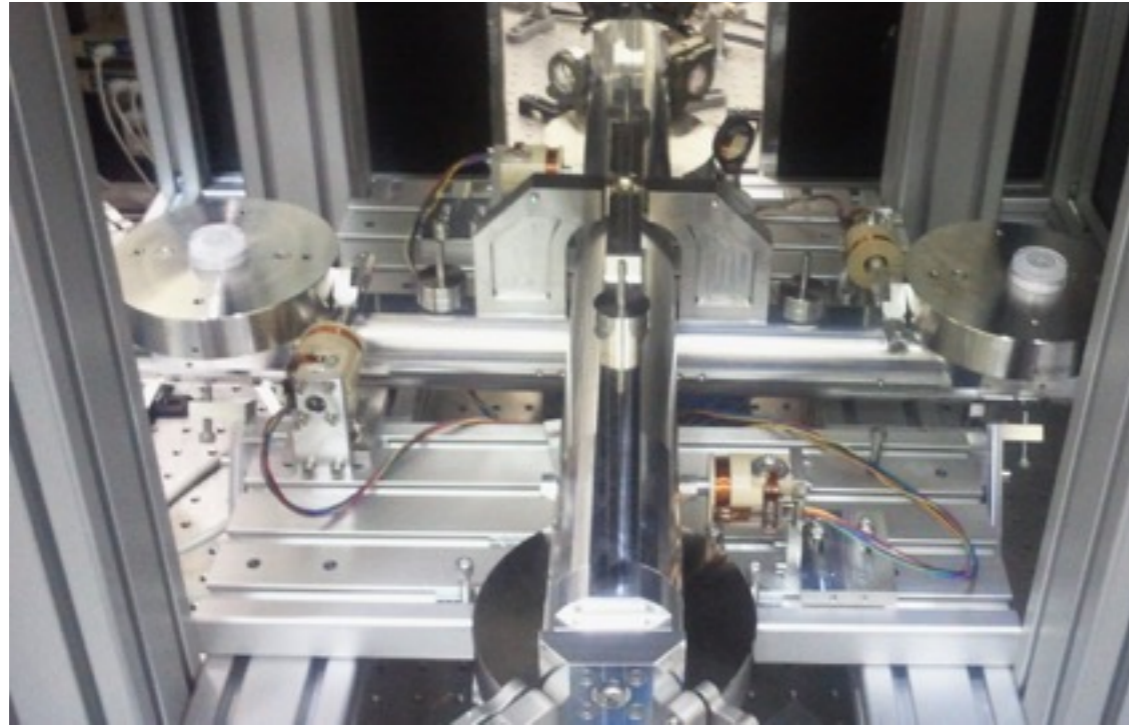
TorPeDO measures gravitational forces by accurately measuring the differential rotation between two torsion pendulums.

### Applications:

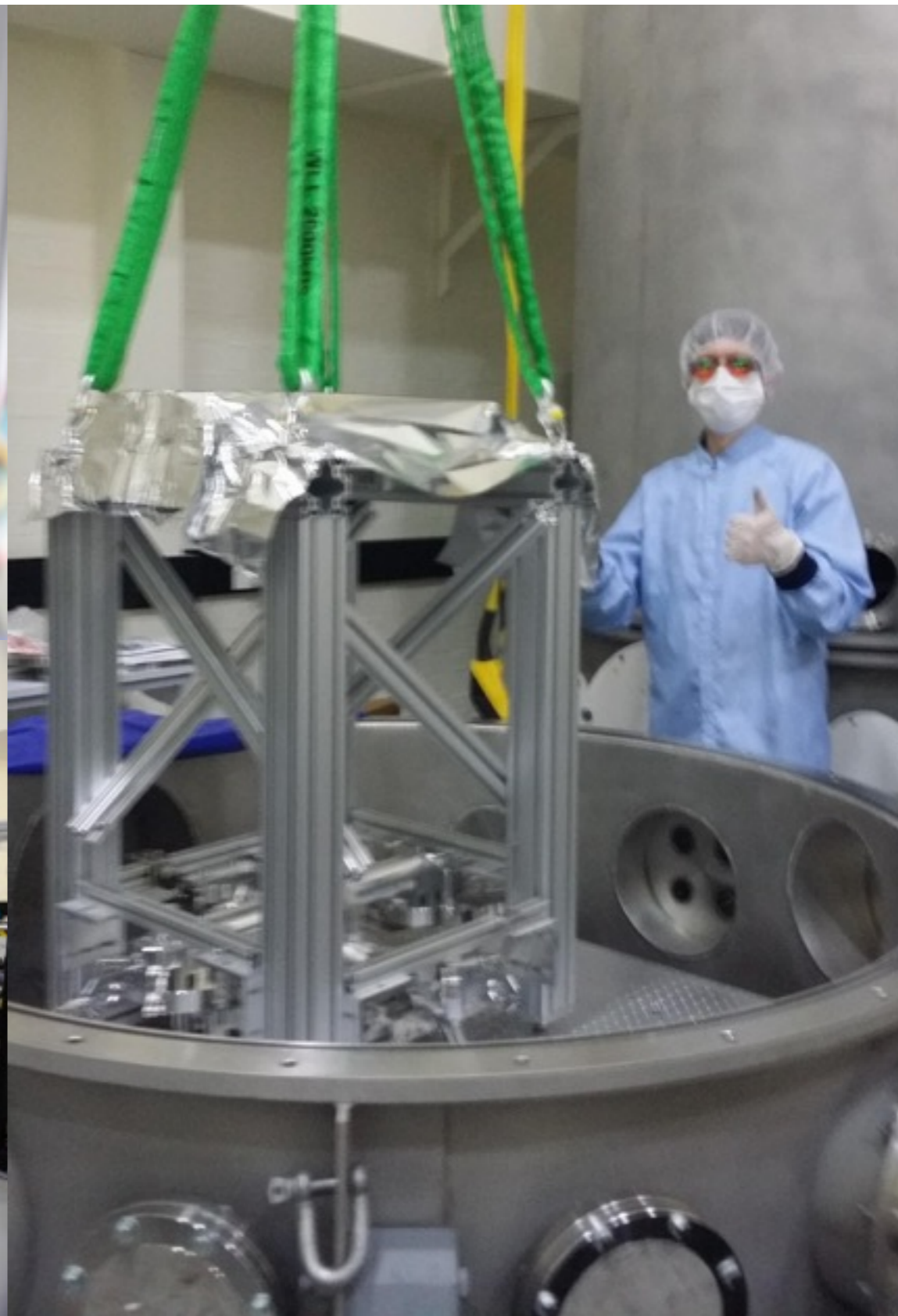
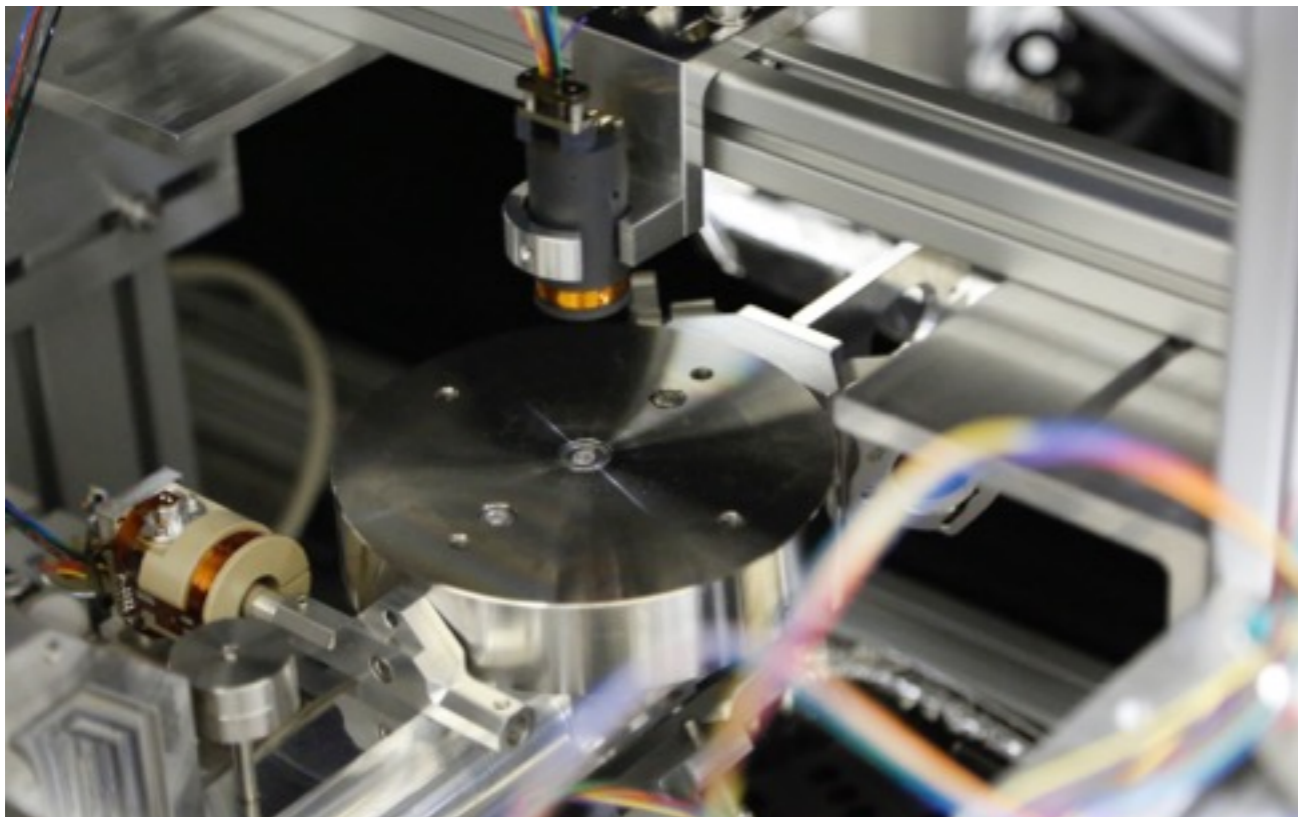
- Measuring Newtonian noise
- **Early earthquake detection**
- Measuring Quantum Radiation Pressure Noise
- Testing semi-classical gravity
- Low Frequency Gravitational Wave Detector



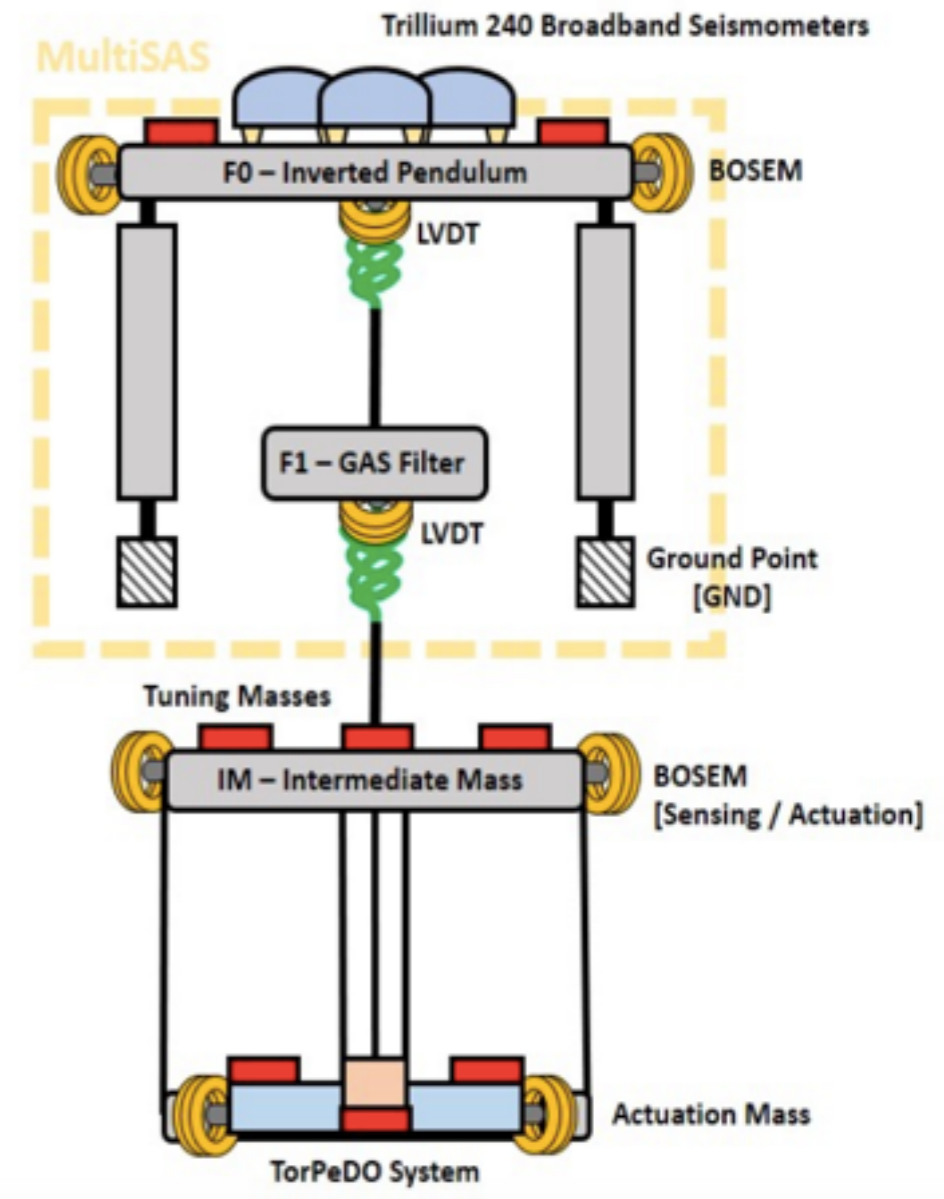
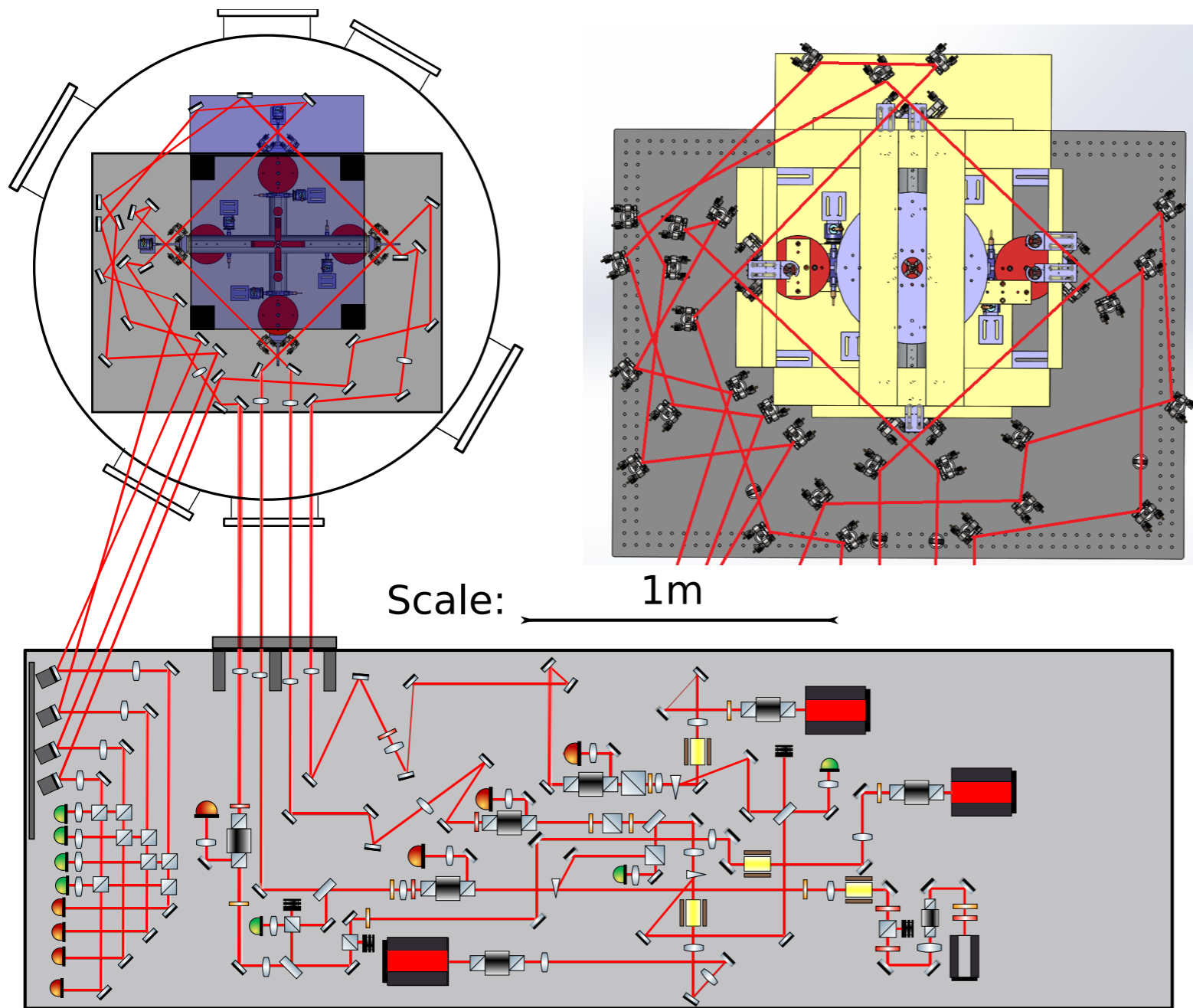
# TorPeDO (recently)



# TorPeDO (right now)

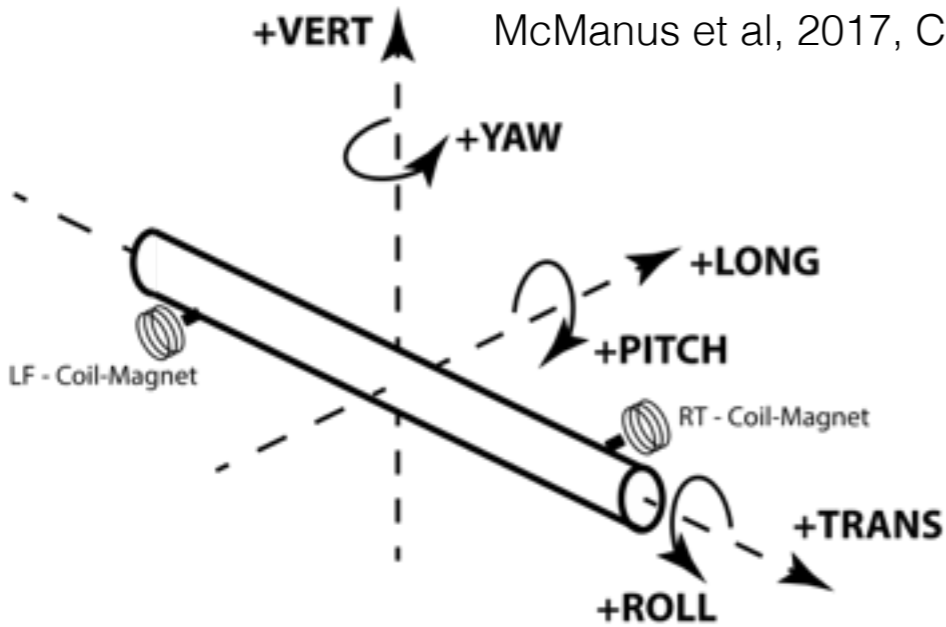


# TorPeDO (Soon)



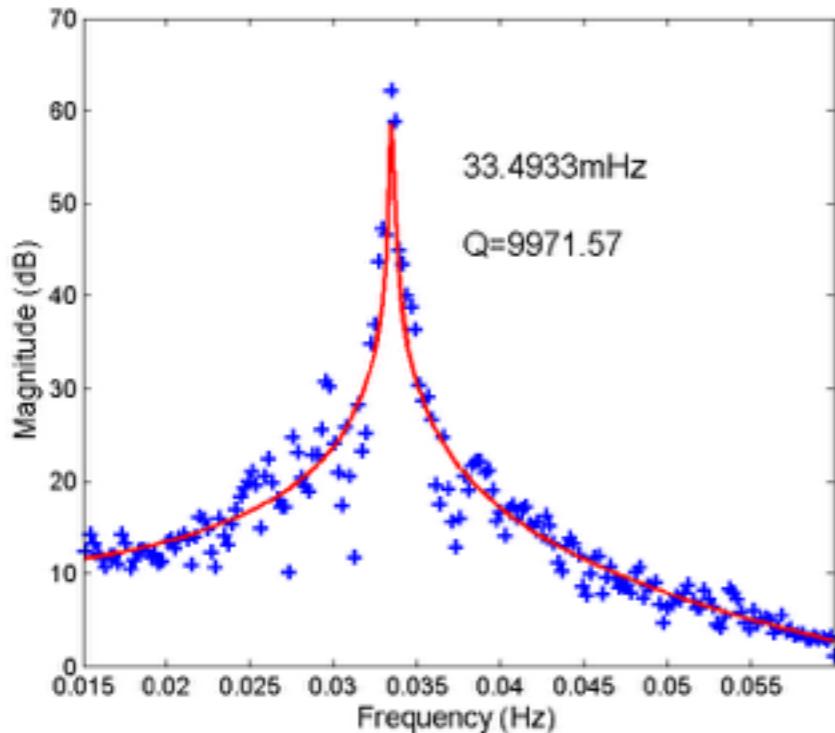
# Mechanical Properties

McManus et al, 2017, Class. Quantum Grav. <https://doi.org/10.1088/1361-6382/aa7103>

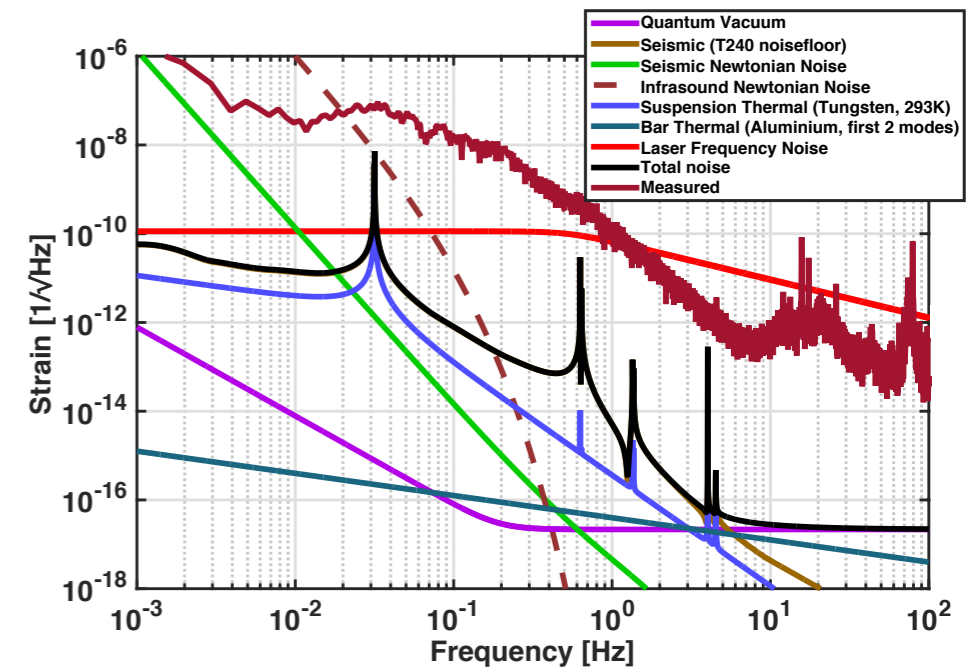
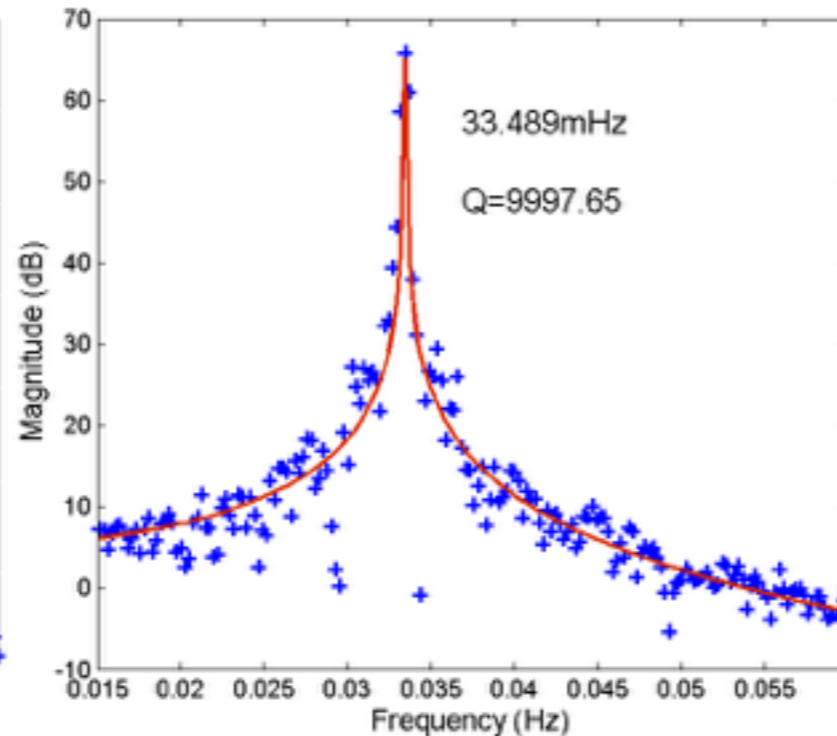


Mode	Bar 1	Bar 2	Difference
Yaw	33.4933 mHz	33.489 mHz	4.3 $\mu$ Hz
Longitudinal	0.6072 Hz	0.6077 Hz	0.53 mHz
Transverse	0.65465 Hz	0.653 Hz	1.6 mHz
Pitch	1.16286 Hz	1.14326 Hz	0.0196 Hz
Roll	4.334 Hz	3.853 Hz	0.481 Hz

Bar 1 Tuned Yaw Mode

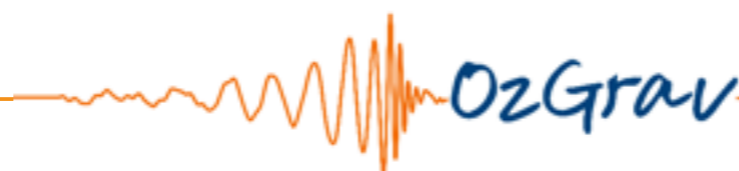
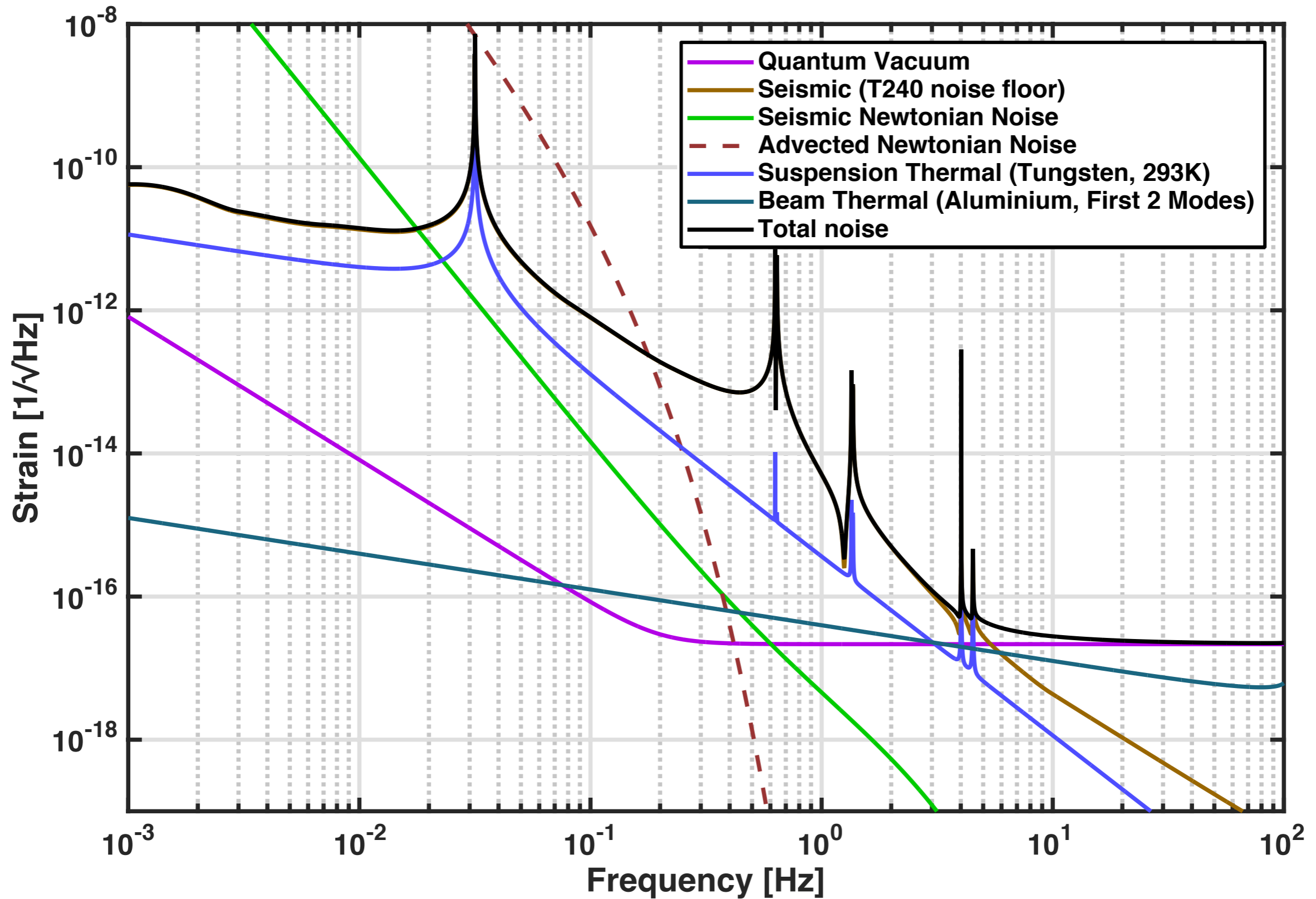


Bar 2 Tuned Yaw Mode

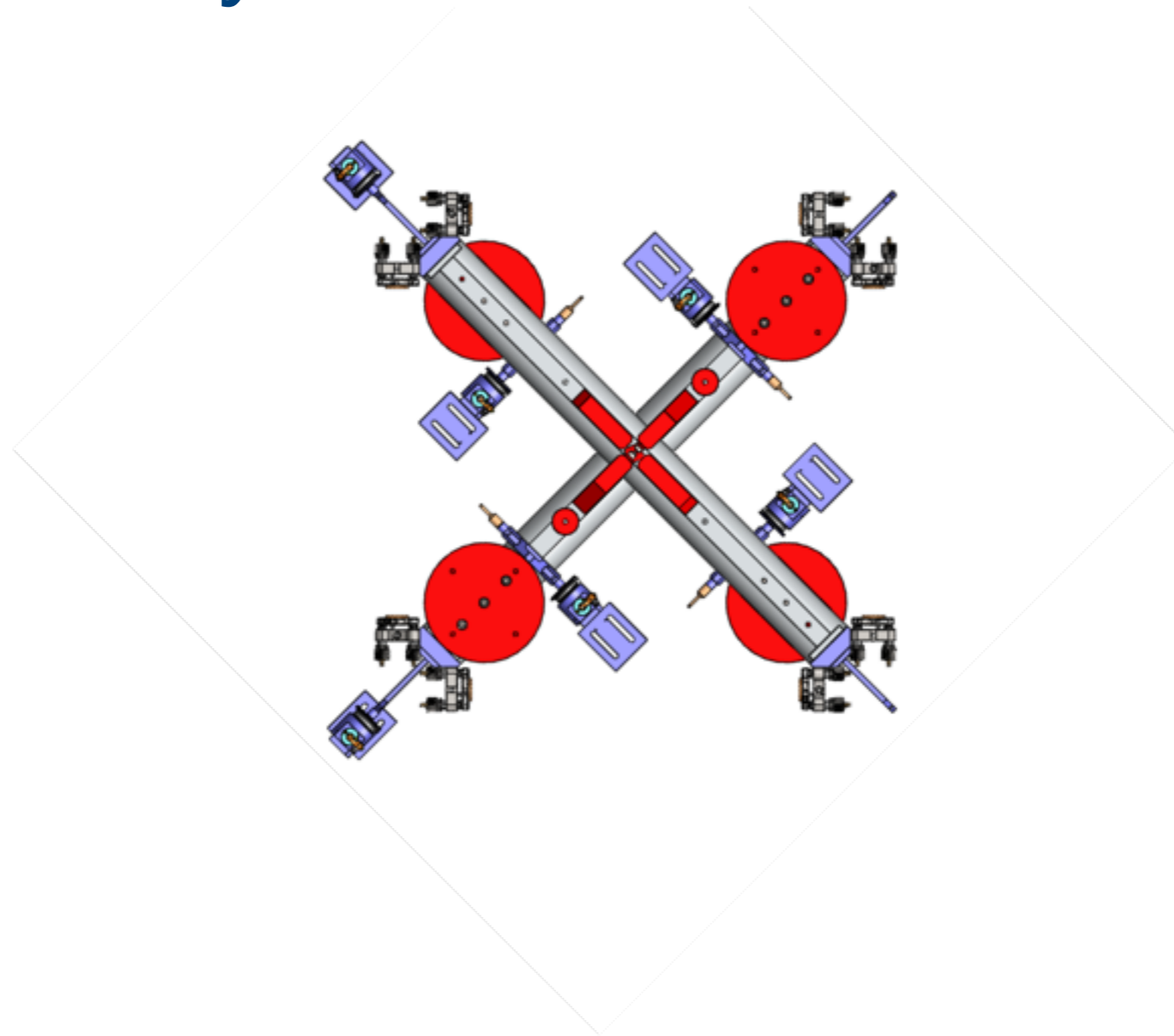




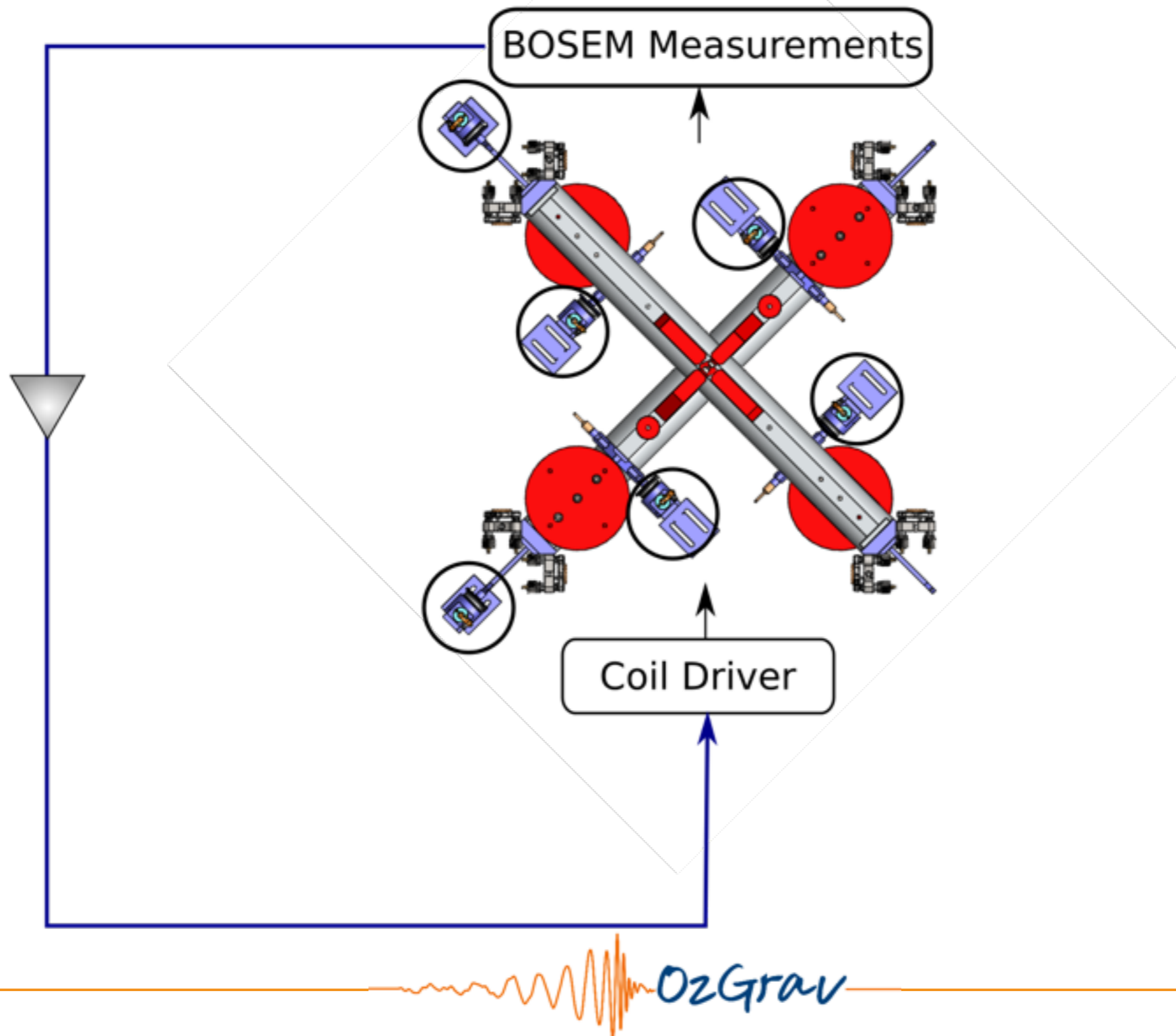
# TorPeDO Prototype Noise Budget



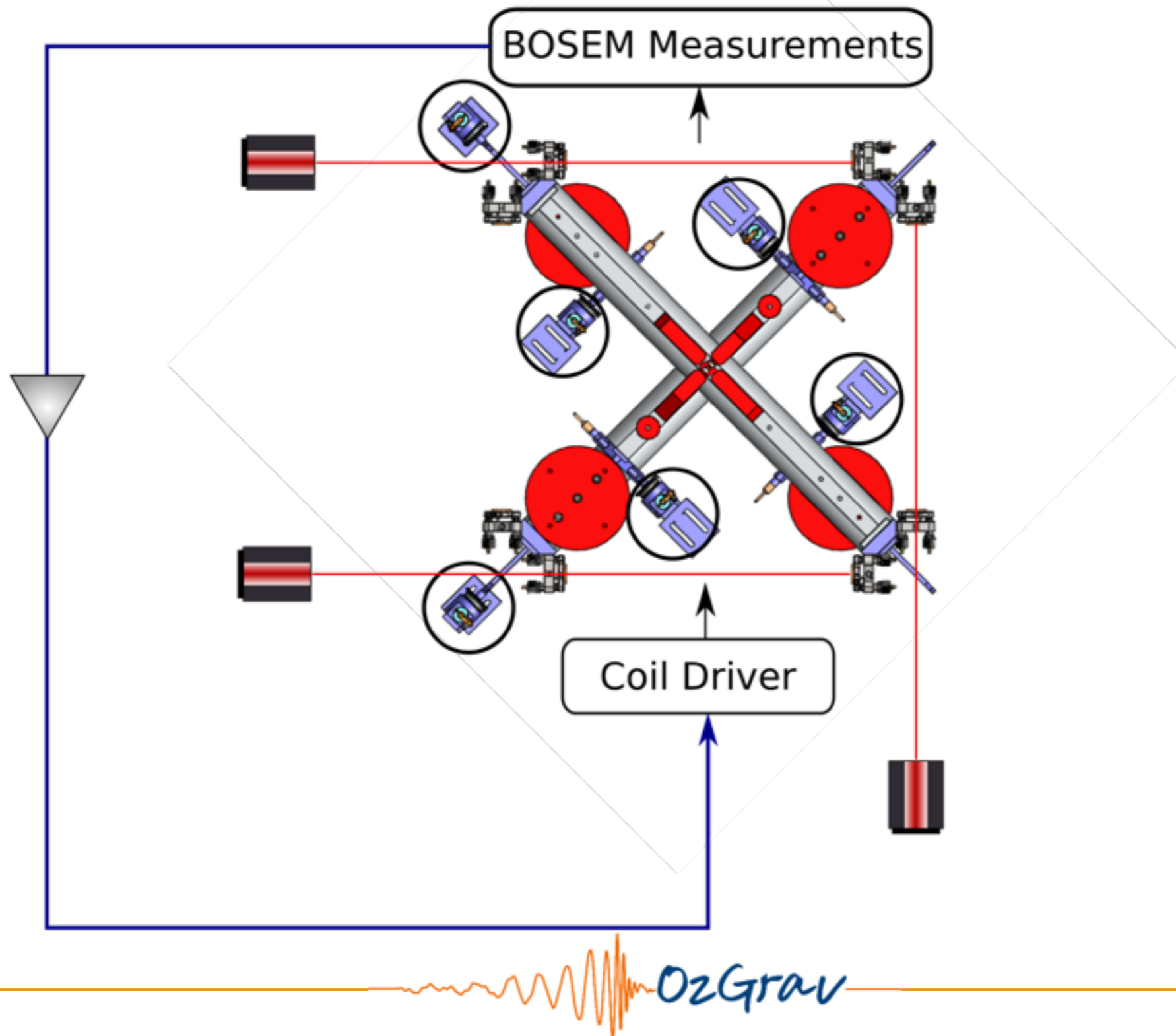
# System Control



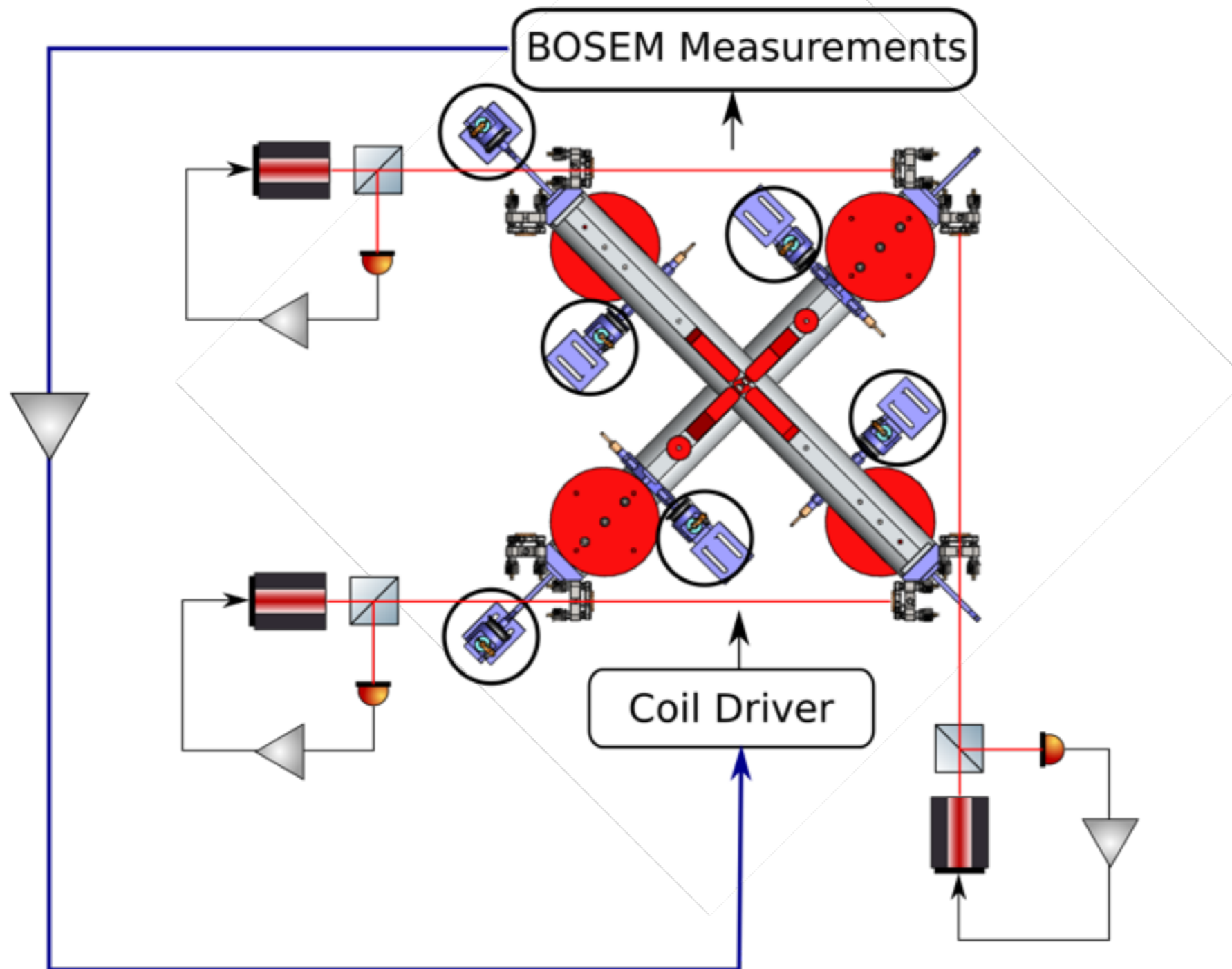
# System Control



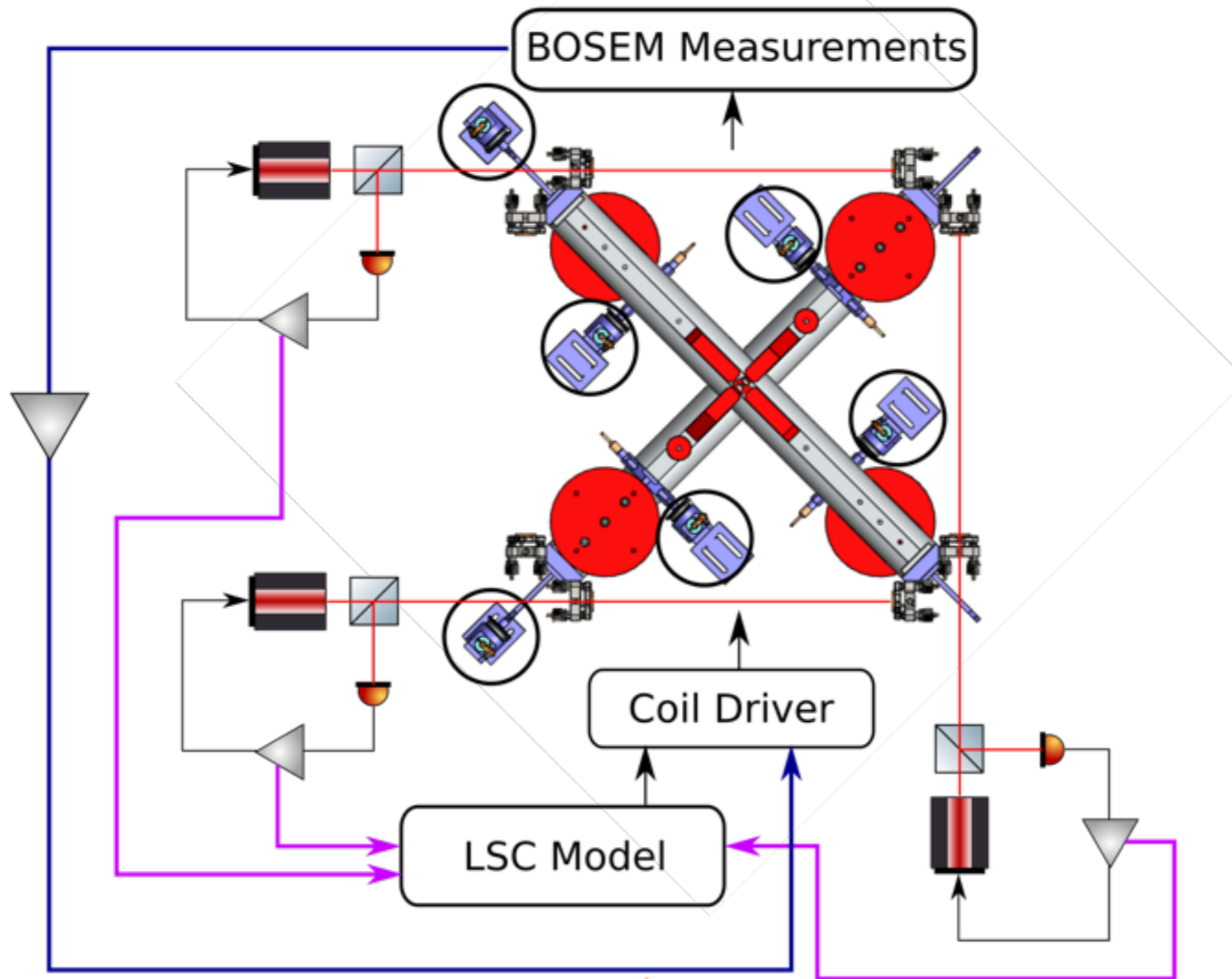
# System Control



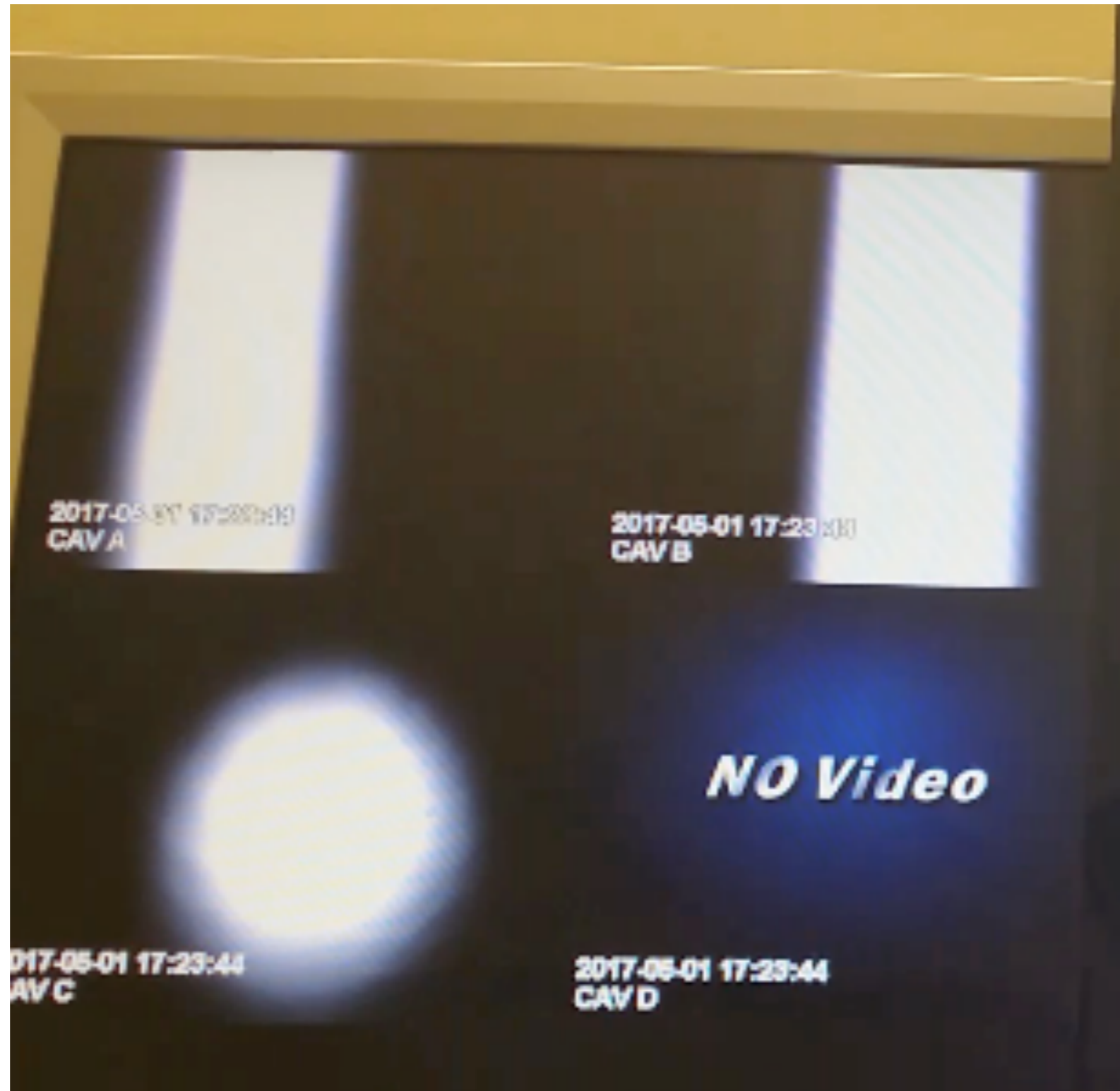
# System Control



# System Control

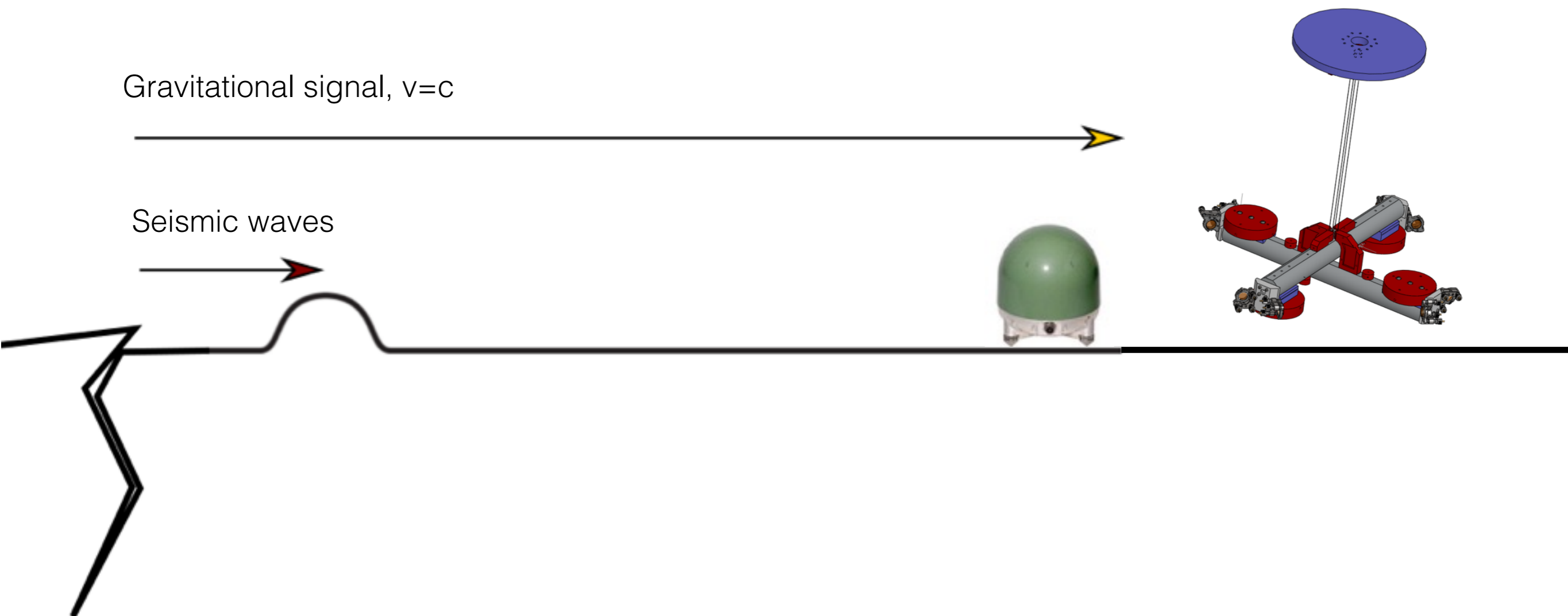


# Lock Acquisition with Guardian



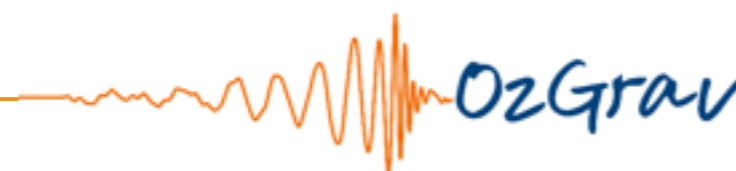
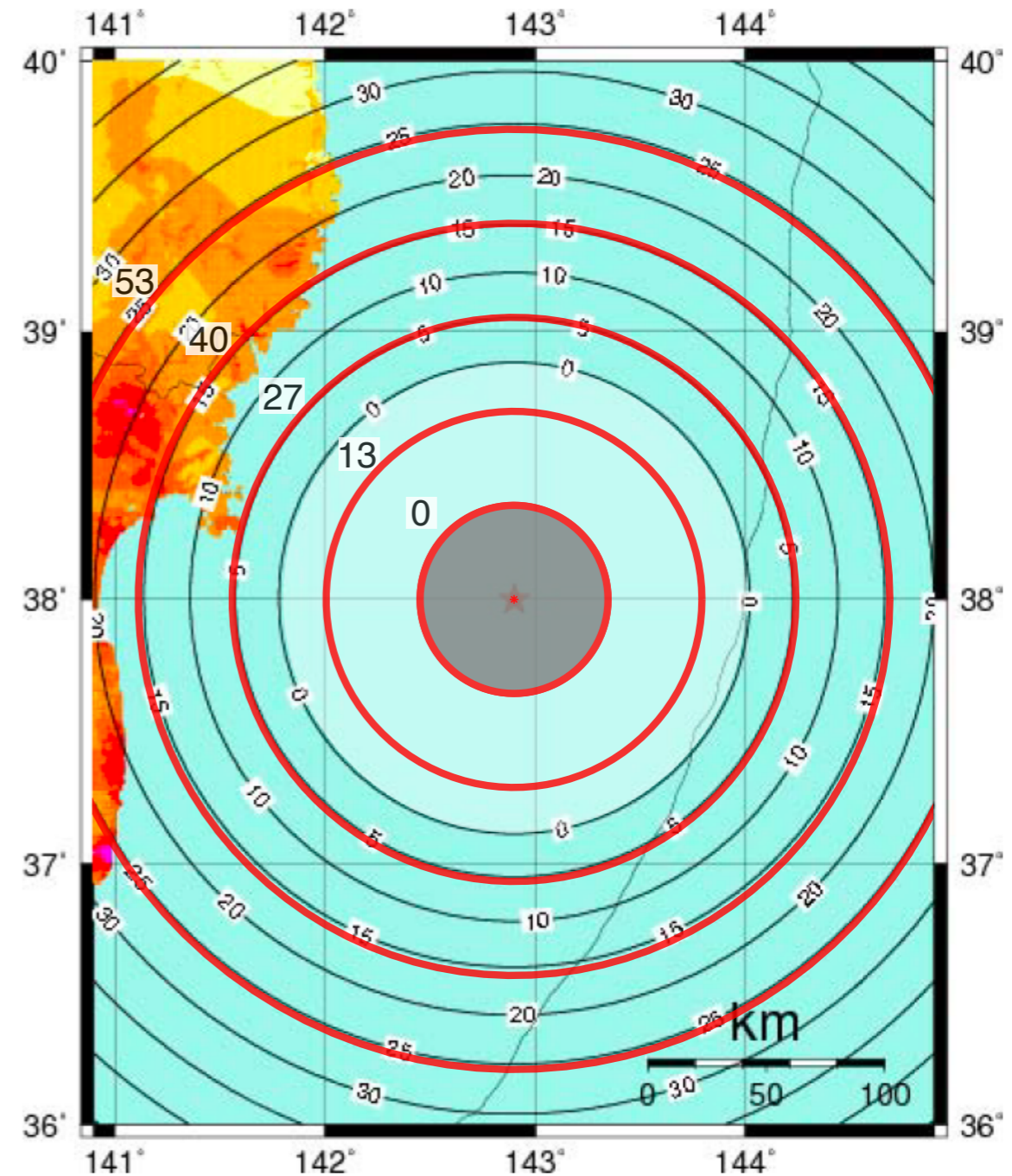
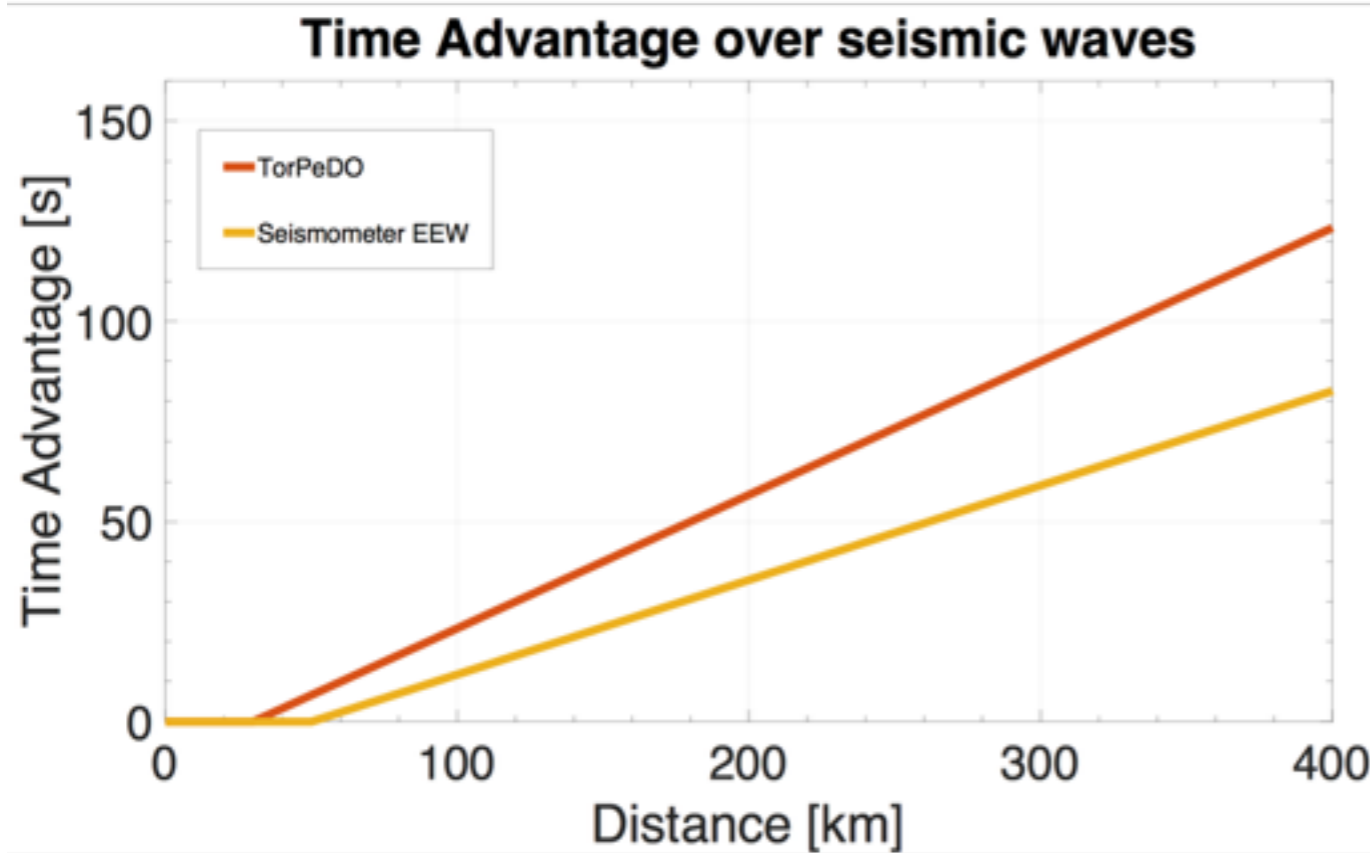
# Early Earthquake Detection

- Gravity travels faster than seismic waves
- In some cases this extra warning could allow for crucial systems to be shut off or put in a safe operating mode that may prevent injury, death, or damage to assets and infrastructure.

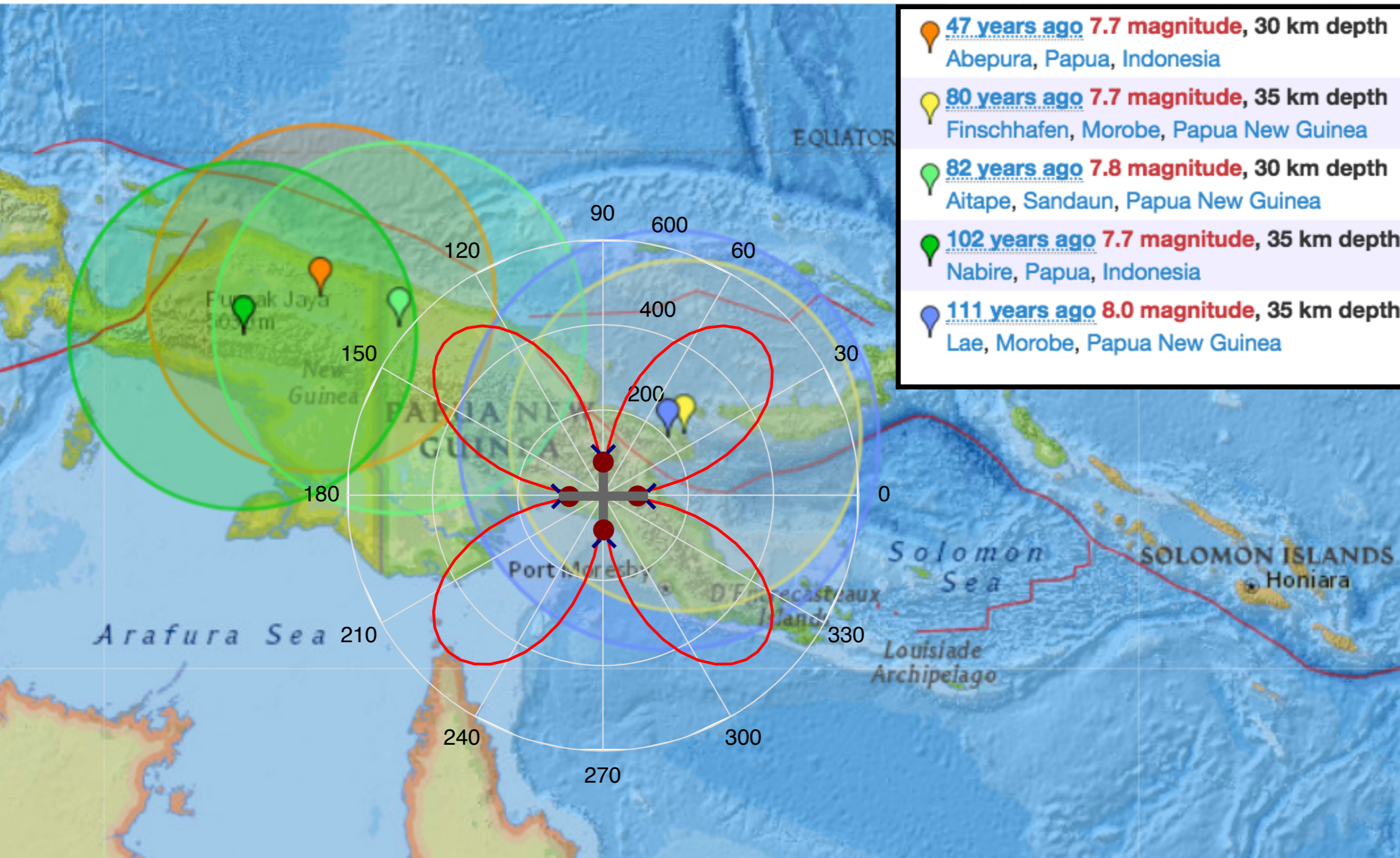




# Early Earthquake Warning



# Early Earthquake Warning

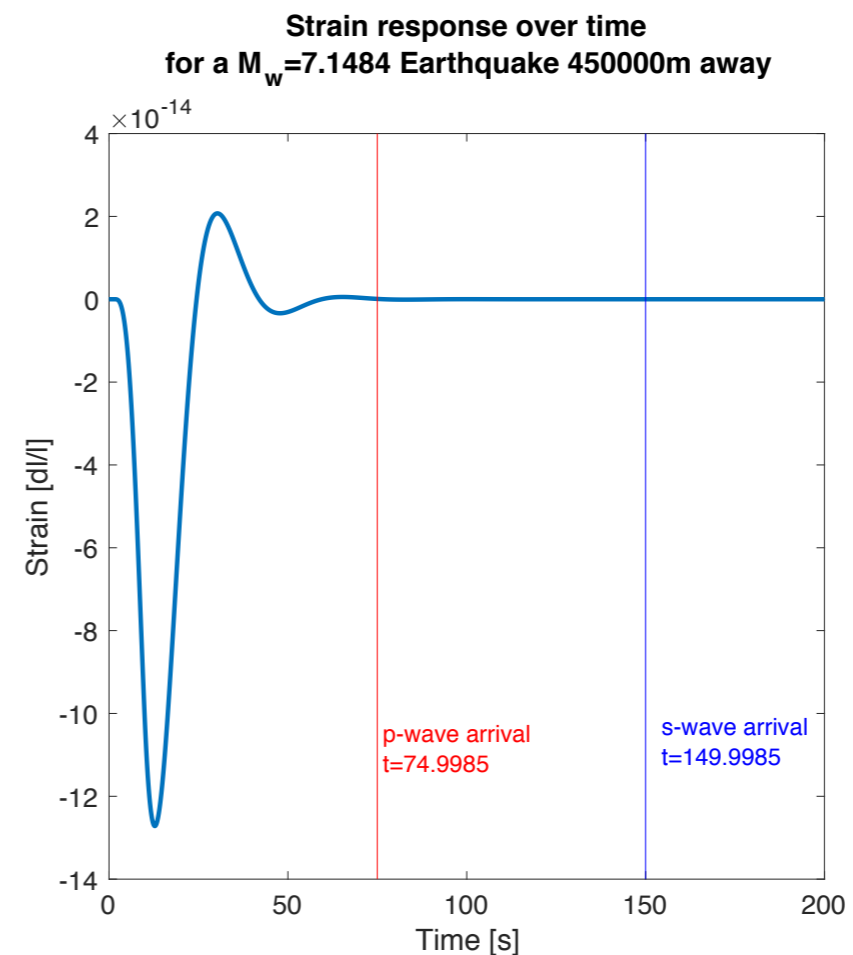
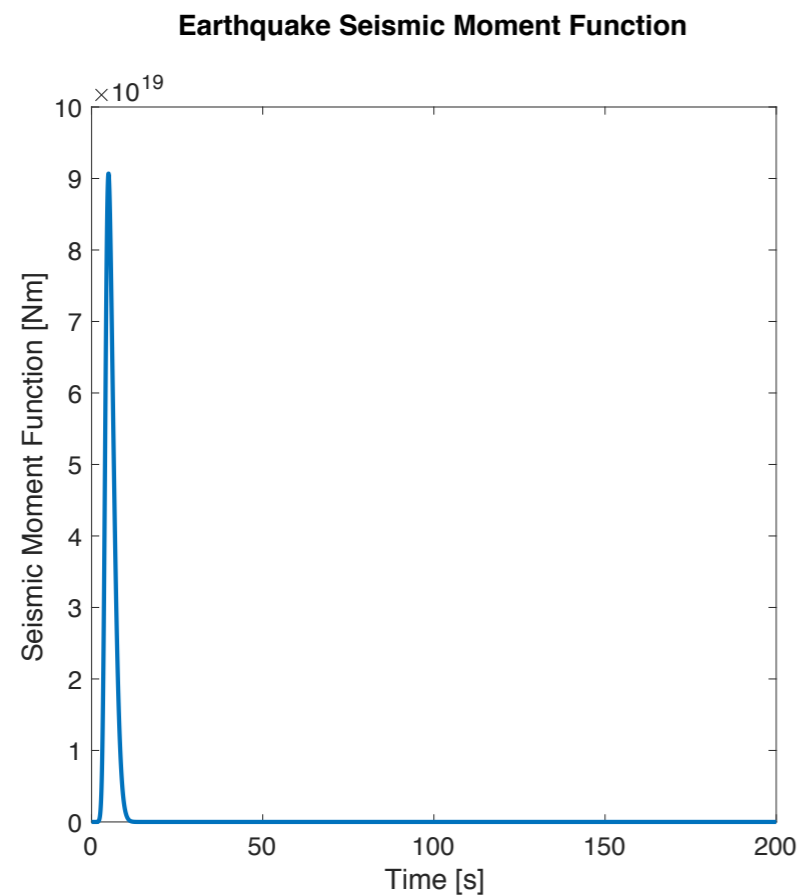


# Simulated time-domain response

Preliminary

$$\ddot{h}(r_0, t) = -\frac{6G}{r_0^5} S(\theta, \phi) \int_0^t du u M_0(t-u)$$

J. Harms, et al. Geophys. J. Int. (2015) 201, 1416–1425



# Things I'd like to look at

- Localisation accuracy and sensor placement
- Matched filtering / Signal triggering
- Parameter Estimation

# Conclusions

- The initial TorPeDO configuration allowed us to test our control scheme
- The sensor is now offline and we are upgrading to a more advanced configuration
- The applications of the TorPeDO as an early earthquake detector appear promising.