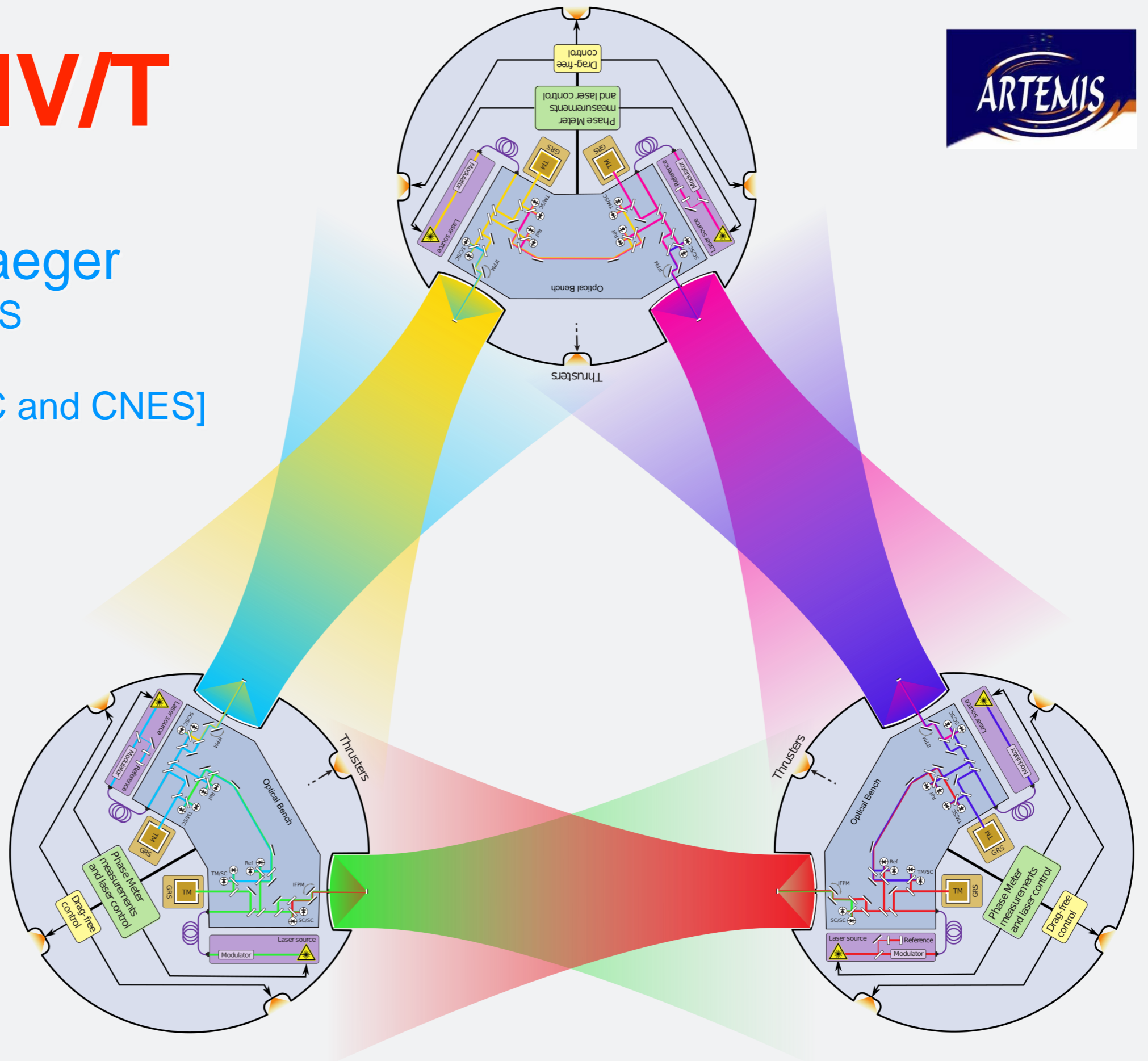


LISA AIV/T



N. Dinu Jaeger
ARTEMIS

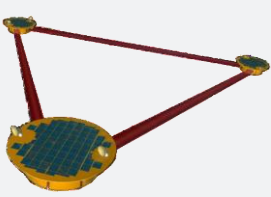
[joint work with APC and CNES]



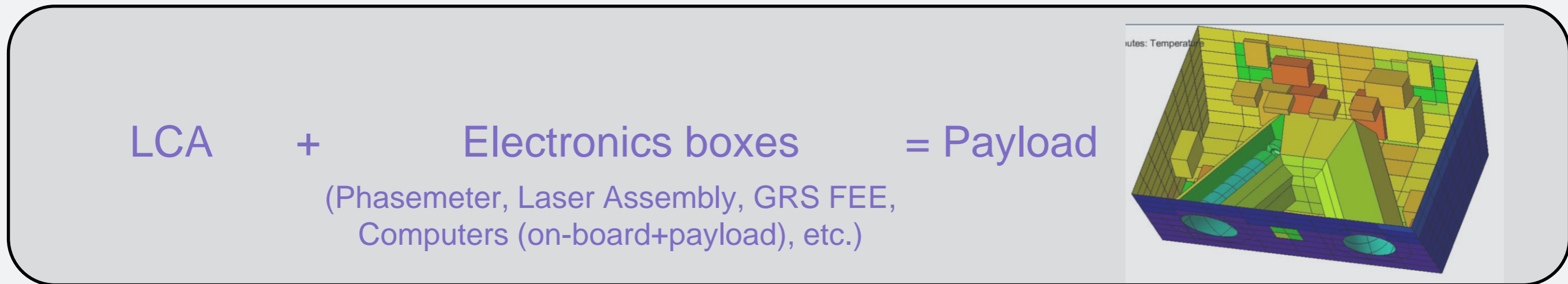
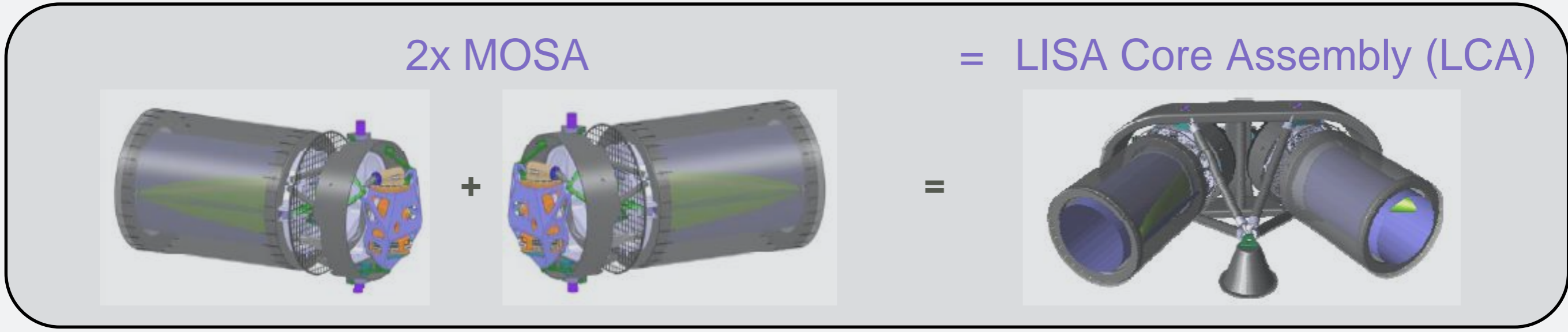
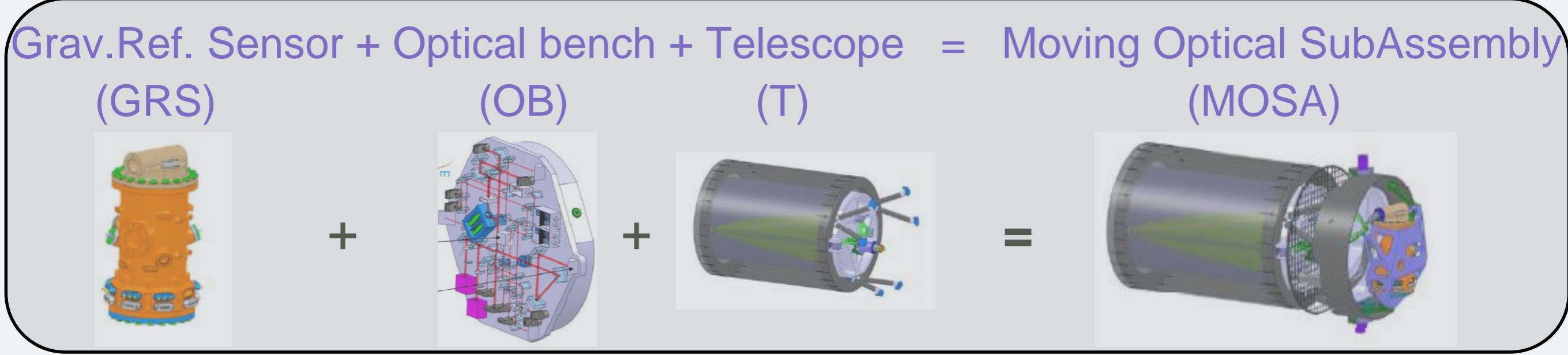


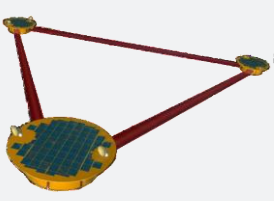
Outline

- General configuration of LISA payload & MOSA
- Top level MOSA AIV/T flow description
- Main French MOSA AIV/T activities
- Proposal for French activities organization
- Possible activities for scientific laboratories teams



LISA Payload elements on each S/C





Most recent MOSA architecture (based on new USA telescope design)

Viewing Don de Wilde's applications



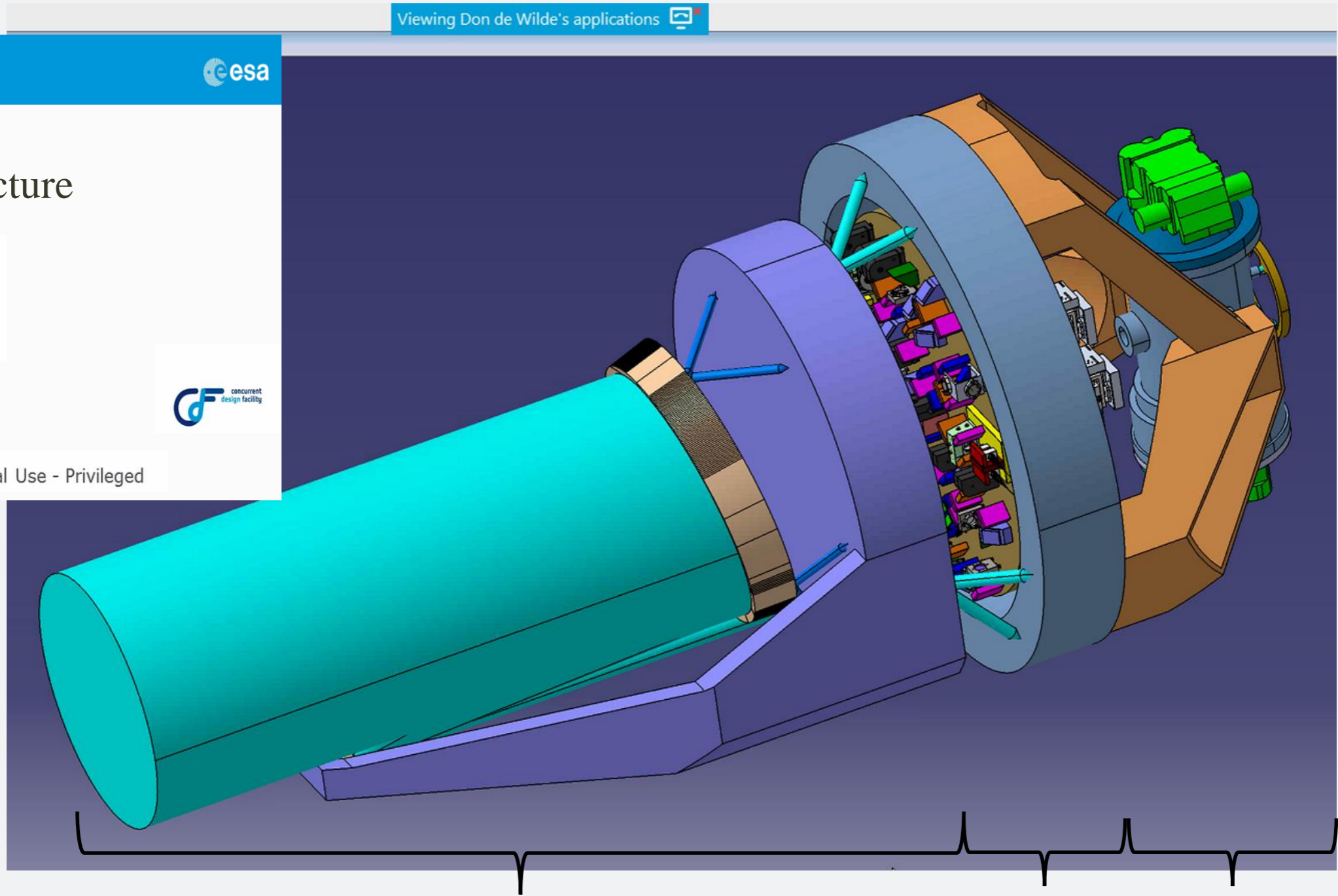
MOSA Architecture

Prepared by the CDF* Team

(* ESTEC Concurrent Design Facility



ESA UNCLASSIFIED - For Official Use - Privileged

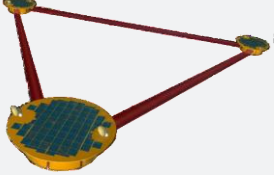


Telescope + Baffle + Bobsled

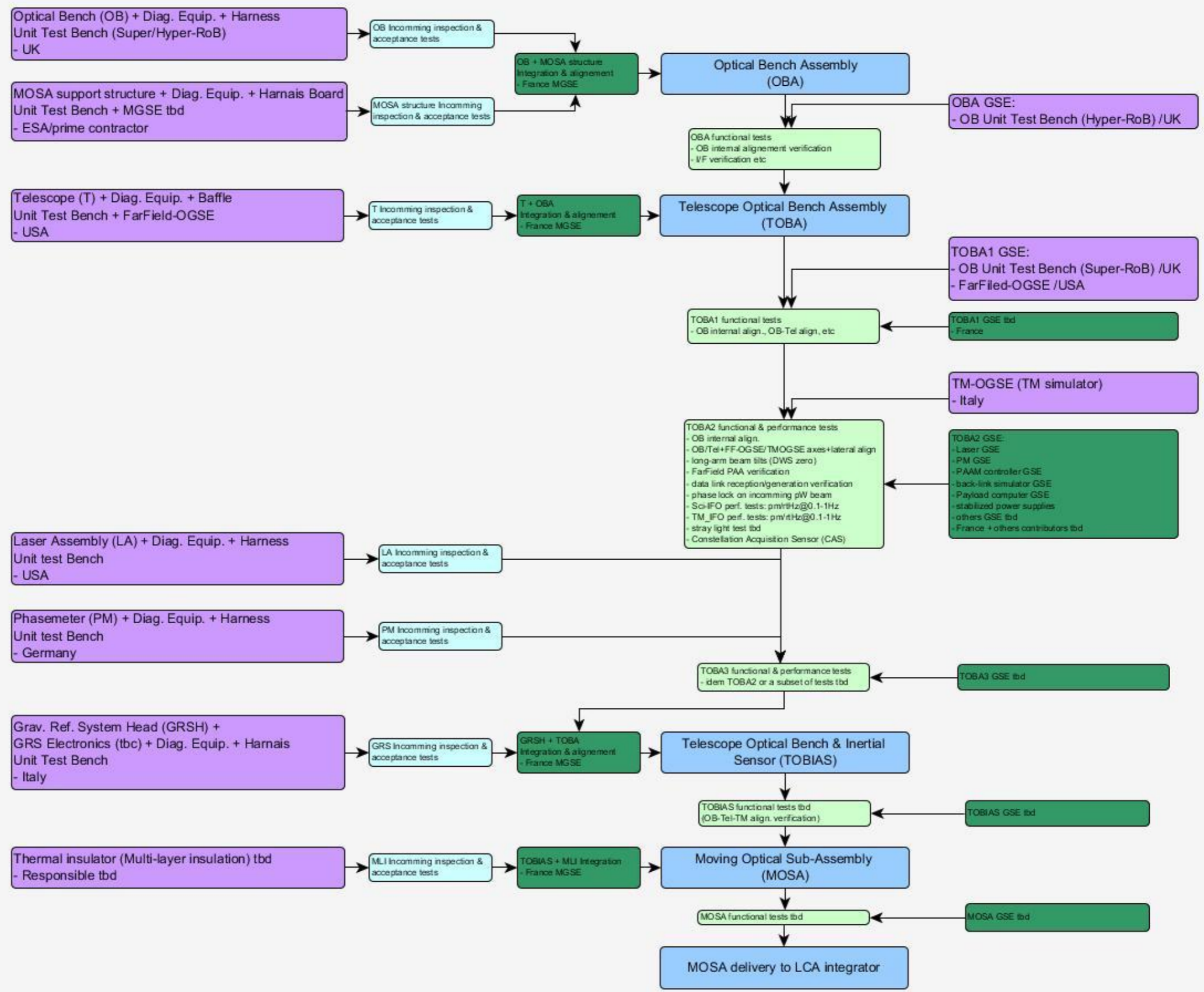
OB

GRS

MOSA support structure with internal interfaces between OB, Tel & GRS head still to be defined

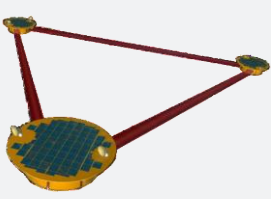


MOSA Top Level AIV/T Flow



Legend of colours:
 Magenta: units + additional elements to be delivered by various providers
 Light blue: acceptance tests, to be defined by various units providers, carried out by France with units providers
 Light green: functional/performance tests to be carried out by France (+help of various providers)
 Dark green: GSE to be developed by France (+ other contributors)
 Dark blue: integrated sub-assemblies

MOSA Top Level AIV/T Flow
 N. Dinu Jaeger (ARTEMIS)/ H. Halloin (APC)
 V0.2 21/09/2017



Units test benches

- Delivered together with the corresponding unit (OB, Tel, LA, PM etc.)

- Aimed to be used for units acceptance tests (check that units satisfy the specifications) at the entrance to the integration facility

- When possible, they can be used for tests during integration steps

Example: OB unit test bench

RoB

- Opto-mechanical GSE

- Read-out box: simple, battery powered, allowing to read out spot position from individual photodiodes (a suitable laser should be connected to the system);

Super RoB (already prepared for LISA Pathfinder)

- Same as RoB, but with its own laser system, that can illuminate fiber inputs

- Able to read out all photodiodes simultaneously;

- Can be used to monitor and minimize distortions during various integration stages;

- Gives functional tests of OB: integrity of fibers and optics on the bench, integrity, function and position stability of photodiodes

Hyper-RoB

- To be developed

- Including Optical Telescope simulator

- Simulates the laser beam entering from the Telescope to the OB

- Monitor and record the properties of the beam sent from OB to Telescope



Specific simulators delivered by units providers

- **Far-Field Optical Ground Support Equipment (FF-OGSE)**
 - Simulates the characteristics of the laser beam entering the telescope
 - Direction
 - Low intensity (nW/m^2)
 - Truncated Gaussian beam shape (it should illuminate more than telescope diameter)
 - Wavefront quality
 -

- **Test-Mass Optical Ground Support Equipment (TM-OGSE)**
 - Mirror with 3 DoF (2 angles and 1 translation)
 - Mimic the movement of the test mass within its enclosure



Main French AIV/T activities

- Set-up a dedicated integration facility
- Carry out the reception of main MOSA units, units test benches and specific simulators
 - OB, Telescope, GRS, LA, Phasemeter delivered by consortium/USA providers
 - MOSA mechanical structure, provided by ESA Prime contractor
 - Simulators: Far Field OGSE, Test Mass OGSE by consortium/USA providers
 - Perform inspection and acceptance tests, with support from units providers
- Integrate the OB, Telescope and GRS head into the MOSA mechanical structure
- Test the alignment and shows that it stays into the defined budget
- Carry out functional and performance tests at various integration steps and shows that various assemblies satisfy the specifications
- Deliver integrated and tested MOSA to prime contractor



Proposal for French AIV/T activities organization

- MOSA AIV/T requires two specialized teams
 - Flight equipment integration
 - Precise/fine metrology

- Proposal
 - Set-up the integration activity in a unique place/site in France, having:
 - Dedicated infrastructure
 - Clean-room of large surface (50-100 m²), class 100
 - Mechanical GSE
 - Big vacuum chamber with thermal/vibration control (~2 m diameter, 2-3 m long)
 - μm precision 3D coordinates measurement machine
 - Trained/authorized personnel with background on integration
 - Takes in charge the main integration steps, excepting the environment tests
 - Develop MGSE equipment's for integration and alignment
 - Ex: Mechanical bench required to maintain full MOSA elements
 - Precise metrology under the responsibility of scientific laboratories teams
 - Work in combined team (integration + metrology) on integration site



Possible activities to be developed by scientific laboratories teams

- Define specifications of functional/performance tests to be carried out at various MOSA integration steps
 - Heterodyne efficiency
 - Pointing stability
 - Photodiodes calibration
 - Stray light
 -
- Design, develop & commission specific test benches (OGSE, EGSE) to MOSA integration facility for MOSA functional/performance tests during integration
- Train the personnel at integration facility site to use test benches and to perform tests
- Process the test results and validate the performances
- When tests are not possible (too long, costly etc.), perform modelling for performance validation
- (Some) required competences
 - Electronics, optics, software.....



Additional slides



(Some) required infrastructures

- Required equipments during the integration / validation phases:
 - ~50 m² electronics lab (ambient cleanliness level)
 - ~50 m² clean rooms (1000 / 10000 / 100 000)
 - Coordinate measurement machine (~1 μm level, 1.5x1.5x1.5 m³)
 - Thermal vacuum tanks with associated equipments (temperature sensors, etc.)
 - Programmable power supplies, precision multimeters, communication protocols inspector, precision phasemeter/counters, etc.
 - High bandwidth data logging devices and infrastructure (acquisition and analysis SW, archiving, ...)
 - Optical benches (Zerodur ?), lasers (seeder, frequency reference, modulator, amplifier), optical components, single element and quadrant photodiodes, ...
 - Piezo driven actuators, thermal compensating mount set-up, remote alignment translation tables



Key performance values

Telescope:

- 30 cm diameter,
- Pathlength stability: $\sim 1 \text{ pm}/\sqrt{\text{Hz}}$

Laser

- Wavelength 1064 nm, 2 W emitted (received $\sim 750 \text{ pW}$)
- RIN : $< 10^{-8} / \sqrt{\text{Hz}}$ above 5 MHz
- Frequency stability $\sim 300 \text{ Hz}/\sqrt{\text{Hz}}$
- Frequency modulation amplitude: $\pm 30 \text{ MHz}$
- Phase modulation at $(2.3 \pm 0.5) \text{ GHz}$

Phase measurement bandwidth

- 5-25 MHz

Timing jitter in clock distribution: $\sim 4 \times 10^{-14} \text{ s}/\sqrt{\text{Hz}}$

Absolute ranging accuracy: $\sim 10 \text{ cm}$

Thermal stability (optical bench): $< 1 \text{ mK}/\sqrt{\text{Hz}}$ at 1 mHz

Laser beam pointing jitter: $\sim 2 \text{ nrad}/\sqrt{\text{Hz}}$

Alignment accuracy of the sub systems during integration: $\sim 10 \text{ } \mu\text{m} / 1 \text{ mrad}$



Proposed model philosophy

- The consortium is responsible for delivering
 - **integrated/tested/validated MOSAs**

- Model philosophy (definition still in progress)
 - **Elegant BreadBoard (EBB)**
 - Demonstrates mechanical/optical/electrical interfaces
 - OB - Telescope: optical, mechanical
 - OB – PM - Laser: electrical, optical, functional; should be at unit level?
 - OB - Telescope-GRS: mechanical
 - CAS – Telescope
 -
 - Uses representative assemblies, but non flight (still modifiable)
 - **Structural/Thermal Model (STM)**
 - Validates mechanical interface, mechanical charges and thermal compartment
 - Uses dummy assemblies/units
 - **Engineering (Qualification) Model (E(Q)M)**
 - Validates MOSA/payload conception and its AIV/T process
 - Uses flight representative assemblies/units
 - It is submitted to qualification tests (launch resistance and spatial environment)
 - **6 Flight Models (FM)**
 - Idem as E(Q)M
 - Submitted to acceptance tests (verification of technical conformity) and non-qualification