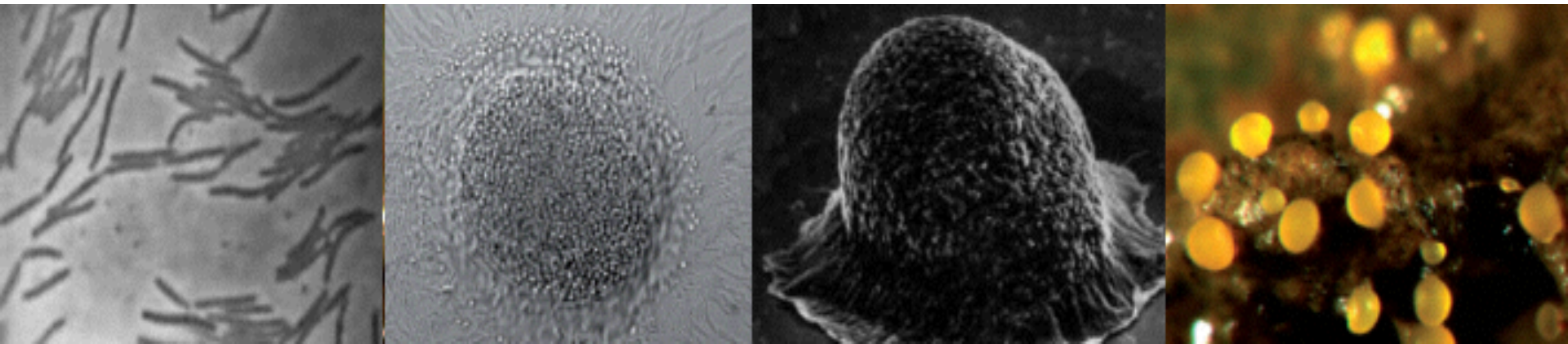


Towards a non-equilibrium statistical mechanics approach of biological systems

Fernando Peruani

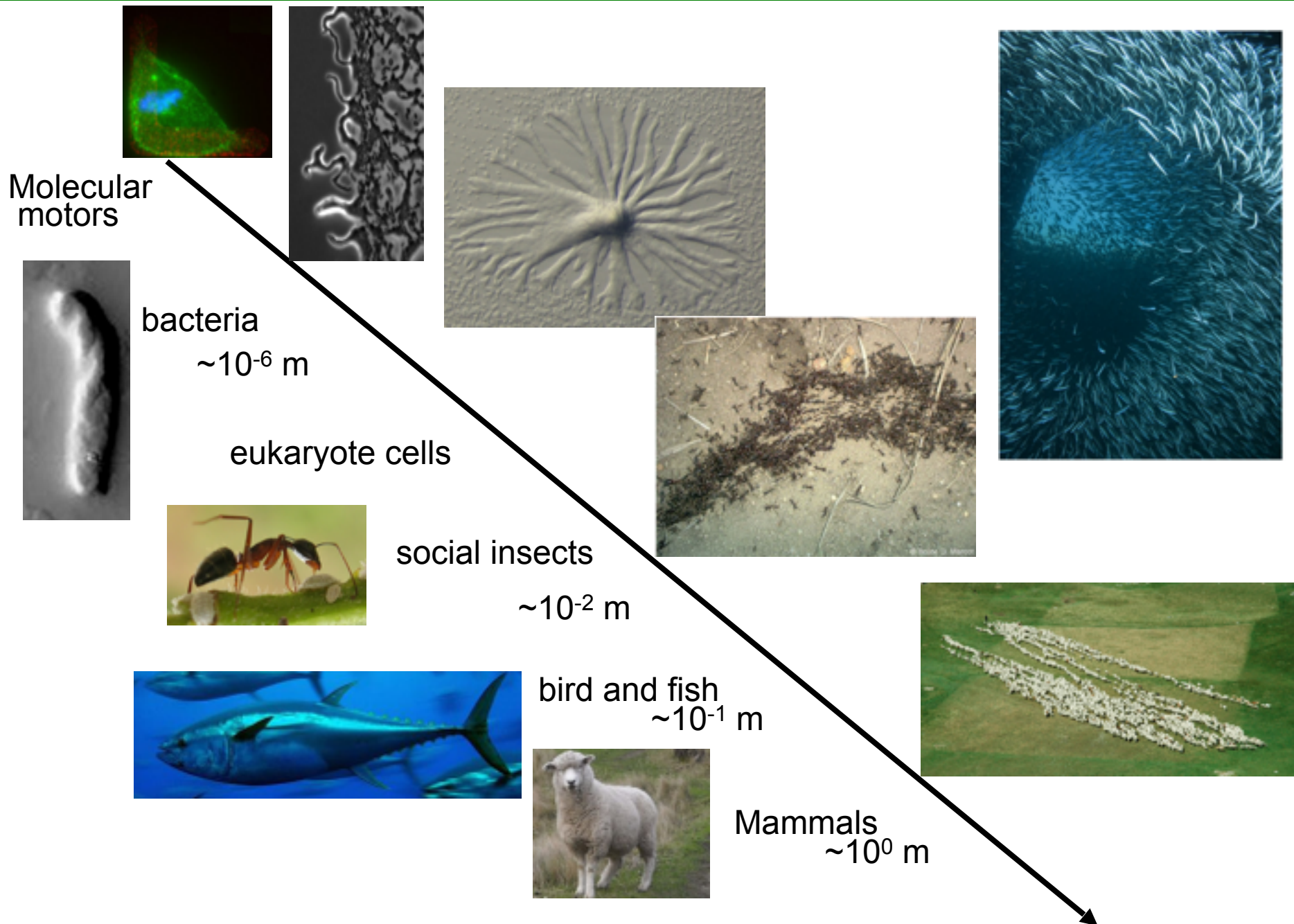
Université Nice Sophia Antipolis, Lab. Dieudonné

LPC - Clermont - Feb. 2017



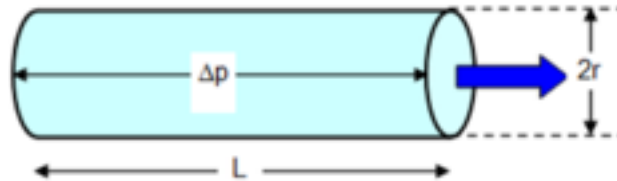
collective behavior at various scales

Peruani



spontaneous self-organized flows ?

we observe a flow if we apply a difference of pressure, or due to a difference in potential energy.



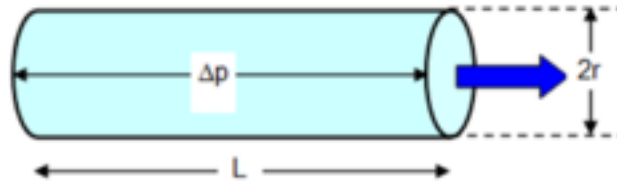
in a glass, the water will not spontaneously start moving in a given direction



Lithograph August Mayer

spontaneous self-organized flows ?

we observe a flow if we apply a difference of pressure, or due to a difference in potential energy.

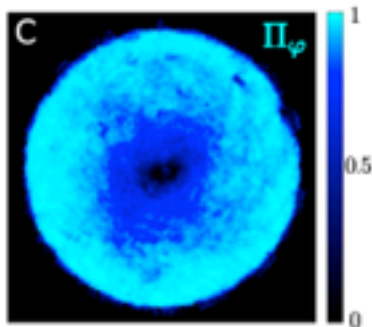
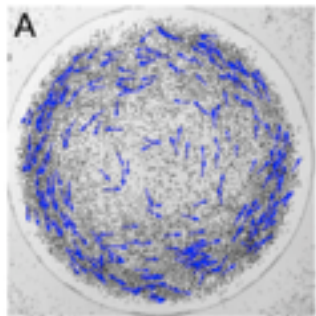


in a glass, the water will not spontaneously start moving in a given direction



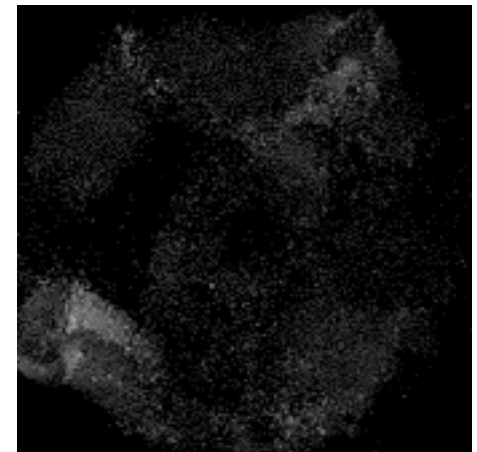
Lithograph August Mayer

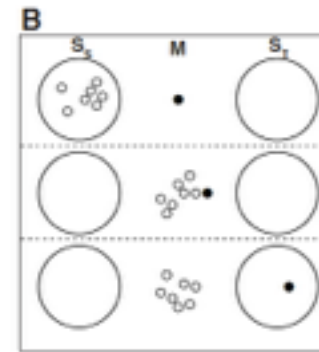
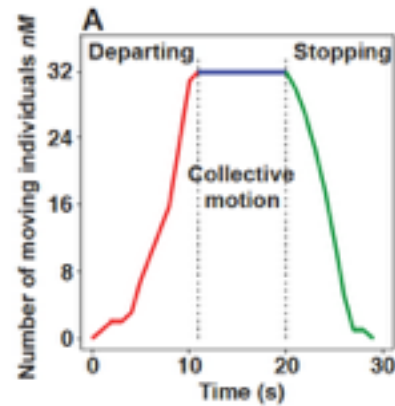
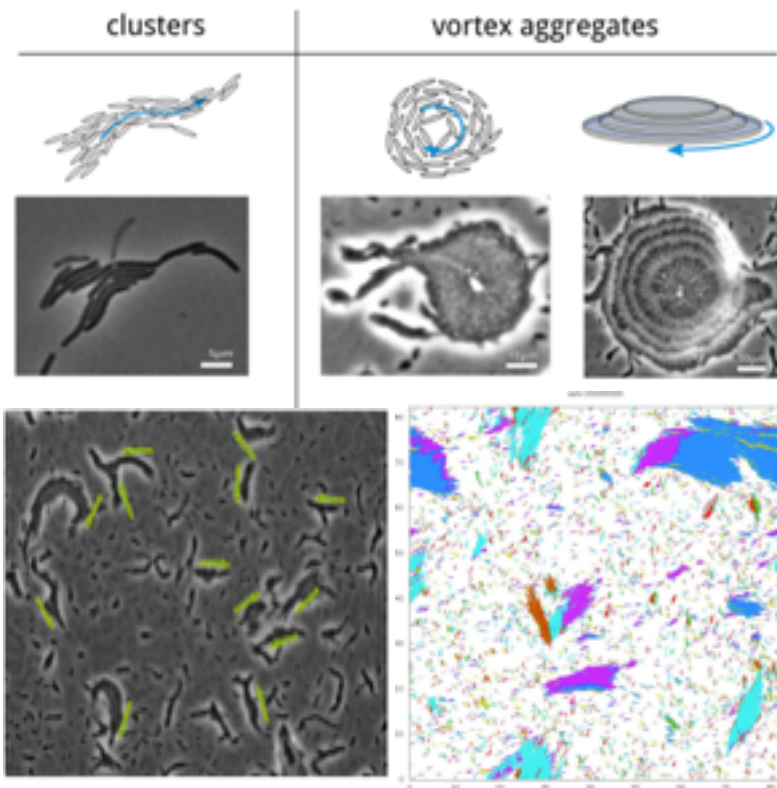
in active or living systems the situation is different...



quincke rollers in confinement

A. Bricard et al. Nature Comm. 6, 7470 (2015)



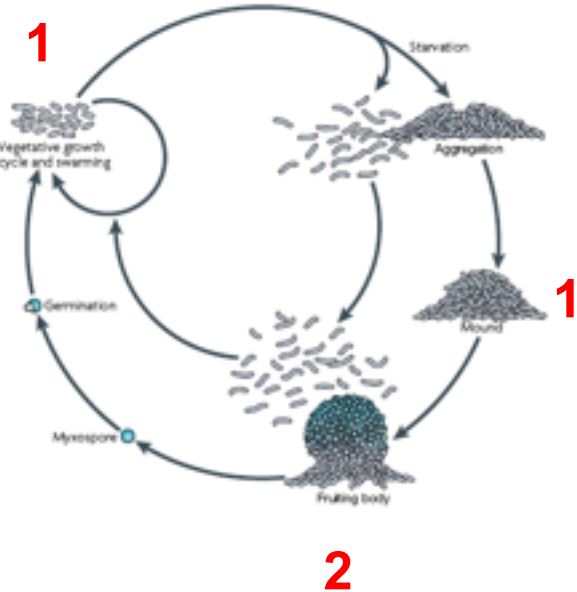


**spontaneous
behaviors/flows
in biological systems**

Peruani, Deutsch, Bär, PRE (2006)
 Peruani et al., PRL (2012)
 Weitz, Deutsch, Peruani, PRE (2015)
 Toulet, Gautrais, Bon, Peruani, PLoS ONE (2015)
 Ginelli*, Peruani*, Pillot, Chate, Theraulaz, Bon, PNAS (2015)



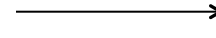
life-cycle



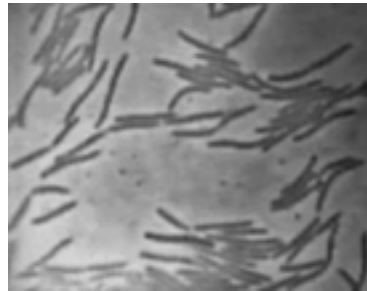
Multicellular organization in myxobacteria

Transition from individual to collective behavior
(i.e. from "unicellular to multicellular")

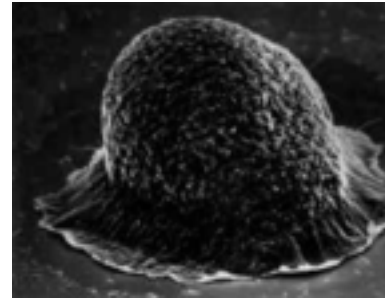
uncoordinated behavior



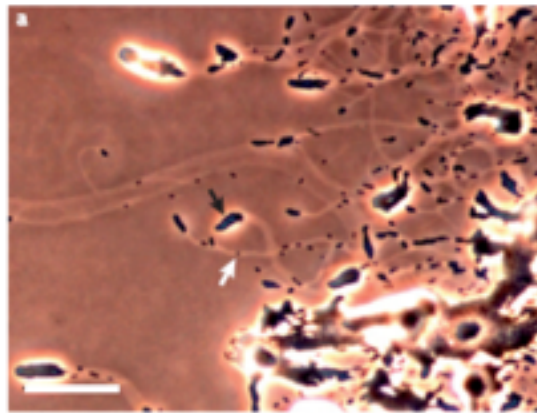
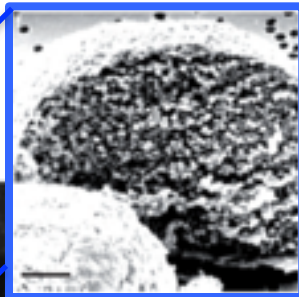
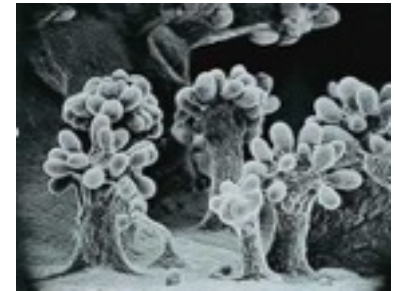
Complex collective behavior



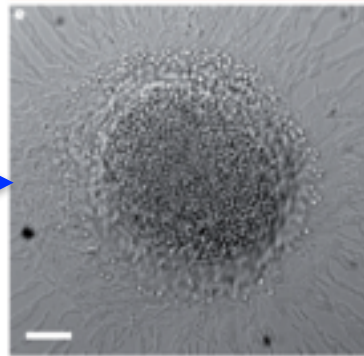
Reichenbach 1965



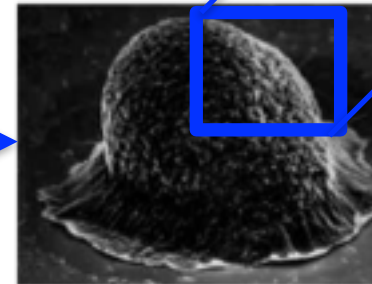
Zusman 2007



bacteria hunting in clusters
(individual phase)

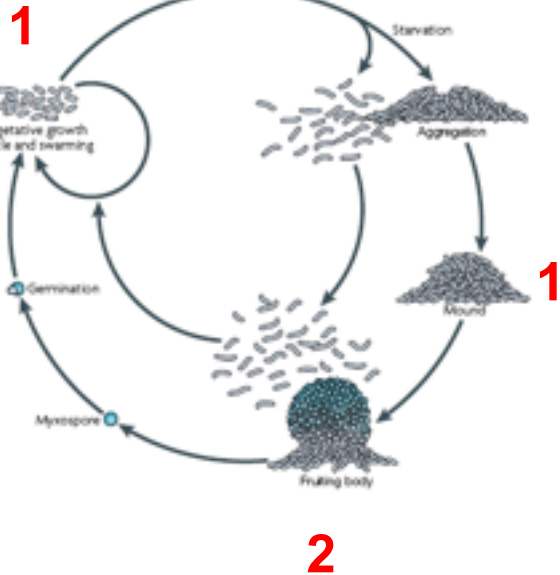


under starvation:
aggregation centers are formed



a morphogenetic process starts,
involving highly coordinated cell
movements, that culminates with the
formation of a fruiting body.

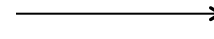
life-cycle



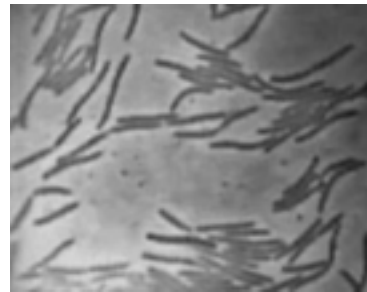
Multicellular organization in myxobacteria

Transition from individual to collective behavior
(i.e. from "unicellular to multicellular")

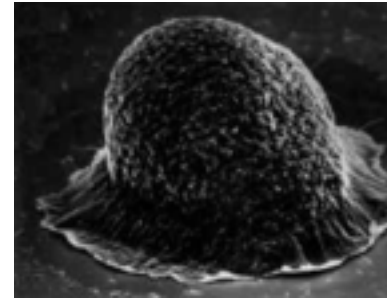
uncoordinated behavior



Complex collective behavior



Reichenbach 1965

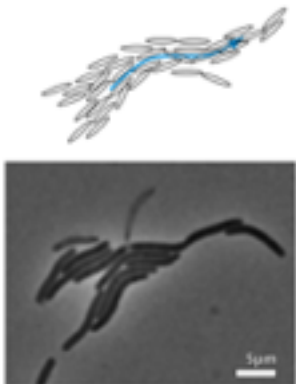


Zusman 2007

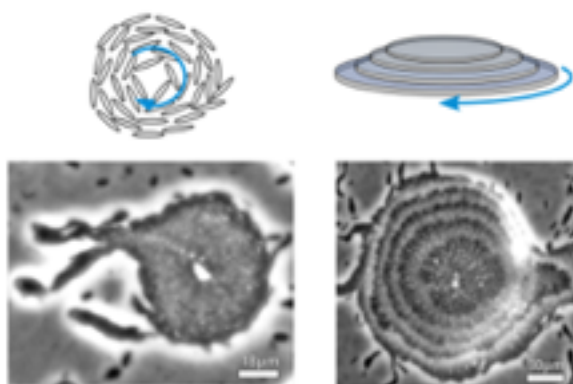


Self-organized patterns we want to explain...

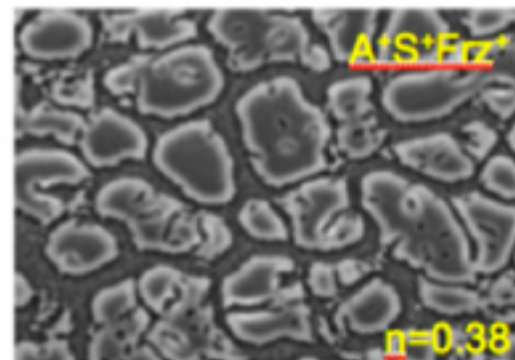
clusters



vortex aggregates



network patterns



fruiting bodies

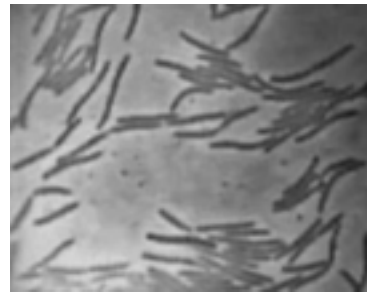
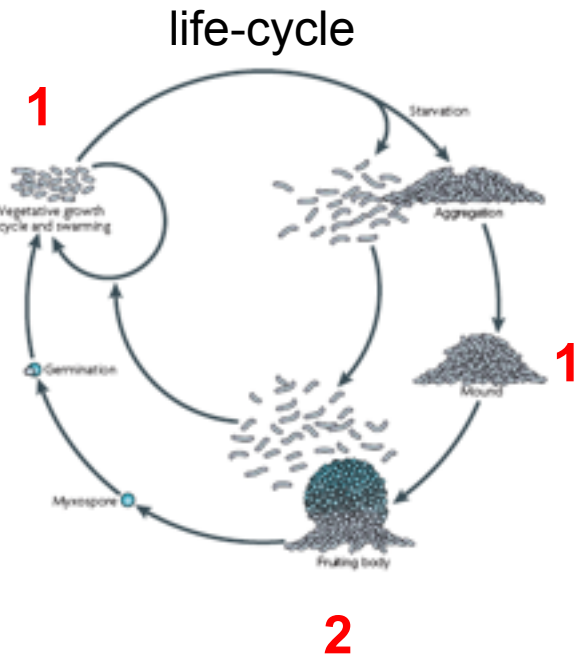


Multicellular organization in myxobacteria

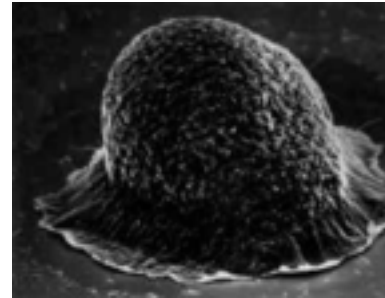
Transition from individual to collective behavior
(i.e. from "unicellular to multicellular")

uncoordinated behavior

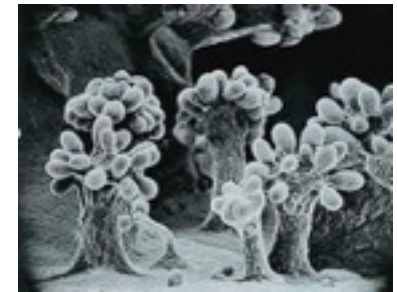
Complex collective behavior



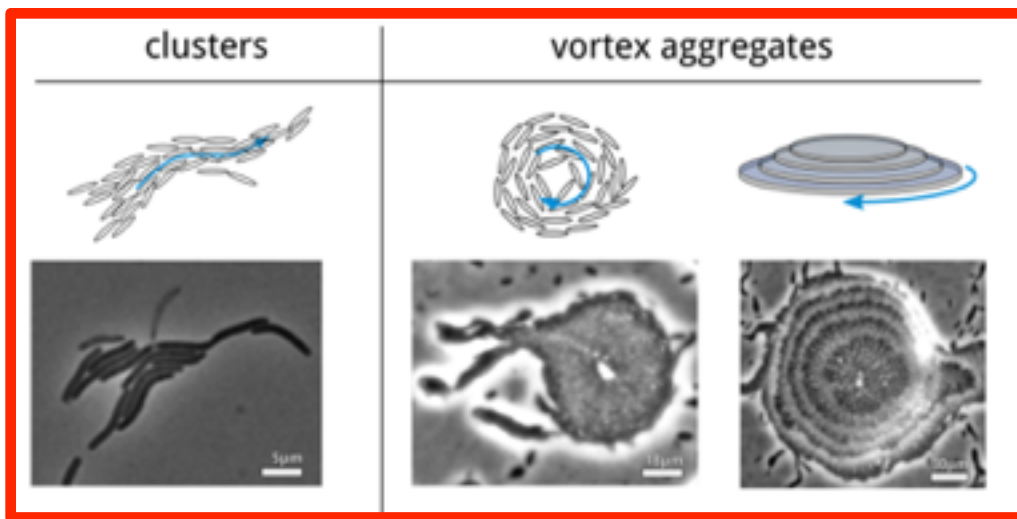
Reichenbach 1965



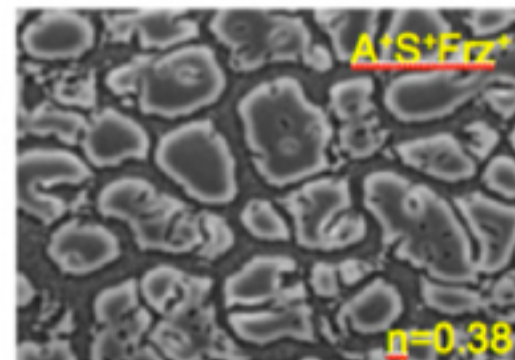
Zusman 2007



Self-organized patterns we want to explain...



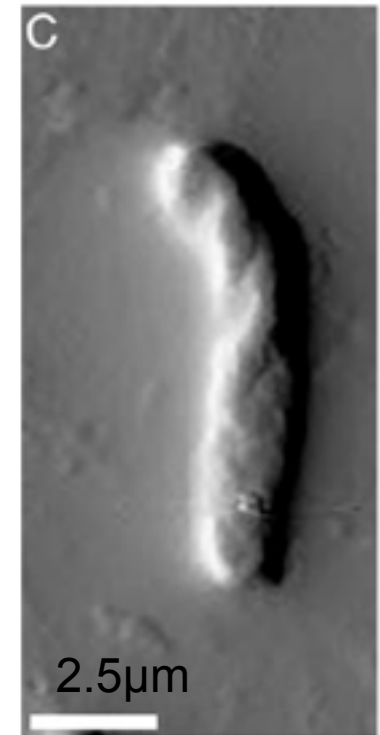
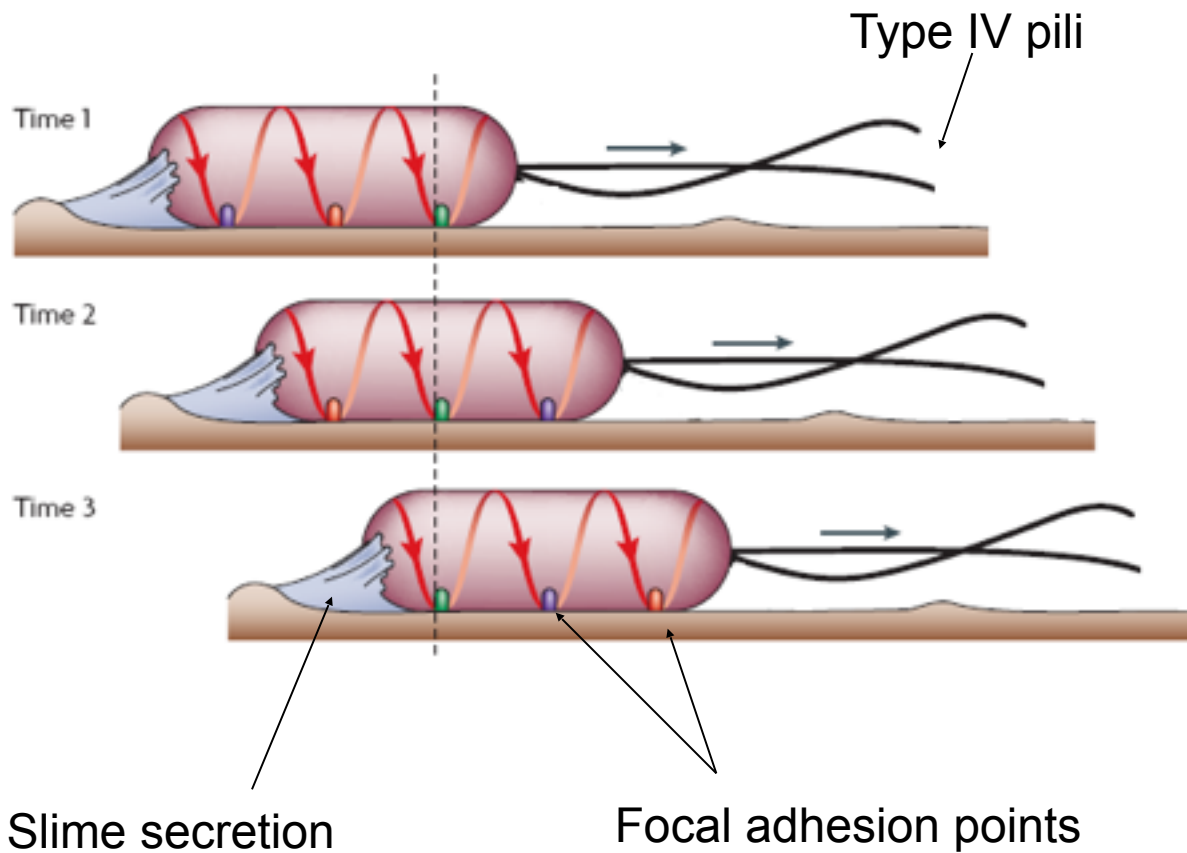
network patterns



fruiting bodies



- Motility engines in *Myxococcus xanthus*:**



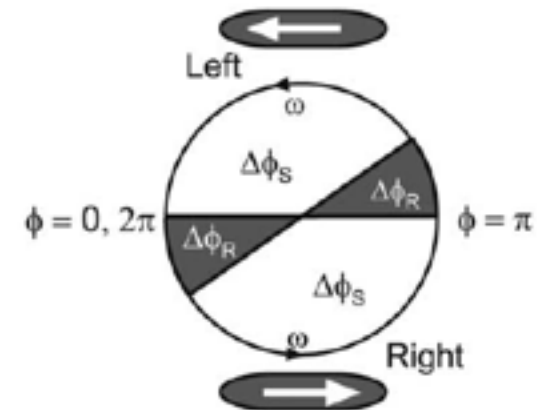
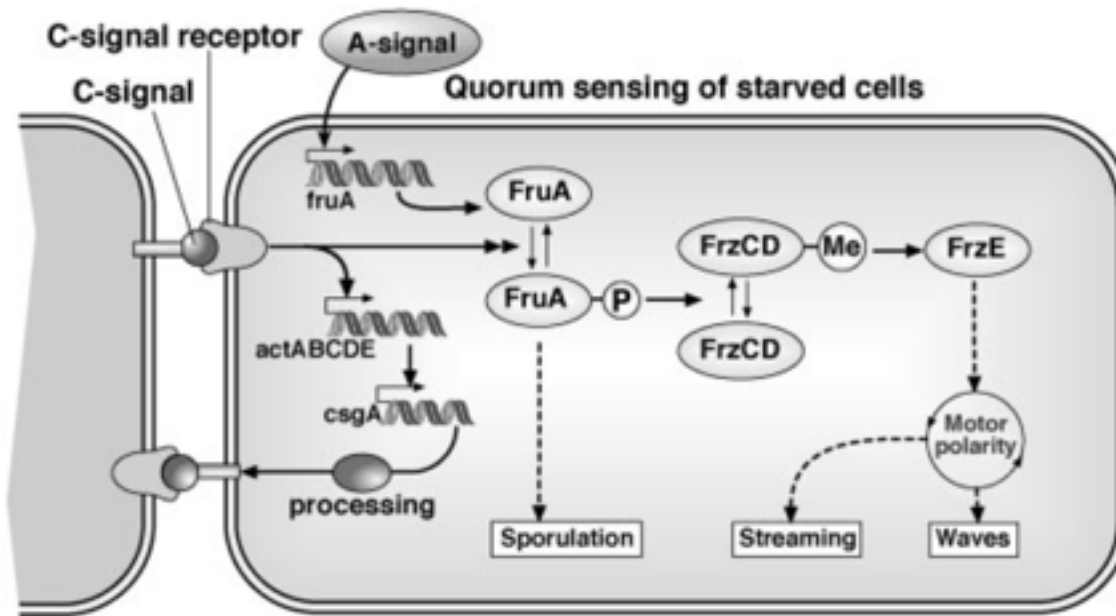
Pelling 05

Myxobacteria (speed = 0.025 to 0.1 $\mu\text{m/s}$)
Cyanobacteria (speed = 10 $\mu\text{m/s}$)
Cytophaga-Flavobacterium (speed = 2 to 4 $\mu\text{m/s}$)

- How do *M. xanthus* cells communicate?

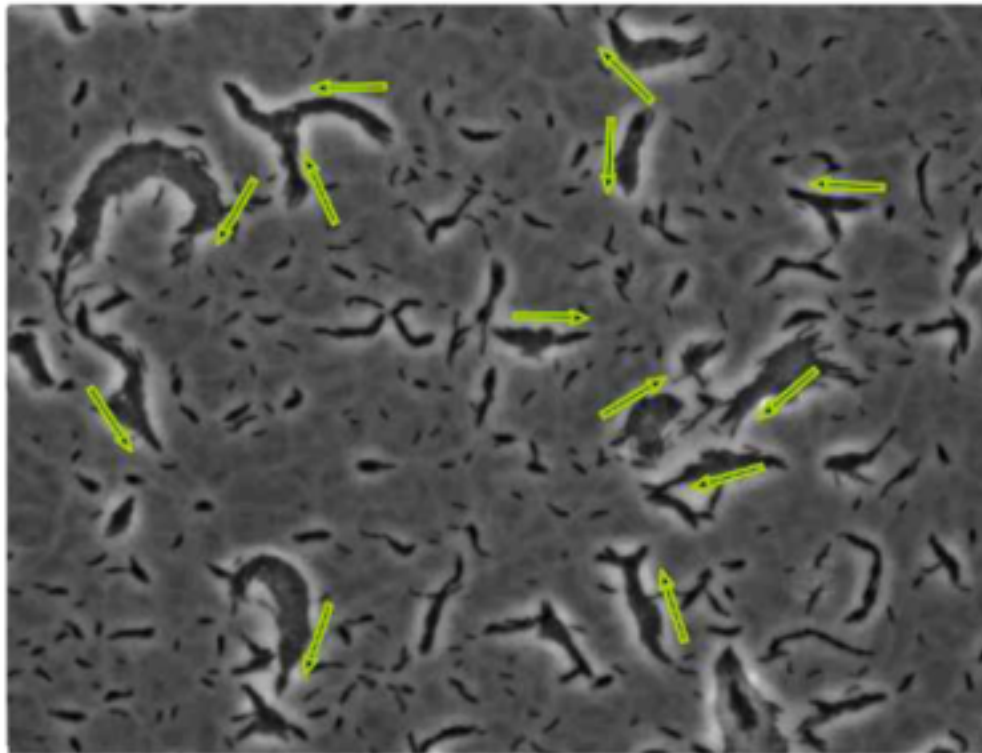
- A quorum sensing diffusive mechanism to trigger the life cycle.
- There is no evidence of a guiding chemotactic signals involved in collective motion.
- Cells exchange C-signal which controls cell reversal (it requires cell-cell contact).

- Cell reversal and C-signal:



Internal clock

Which mechanism is used by the cells to coordinate their motion?



- Is there a hidden guiding chemotactic signal?
- Can slime trail following cause these effects?
- Is there a cell-density sensing mechanism that controls cell speed causing of these effects?
- What is the minimal mechanism that can produce these effects?

**Self-propulsion of bacteria + elongated shape
= collective behavior ?**



**What macroscopic effects emerge
in a system of self-propelled liquid crystals?**

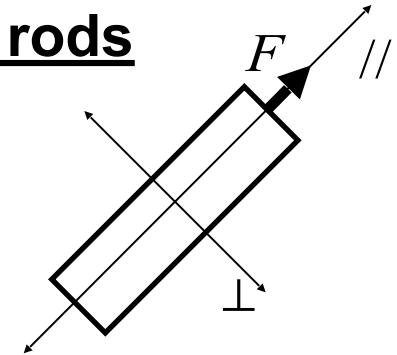


• A simple physical model: bacteria as self-propelled rods

We consider the over-damped situation in which we have:

Self-Propelling force/stress

$$\begin{aligned}\dot{\mathbf{x}}_i &= \mu [-\nabla U_i + F \mathbf{V}(\theta_i) + \boldsymbol{\sigma}_i(t)] \\ \dot{\theta}_i &= \frac{1}{\zeta_\theta} \left[-\frac{\partial U_i}{\partial \theta_i} + \xi_i(t) \right], \text{ noise}\end{aligned}$$



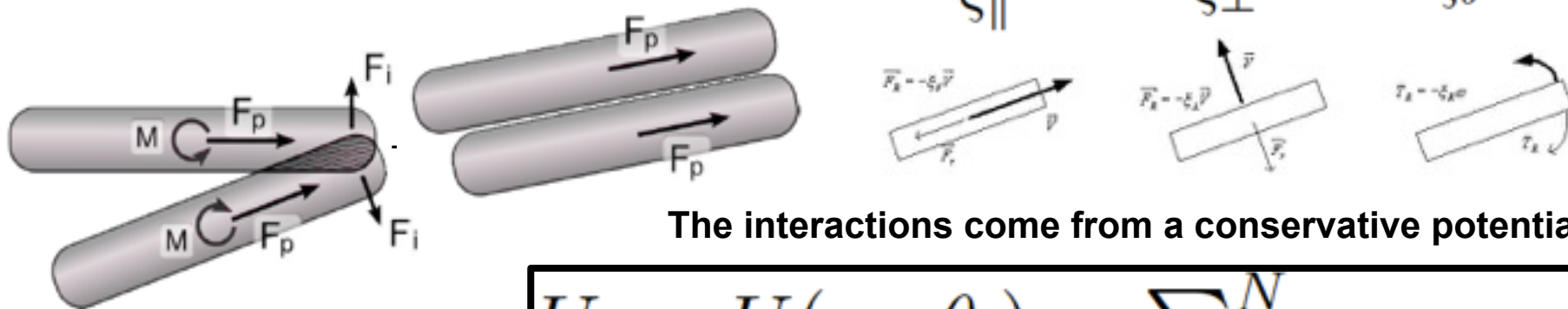
$$\mathbf{V}(\theta) \equiv (\cos(\theta), \sin(\theta))$$

$$\mathbf{V}(\theta) \cdot \mathbf{V}_\perp(\theta) = 0$$

mobility tensor

$$\mu = \zeta_{\parallel}^{-1} \mathbf{V}(\theta_i) \mathbf{V}(\theta_i) + \zeta_{\perp}^{-1} \mathbf{V}_\perp(\theta_i) \mathbf{V}_\perp(\theta_i)$$

friction coefficients



The interactions come from a conservative potential

$$U_i = U(\mathbf{x}_i, \theta_i) = \sum_{j=1; j \neq i}^N u_{i,j}$$

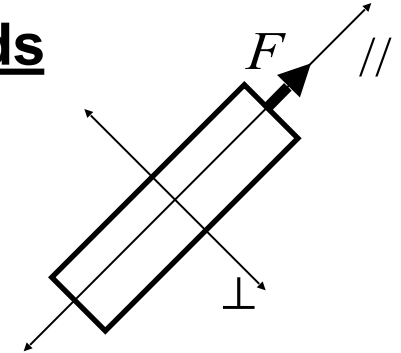
• A simple model of physical active Brownian rods

We consider the over-damped situation in which we have:

Self-Propelling force/stress

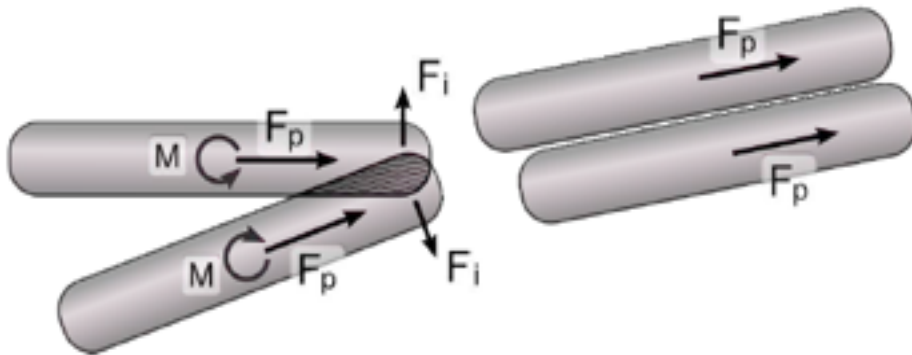
$$\begin{aligned}\dot{\mathbf{x}}_i &= \mu [-\nabla U_i + F \mathbf{V}(\theta_i) + \boldsymbol{\sigma}_i(t)] \\ \dot{\theta}_i &= \frac{1}{\zeta_\theta} \left[-\frac{\partial U_i}{\partial \theta_i} + \xi_i(t) \right], \text{ noise}\end{aligned}$$

$$\begin{aligned}\mathbf{V}(\theta) &\equiv (\cos(\theta), \sin(\theta)) \\ \mathbf{V}(\theta) \cdot \mathbf{V}_\perp(\theta) &= 0\end{aligned}$$



mobility tensor

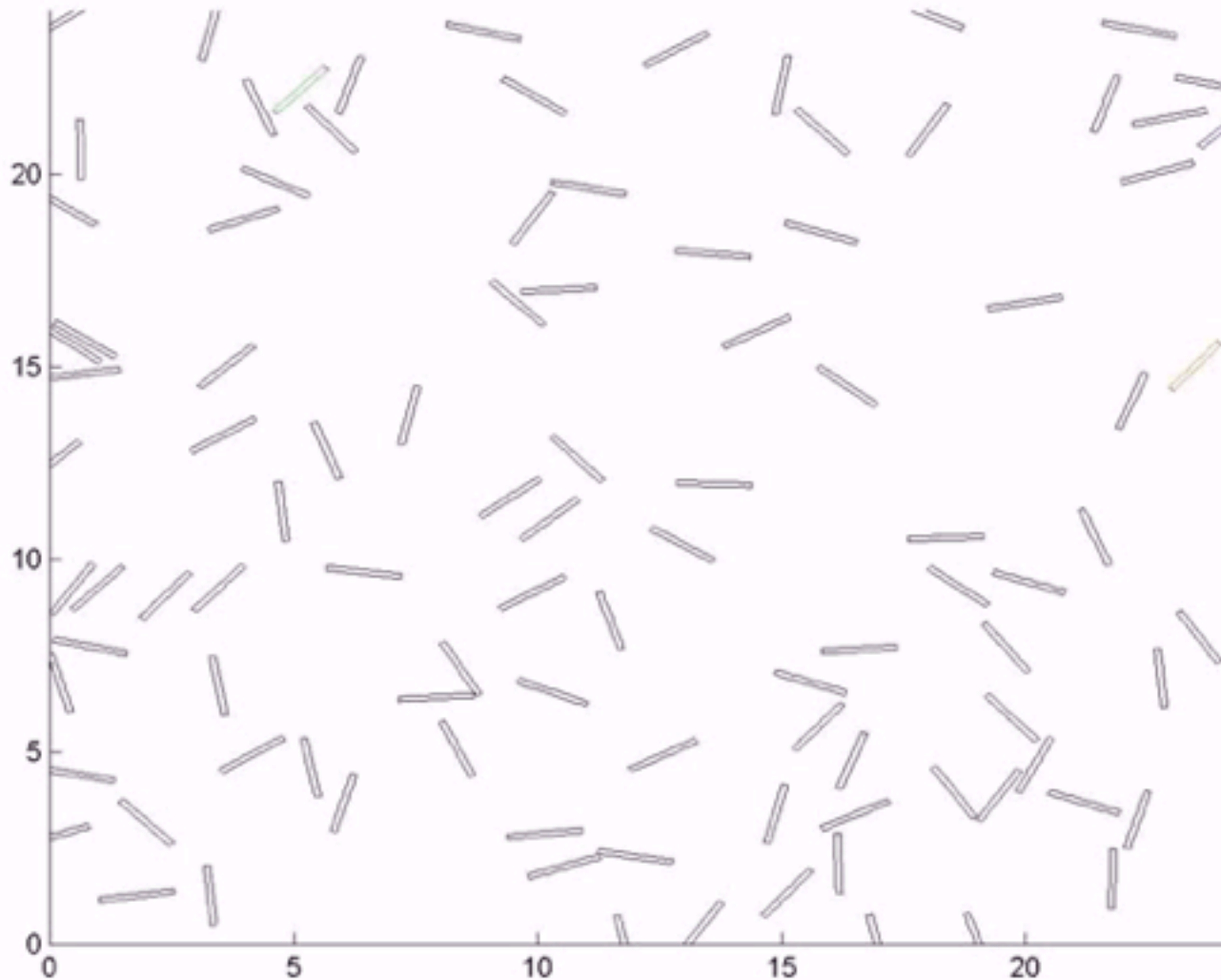
$$\mu = \zeta_\parallel^{-1} \mathbf{V}(\theta_i) \mathbf{V}(\theta_i) + \zeta_\perp^{-1} \mathbf{V}_\perp(\theta_i) \mathbf{V}_\perp(\theta_i)$$



Collective effects in myxobacteria

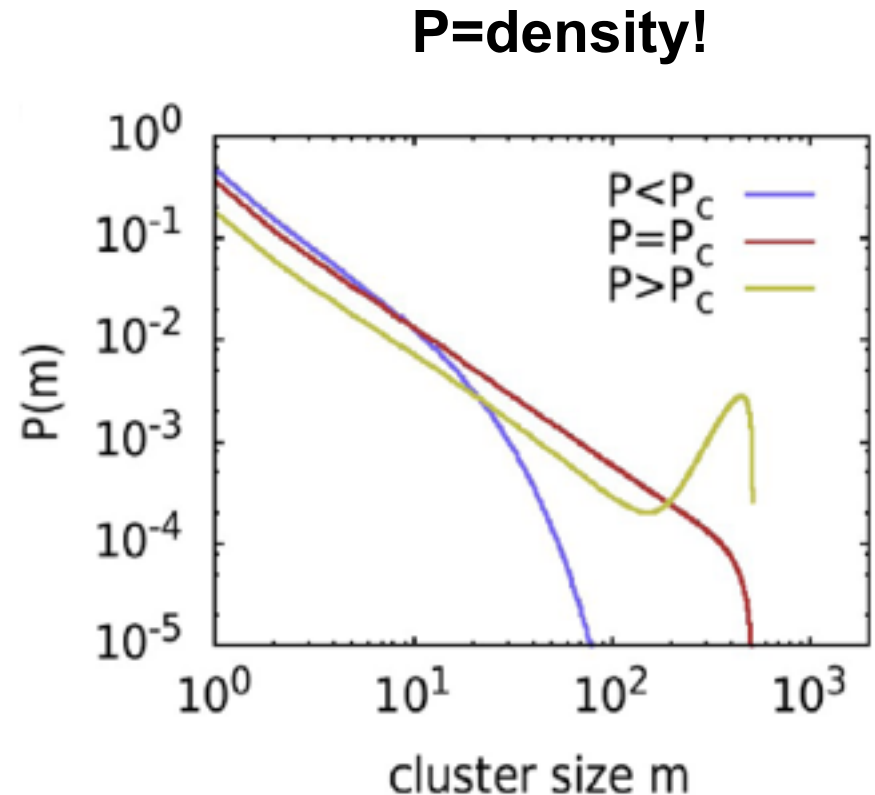
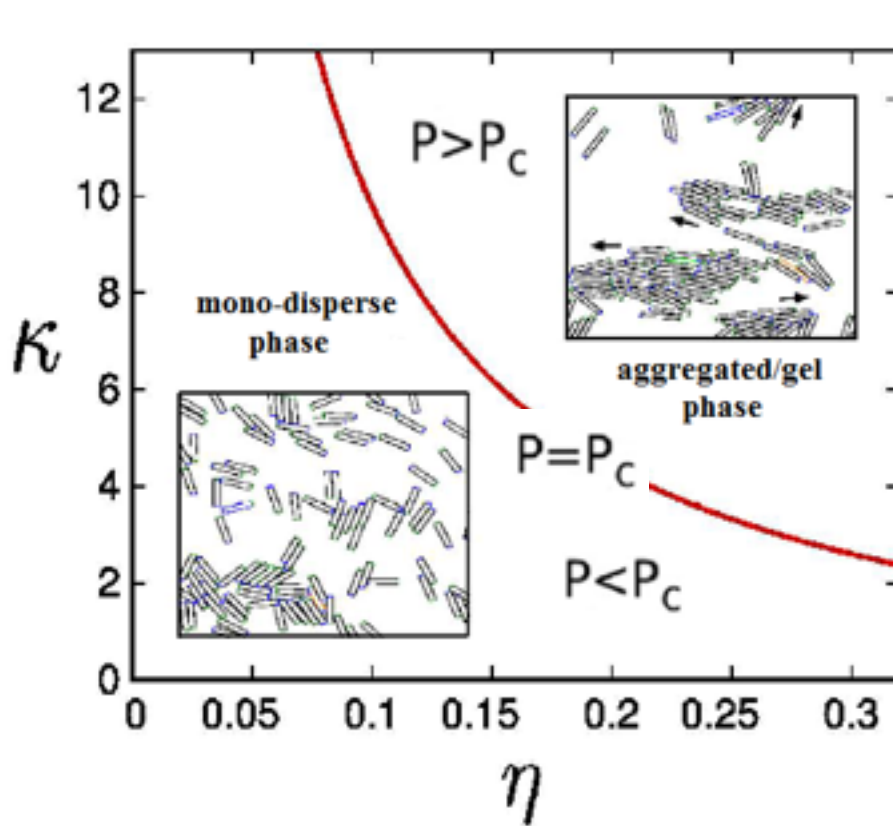
Peruani

[particles form clusters and move together without any attractive force or communication]



How to characterize the collective properties of a SP rod system?

How to characterize the collective properties of a SP rod system?



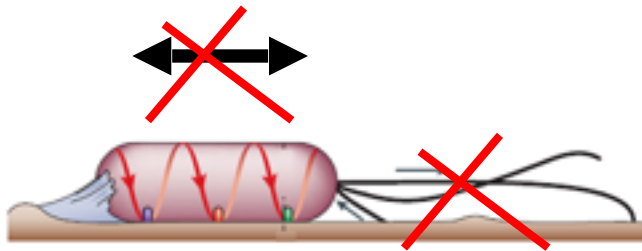
We can look at the clustering properties of the system!

The cluster size distribution (CSD) $p(m)$ conveys valuable information, and indicates that there are two phases: a dilute and an “collective” phase.

What kind of clustering properties exhibit real myxobacteria ?

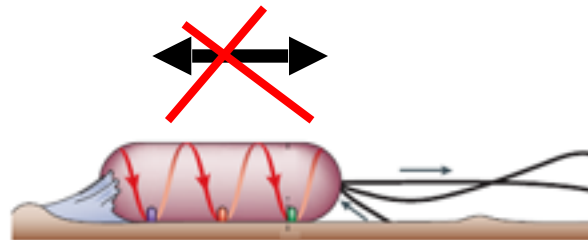
• Experiments with:

***A+S-Frz-* mutants**



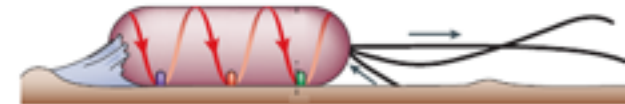
- * Cells do not reverse
- * Social motility engine – off
- * Advent. motility engine - on

***A+S+Frz-* mutants**



- * Cells do not reverse
- * Social motility engine – on
- * Advent. motility engine - on

Wild-type

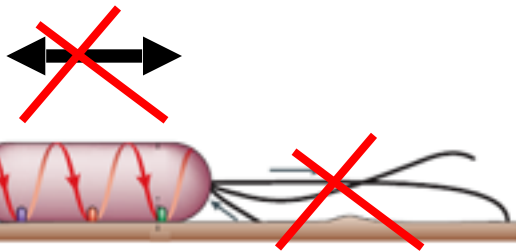


- * Cells do reverse
- * Social motility engine – on
- * Advent. motility engine - on

What kind of clustering properties exhibit real myxobacteria ?

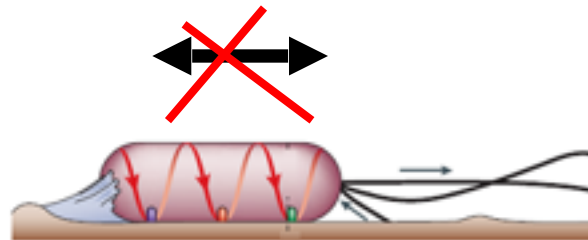
• Experiments with:

A+S-Frz- mutants



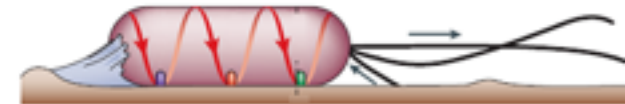
- * Cells do not reverse
- * Social motility engine – off
- * Advent. motility engine - on

A+S+Frz- mutants



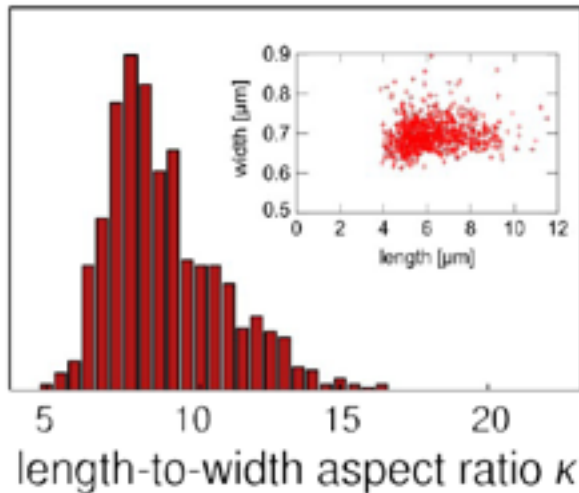
- * Cells do not reverse
- * Social motility engine – on
- * Advent. motility engine - on

Wild-type



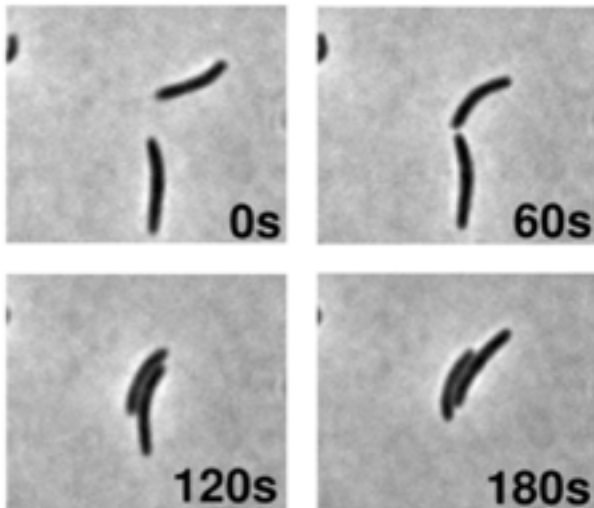
- * Cells do reverse
- * Social motility engine – on
- * Advent. motility engine - on

• Alignment and clustering (A+S-Frz- & A+S+Frz-)

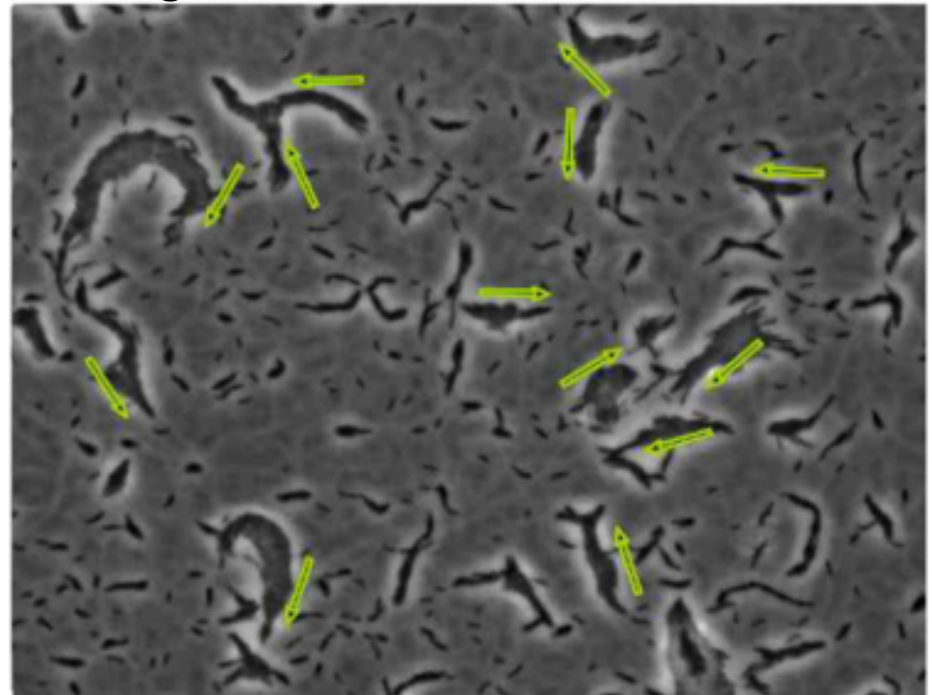


- Gliding speed = $3.10 \pm 0.35 \mu\text{m}/\text{min}$
- $W=0.7 \mu\text{m}$, $L=6.3 \mu\text{m}$, $a=4.4 \mu\text{m}$
- $\kappa=8.9 \pm 1.95$

Cell collision leads to alignment:

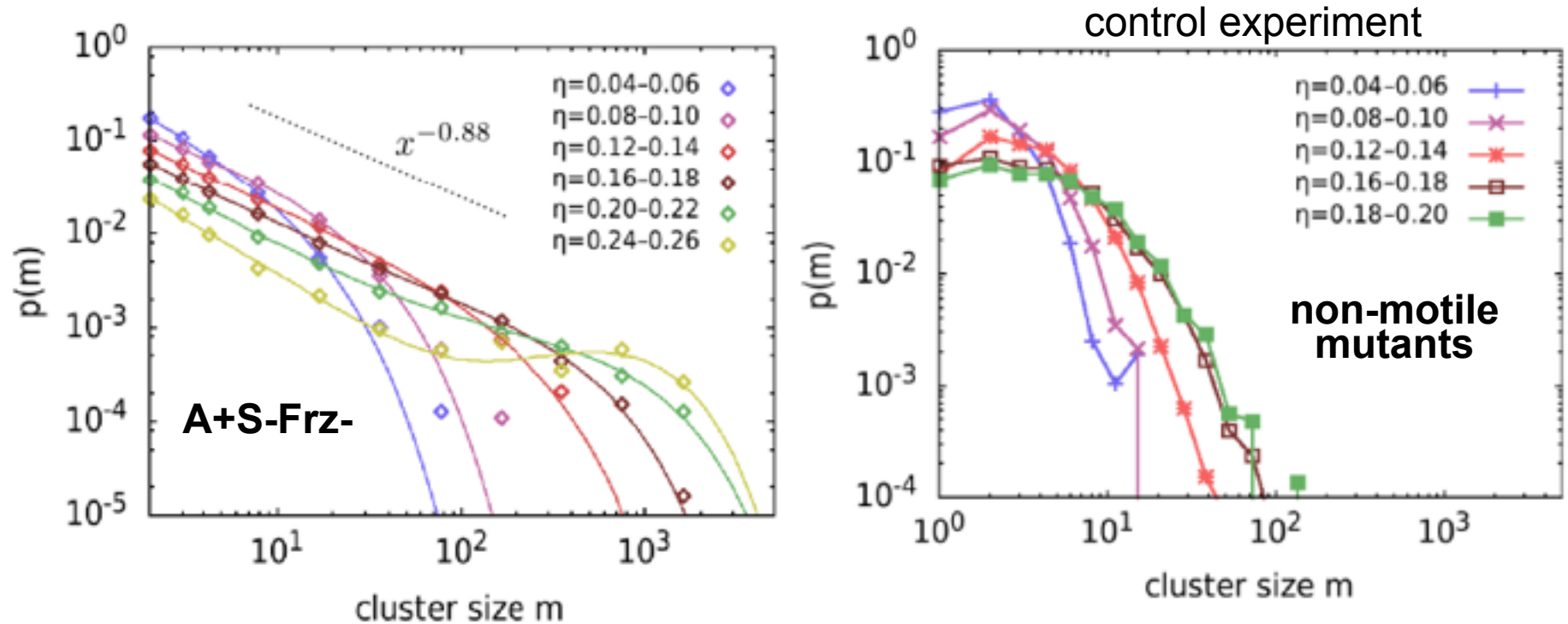


Moving clusters of bacteria are formed:



Collective effects in myxobacteria

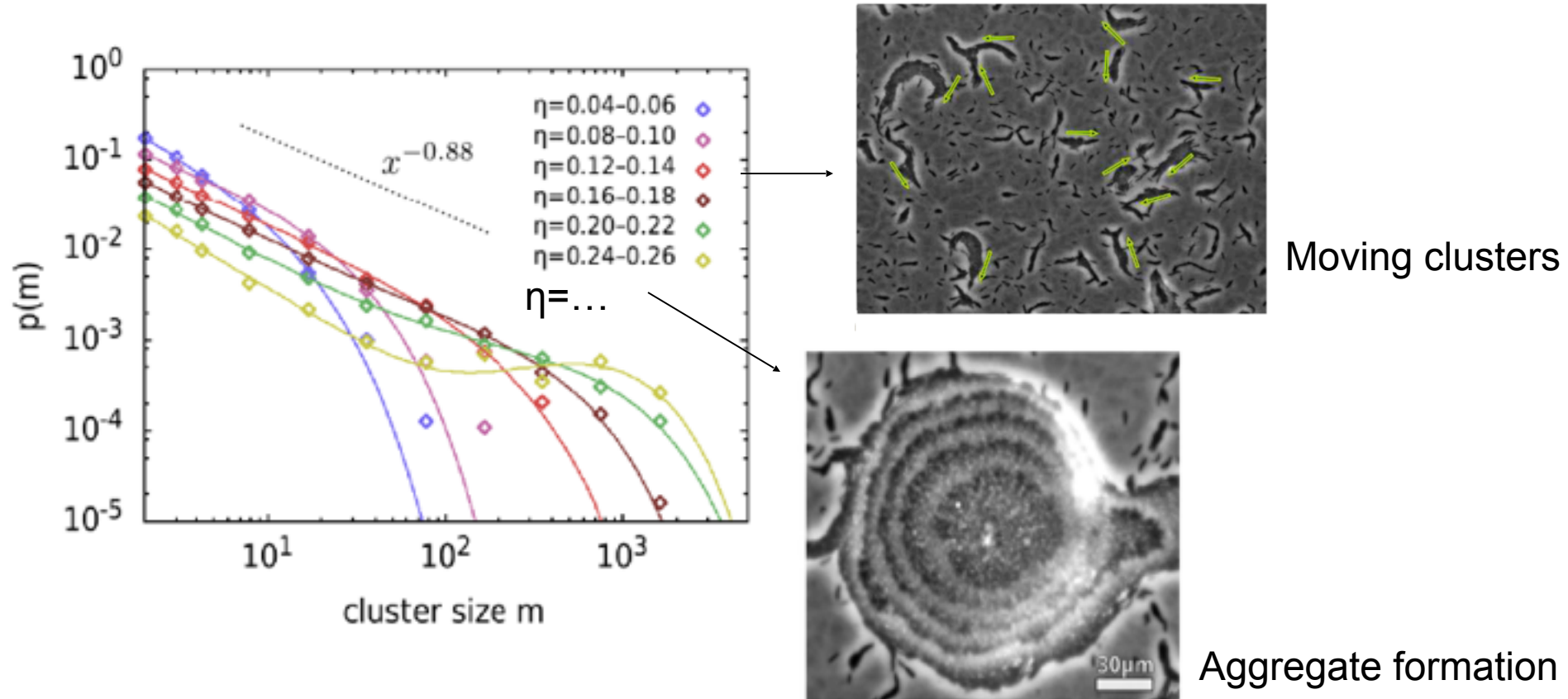
- Steady state cluster size distribution is a function of the density



The packing fraction η affects the cluster size distribution (CSD) in the way predicted by the theory, i.e., there is a change in the functional form of CSD with η .

The exponent at the critical density (0.88) is also in the range expected by the theory!

- By increasing the density: moving clusters -> aggregates !

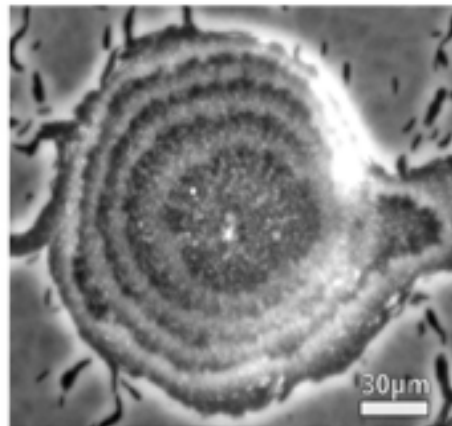


**At very high densities we observe aggregates
in A+S-Frz- & A+S+Frz- !**

How can we understand the formation of these aggregates?

Does this mean the the self-propelled rod model either failed or that is not sufficient to explain these patterns?

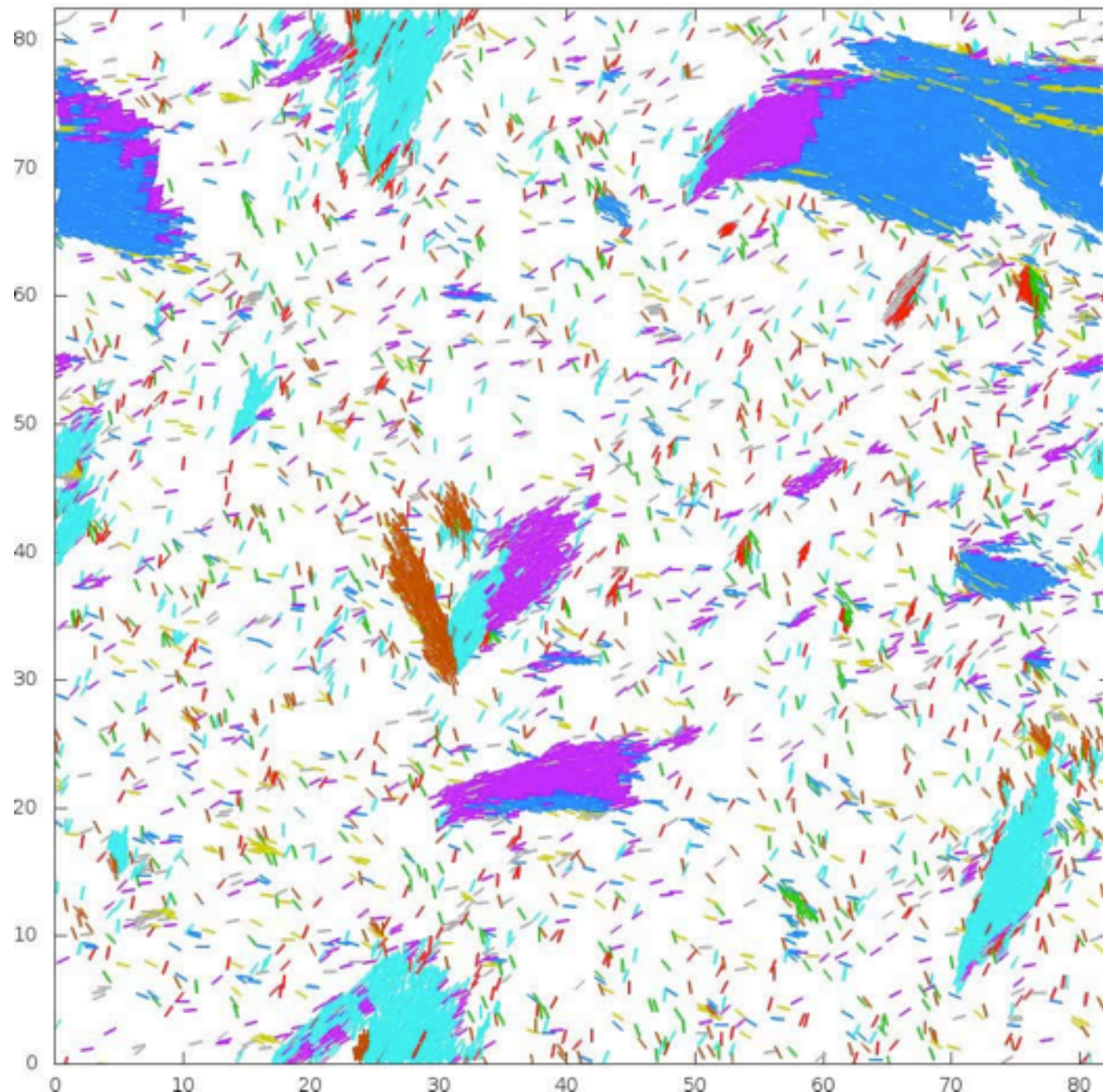
In fact, is it really true that the self-propelled rods cannot produce aggregates?



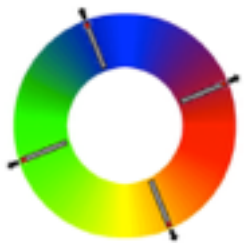
?

Aggregate formation

date 200000000

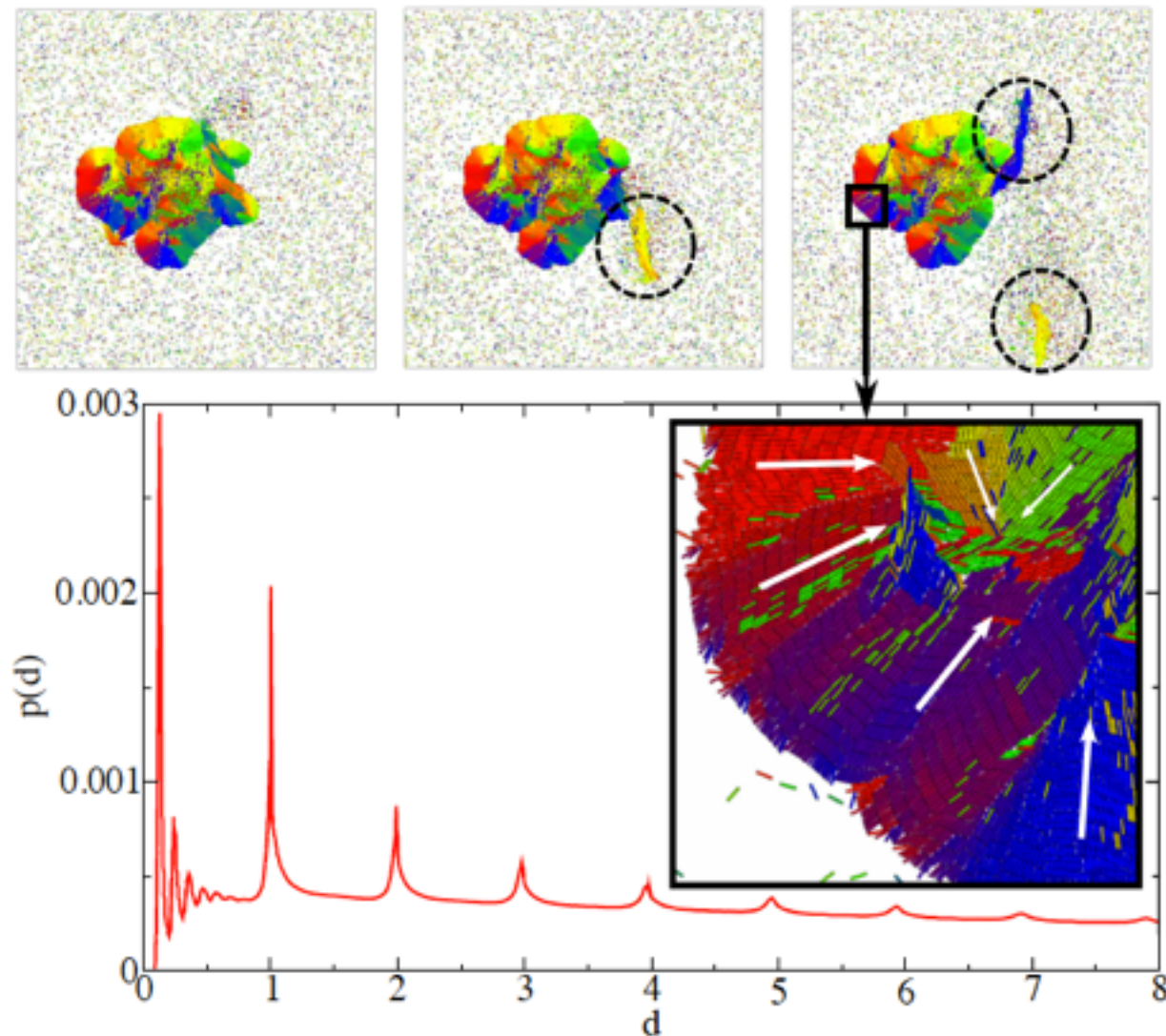


at large densities and very large system sizes...

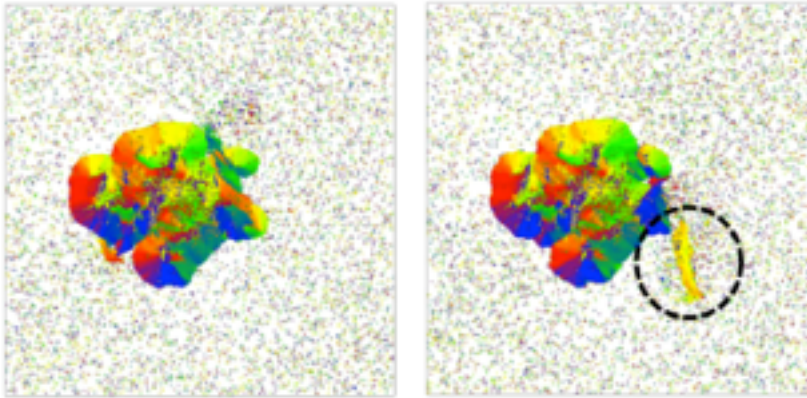


we learn that aggregates are also formed as in the experiments!

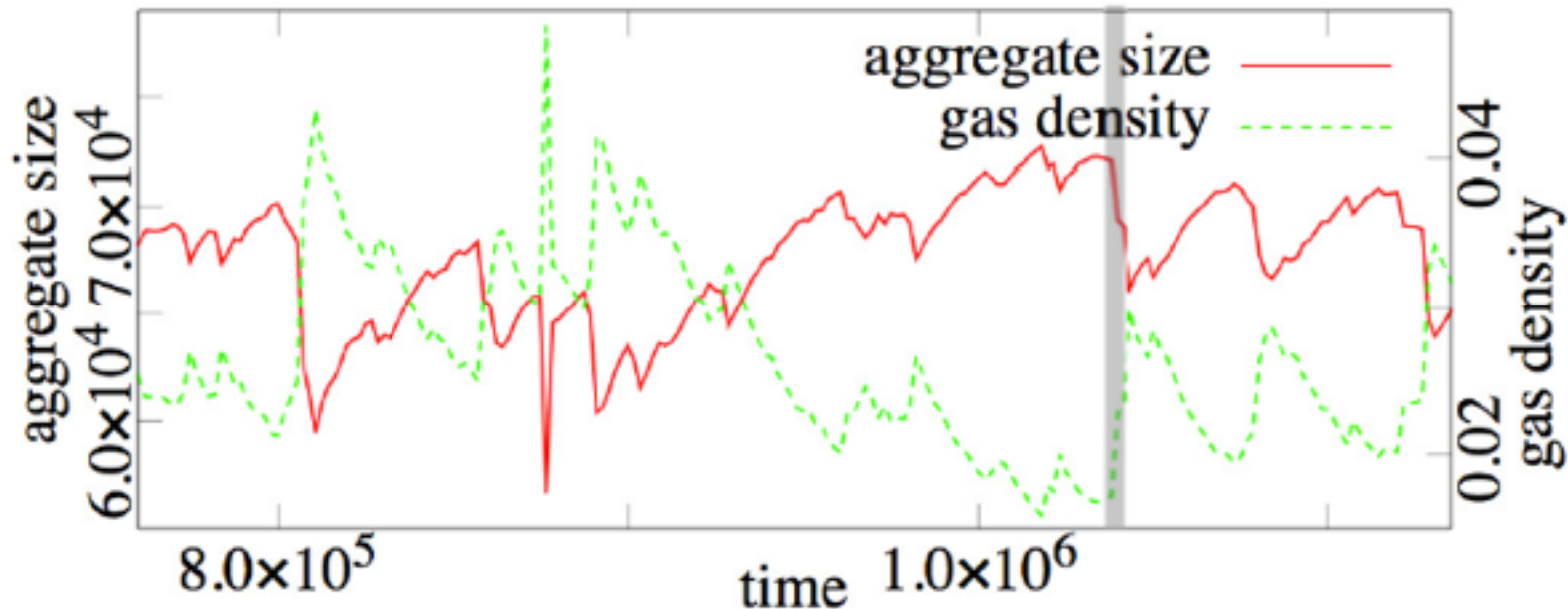
aggregates eject large polar clusters: active stresses play a key role!



aggregates eject large polar clusters: active stresses play a key role!



- a giant aggregate is formed
- multiple topological defects emerge
- the elastic energy increases
- system relaxes by ejecting a polar cluster
- the background gas density increases
- the cycle starts again



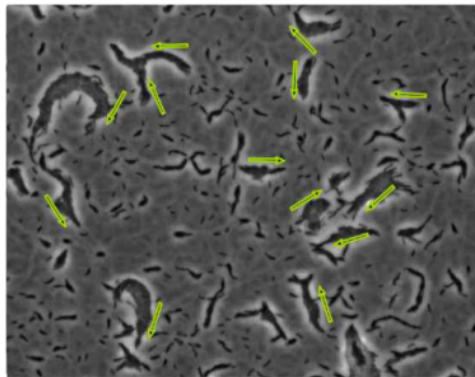
What have we learned ?

And what is the advantage of using mathematical models?

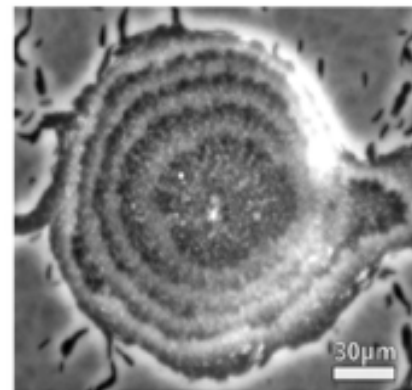
What have we learned ?

And what is the advantage of using mathematical models?

There were several empirical observations, we did not know how to explain...



formation of moving clusters



formation of aggregates

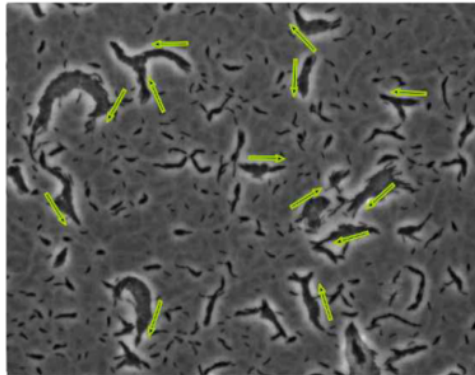
How do myxobacteria self-organize in order to produce these patterns?

(let us remember that the usual explanation, i.e. chemotaxis, seems not to be working here)

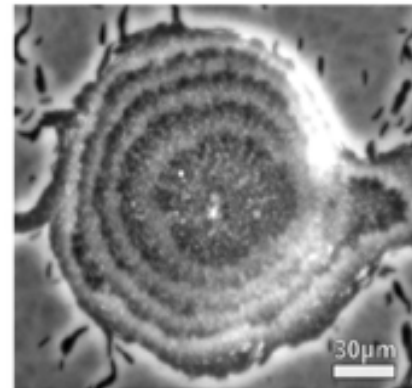
What have we learned ?

And what is the advantage of using mathematical models?

There were several empirical observations that we did not know how to explain...



formation of moving clusters



formation of aggregates

How do myxobacteria self-organize in order to produce these patterns?

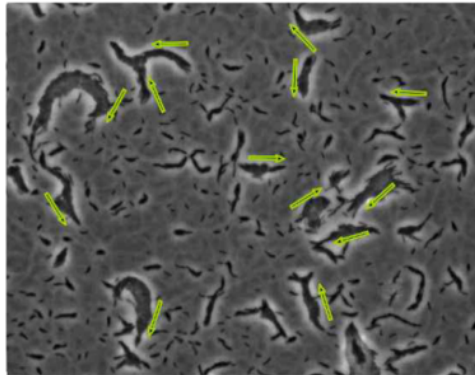
The mathematical models, together with the simulations, allow us to test various hypotheses!

We provided a proof of principle for the proposed mechanisms.

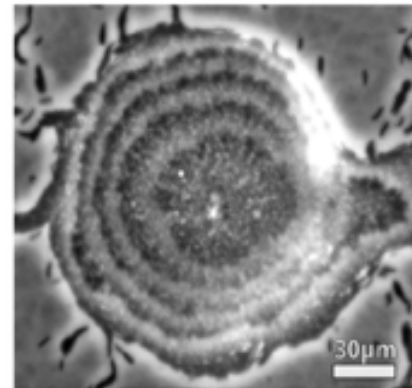
What have we learned ?

And what is the advantage of using mathematical models?

There were several empirical observations that we did not know how to explain...



formation of moving clusters



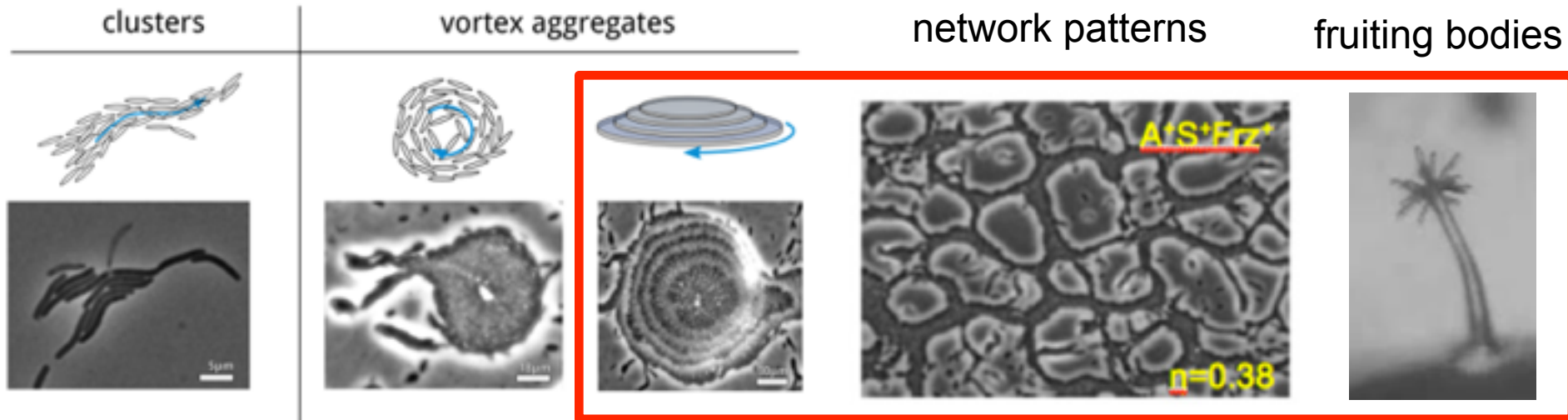
formation of aggregates

So, what have we learned?

We learned that the combined effect of being self-propelled + having an elongated cell shape is enough to produce moving cluster and aggregates!

(and we have seen that these patterns produce with the mathematical model are quantitatively consistent with the empirical observations)

What is next?

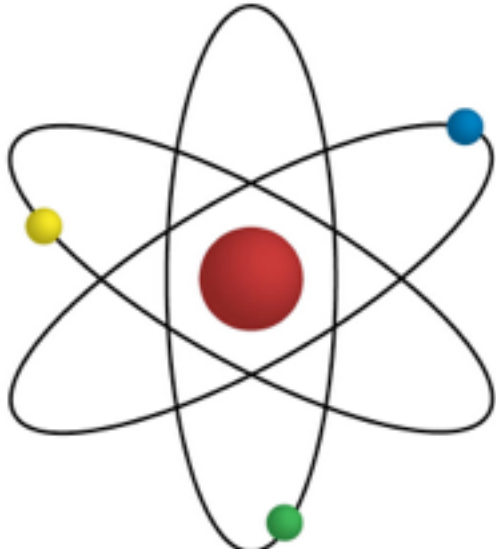




when we look at animal groups, we aim at:

1. Identify the underlying behavioral rules
2. Characterize the emerging macroscopic patterns

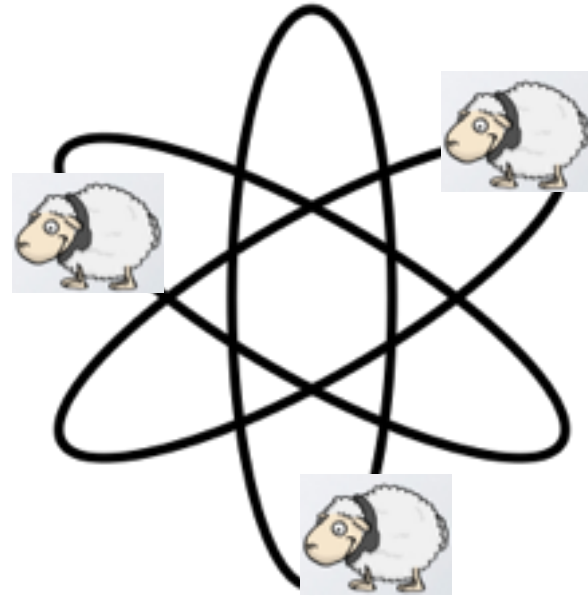




object of study: atom



to study its properties, we perturb it!



object of study: group of sheep



here, we will apply the same logic!

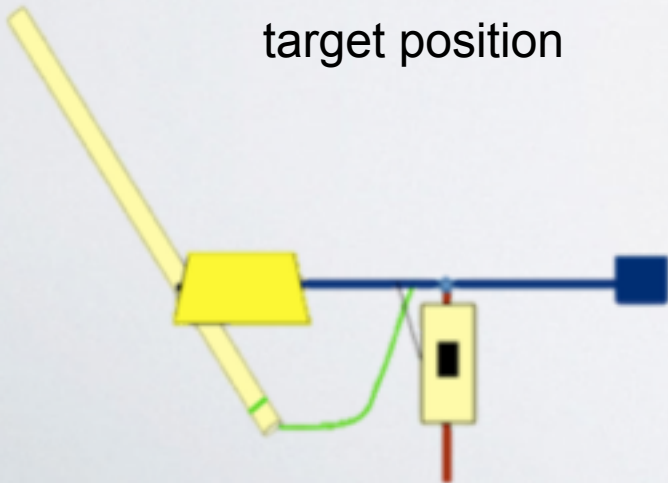


A simple, well-controlled experiment...

vibrating collar



target position



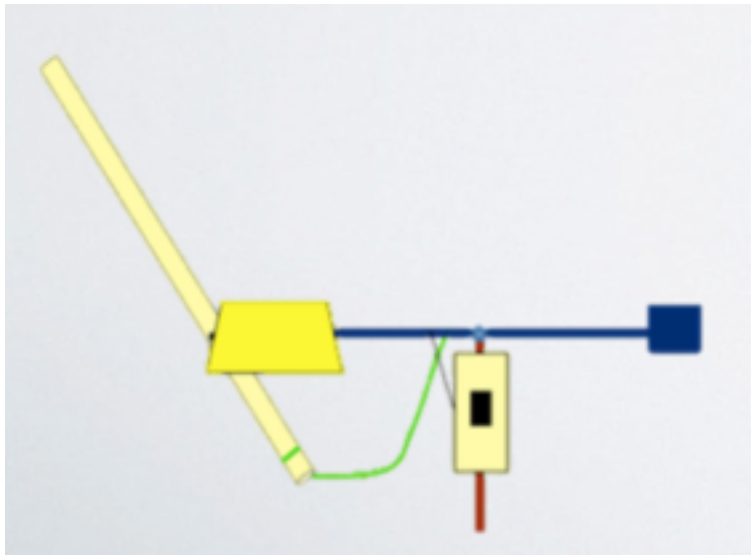
A simple, well-controlled experiment...



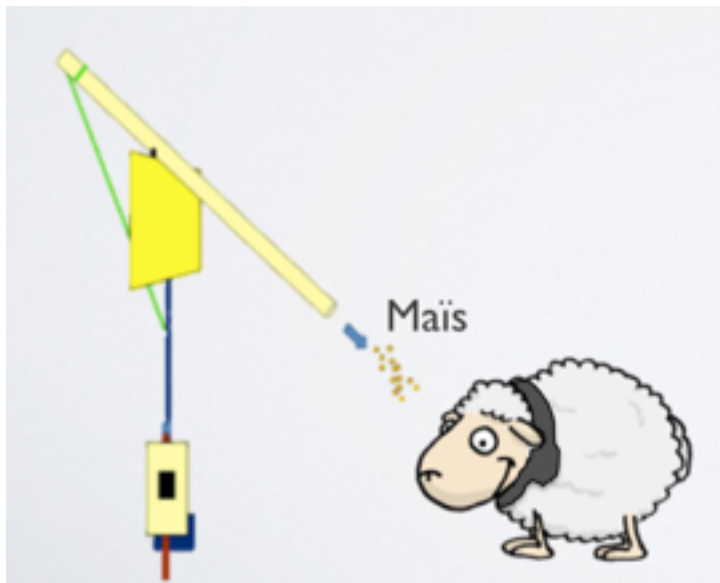
upon activation of the collar...



the trained individual
moves toward the
target position



A simple, well-controlled experiment...

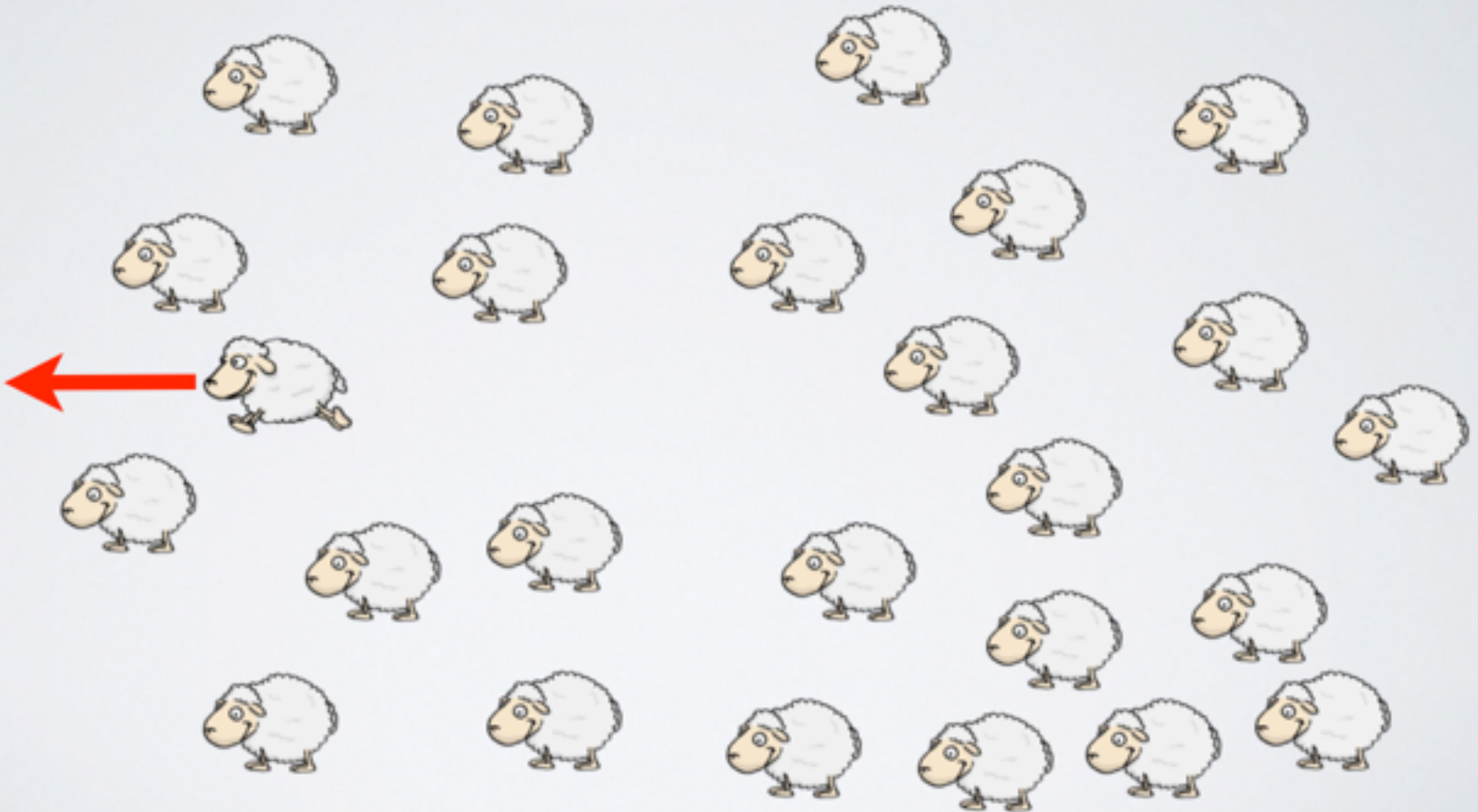


[Toulet, Gautrais, Bon, Peruani, PLoS ONE (2015)]

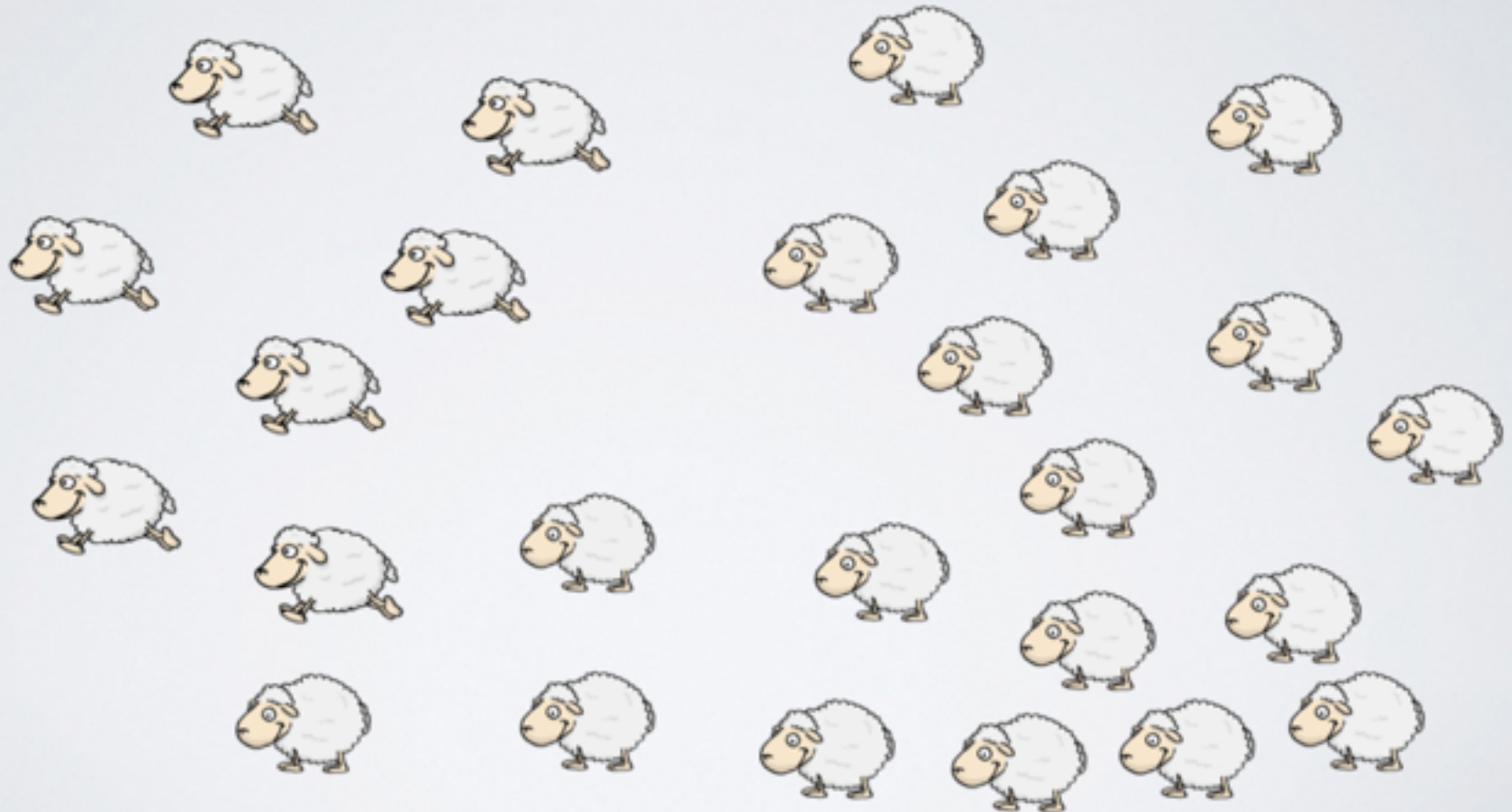
A simple, well-controlled experiment...



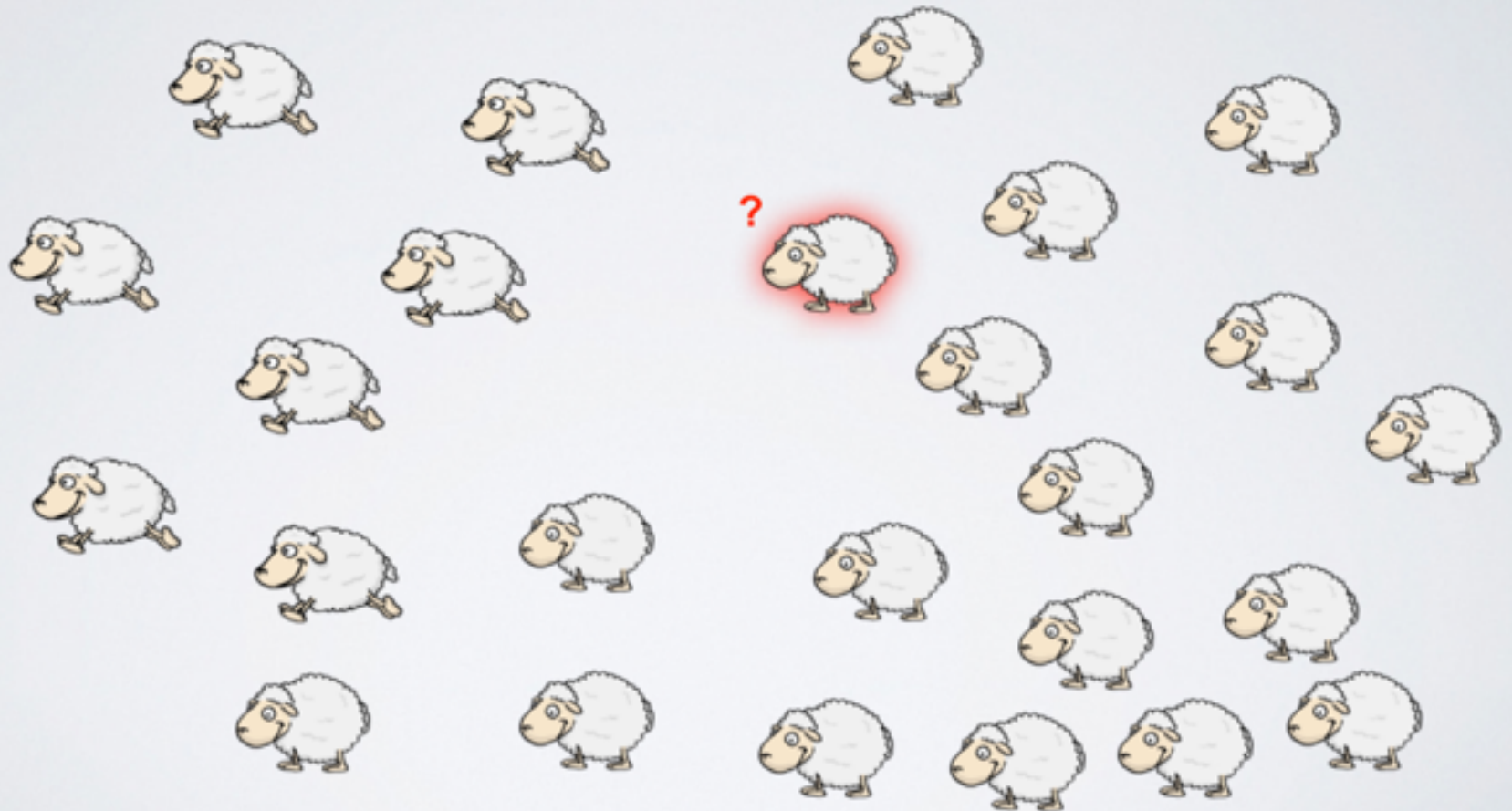
A simple, well-controlled experiment...



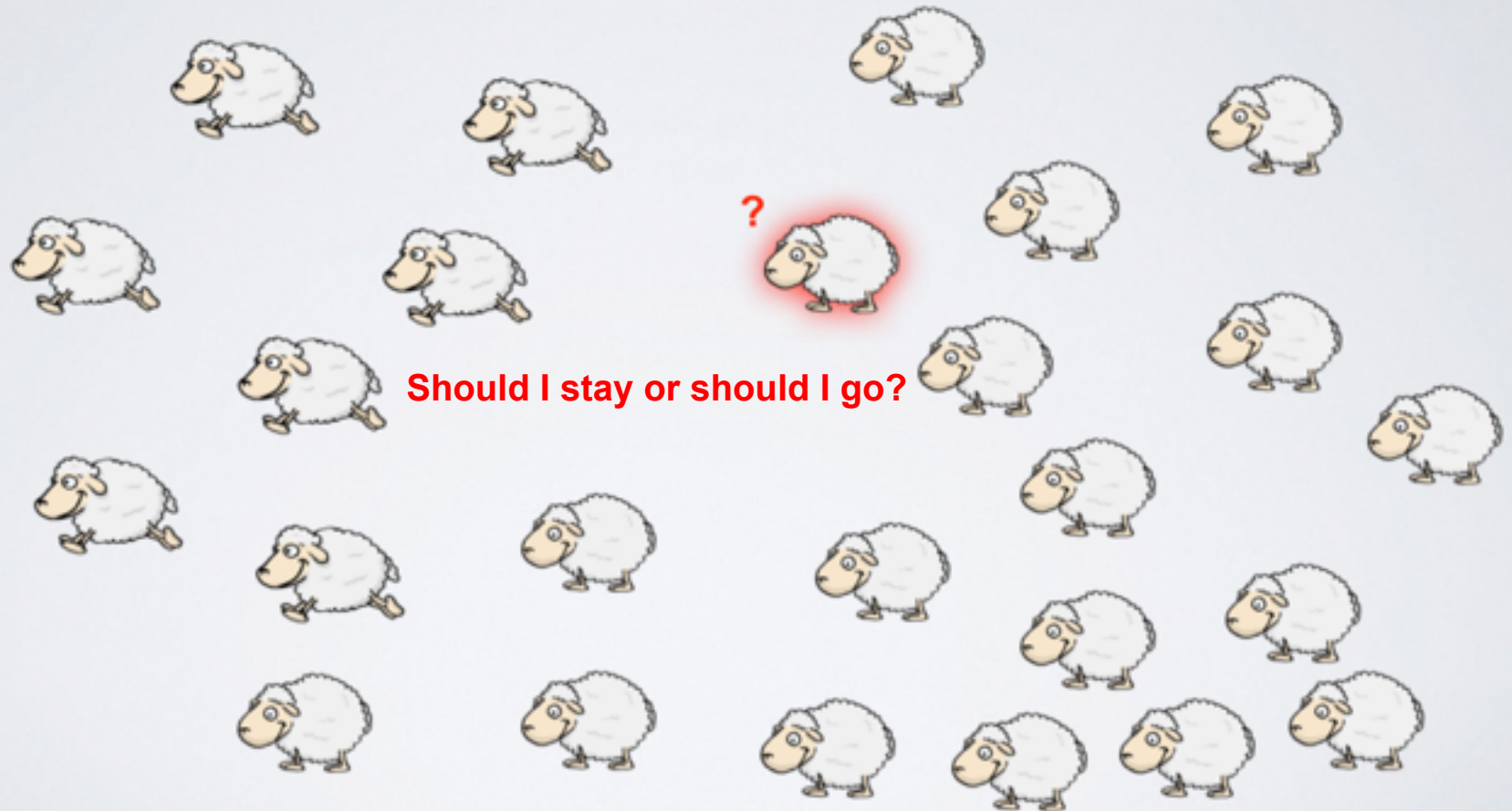
A simple, well-controlled experiment...




A simple, well-controlled experiment...



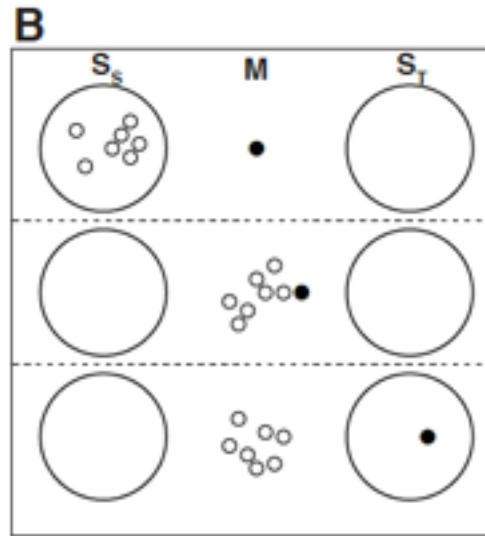
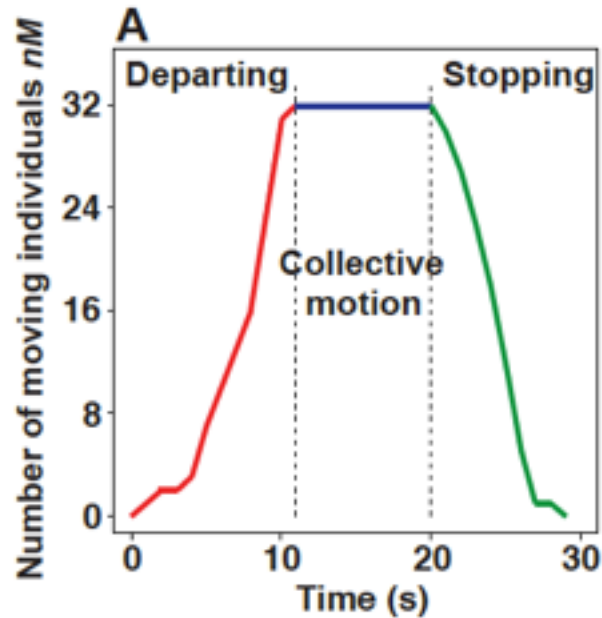
A simple, well-controlled experiment...



An aerial photograph of a large green field. A long, dark green net is stretched across the field, forming a large, irregular loop. Inside the loop, a group of sheep is gathered. In the background, there are several tall, dark evergreen trees and a few smaller buildings. The sky is overcast.

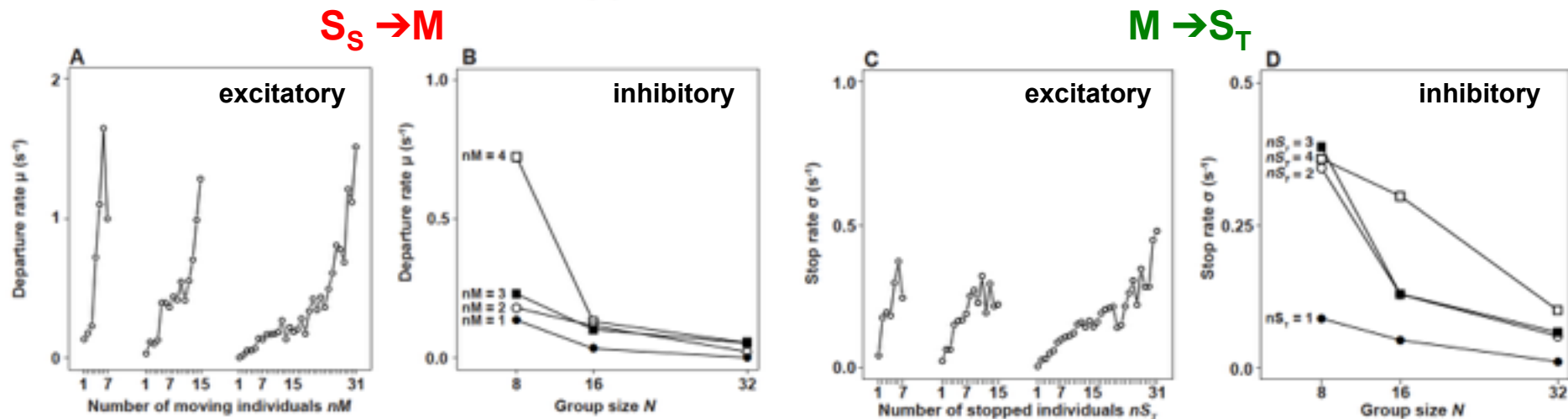
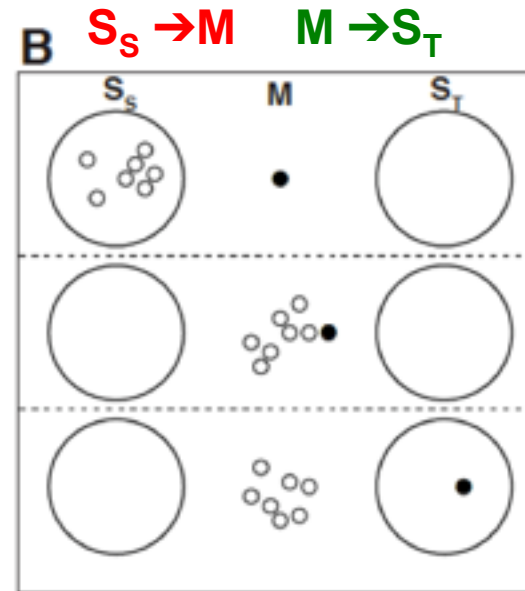
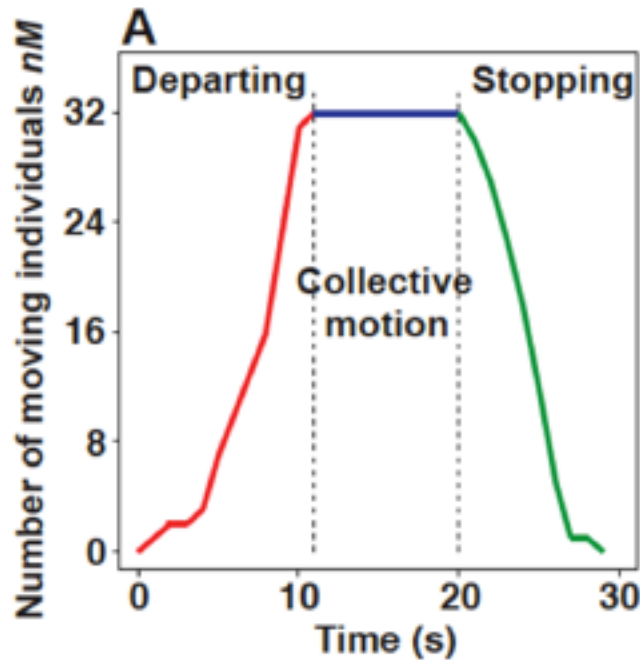
Clip 1:
**The initiator provokes
collective motion**

The temporal dynamics...



N-1 naïve indiv.
1 trained indiv.
N=8, 16, 32

The temporal dynamics...



The temporal dynamics...

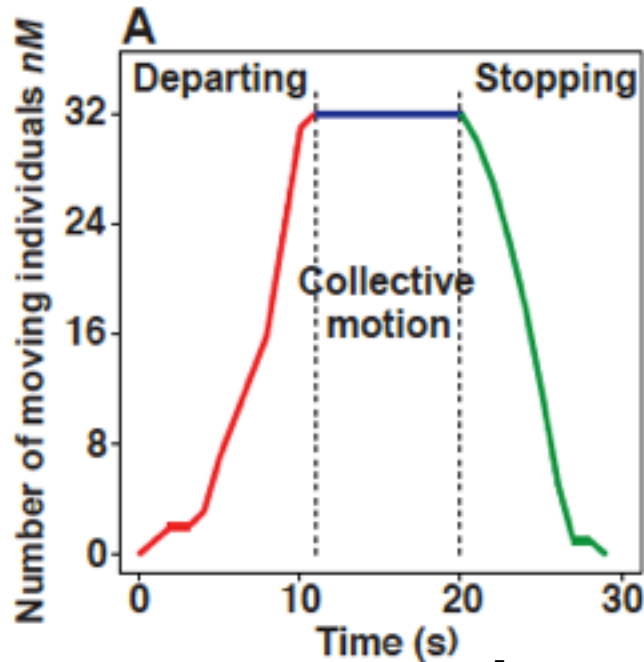
$$\mu = \alpha \frac{nM^{\beta}}{nS_s^{\gamma}}$$

$$\sigma = \alpha' \frac{nS_T^{\beta'}}{nM^{\gamma'}}$$



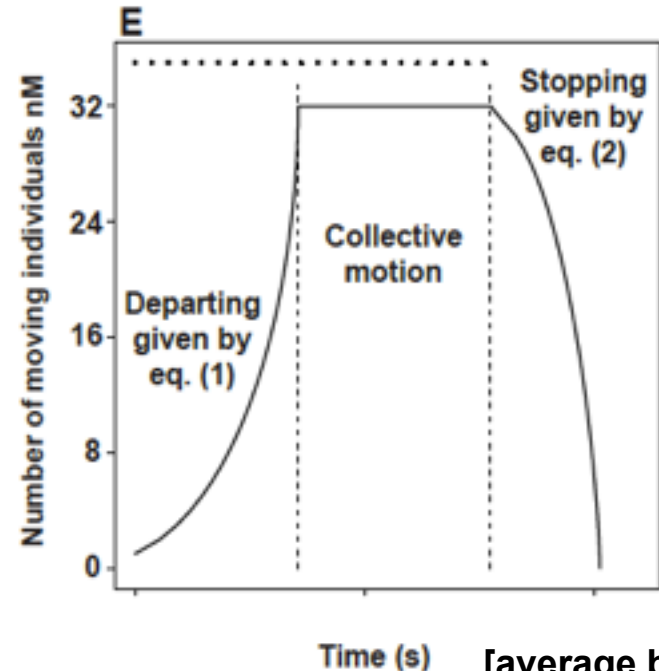
(this is very different from physical interactions: i.e. no pairwise interactions)
 (important observation: we assume that each individual is able to see all other individuals in the group)

The temporal dynamics...



[one experiment]

$S_S \rightarrow M$




[average behavior]

$M \rightarrow S_T$

$$\mu(nM, N) = \alpha \frac{nM^\beta}{nS_S^\gamma} = \alpha \frac{nM^\beta}{(N - nM)^\gamma}$$

$$\sigma(nM, N) = \alpha' \frac{nS_T^{\beta'}}{nM^{\gamma'}} = \alpha' \frac{(N - nM)^{\beta'}}{nM^{\gamma'}}$$

This is not all...

An aerial photograph of a large green field. A green net is stretched across the field, forming a large, irregular loop. Several sheep are visible inside the netted area. In the background, there are some buildings and trees under a cloudy sky.

Clip 2:
The initiator fails
to provoke
collective motion

**The group of naïve individuals seems to reach a consensus:
either all of them follow the trained individual, or none does it!**

Is there a collective decision-making process?

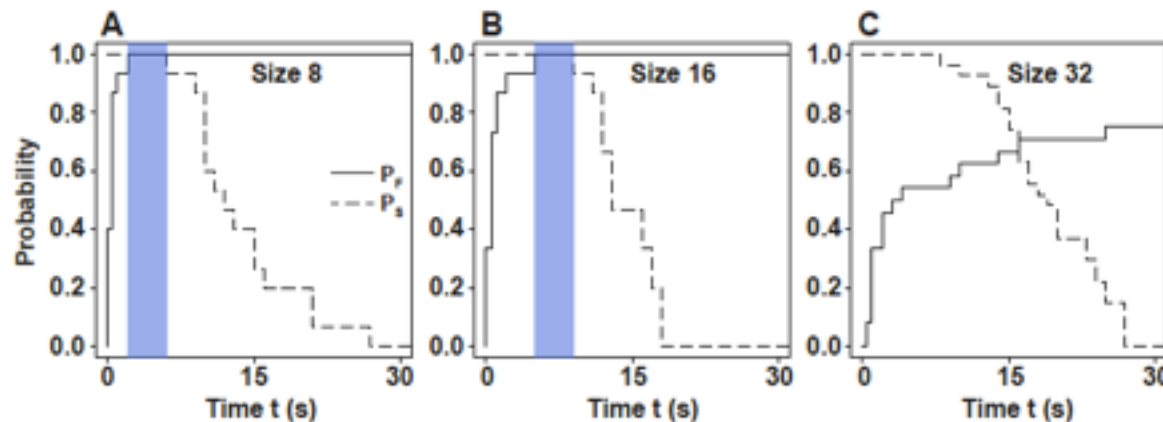
What is the mechanism behind this?

**The group of naïve individuals seems to reach a consensus:
either all of them follow the trained individual, or none does it!**

Is there a collective decision-making process?

What is the mechanism behind this?

Two key factors: the “stimulus” time & characteristic time to react ($1/\mu$)

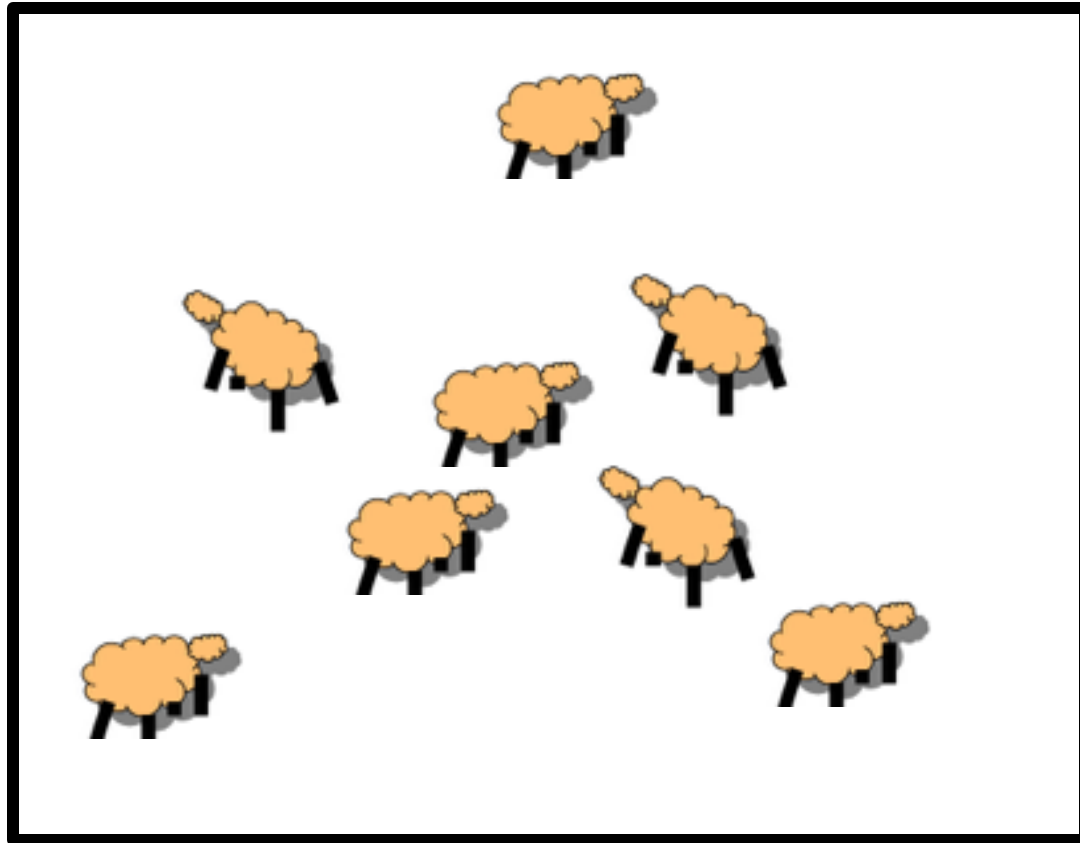


P_F = prob. first follow occurs before time t

P_S = prob. the trained individual has reached the target at time t

Notice that we have assumed that individuals in state S_t cannot induce a transition from the state S_s . This implies also that the trained individual can only induce a transition if it is in motion.

Spontaneous behavior (= no leader/trained individual)... with N=100



a dilemma:

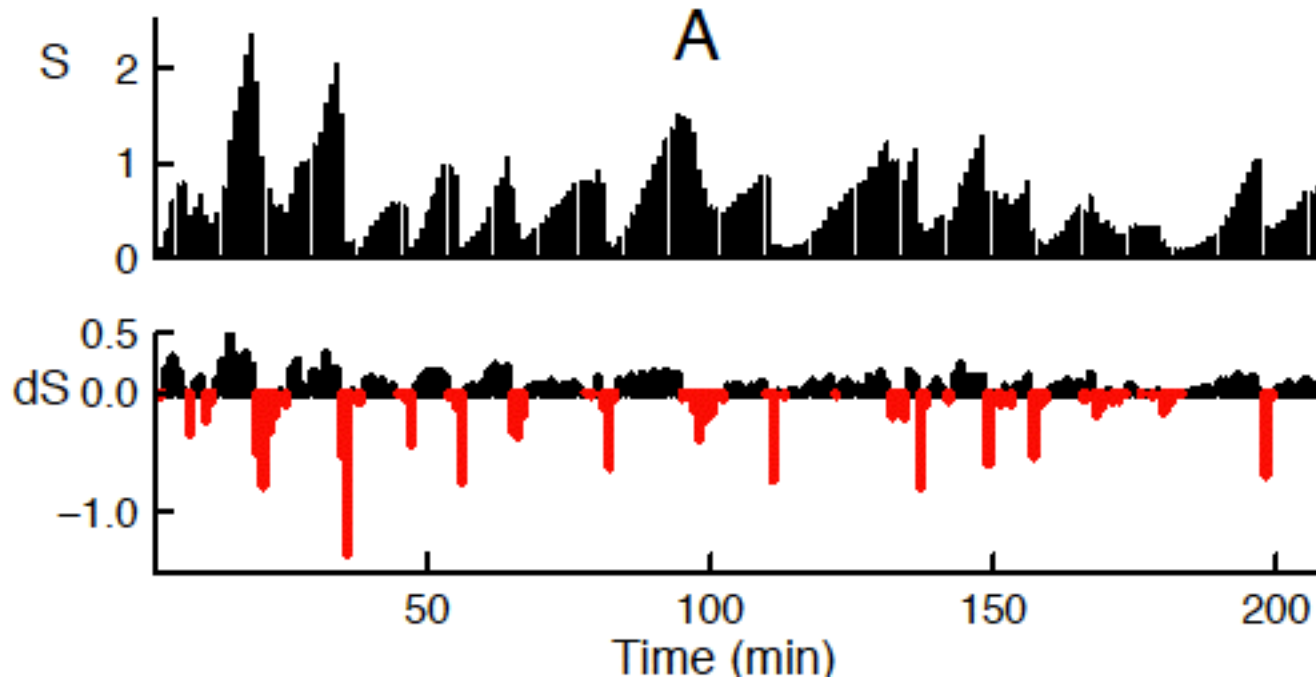
How to stay together while looking for green pastures for yourself?

How to eat without being eaten?

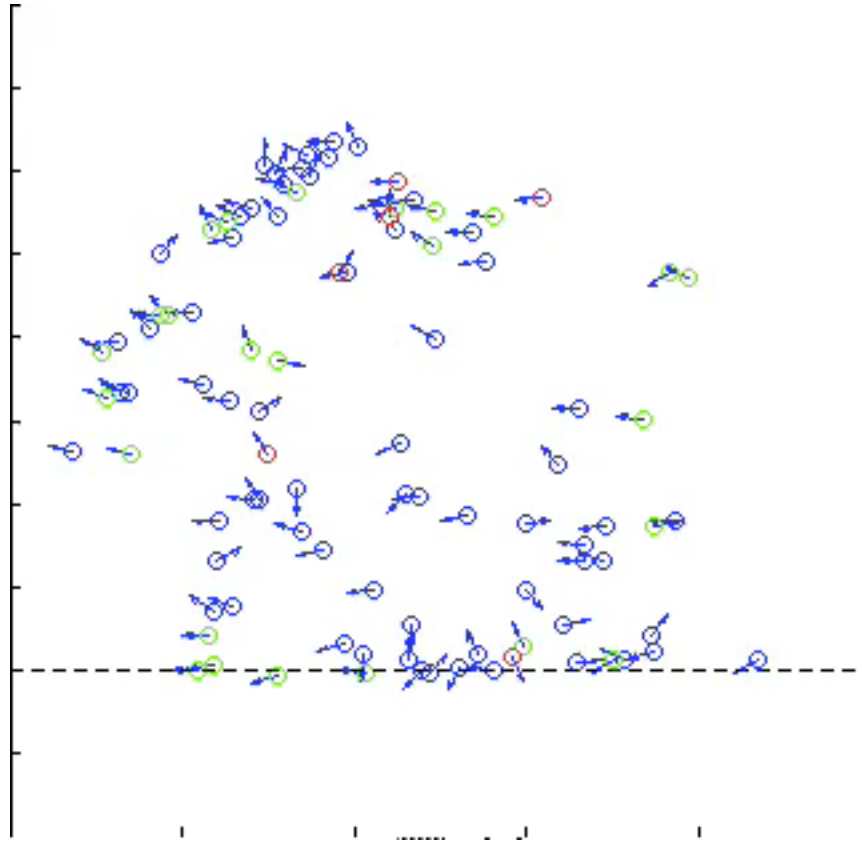




How to characterize the observed collective behavior?

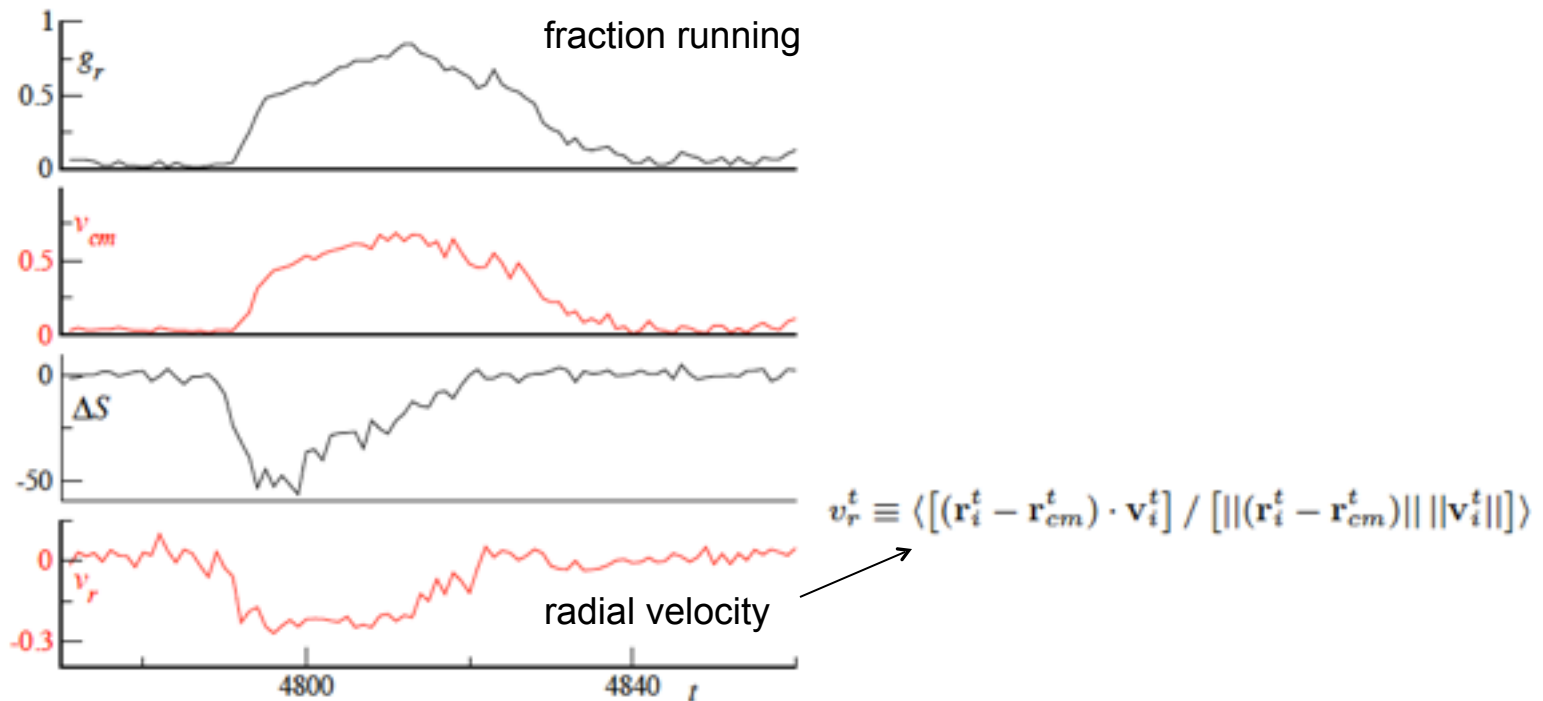
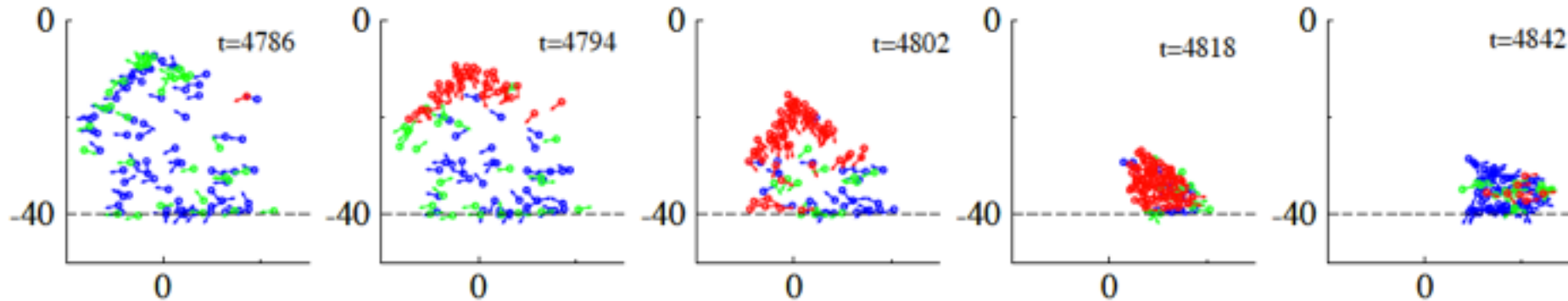


An aggregation event:

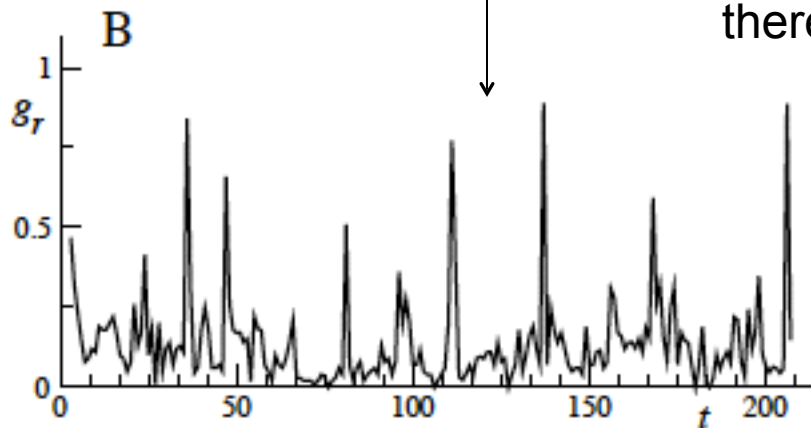
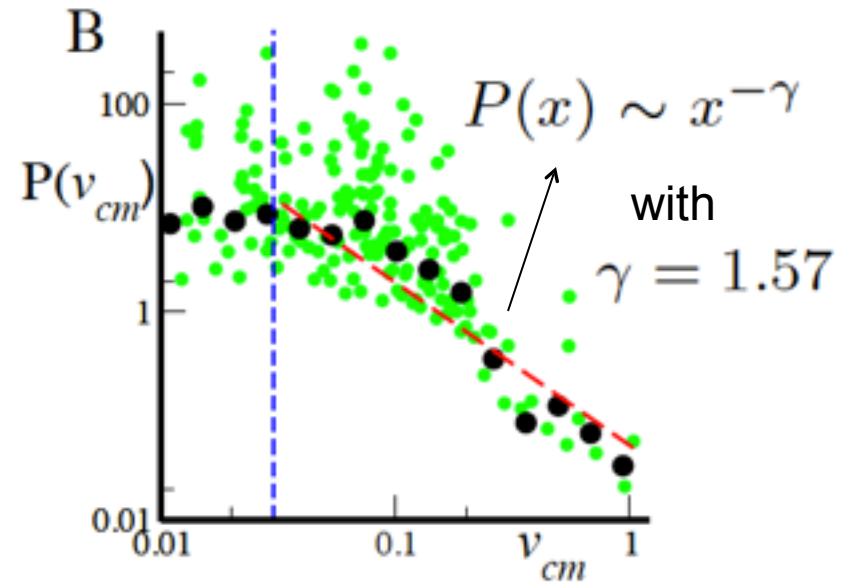
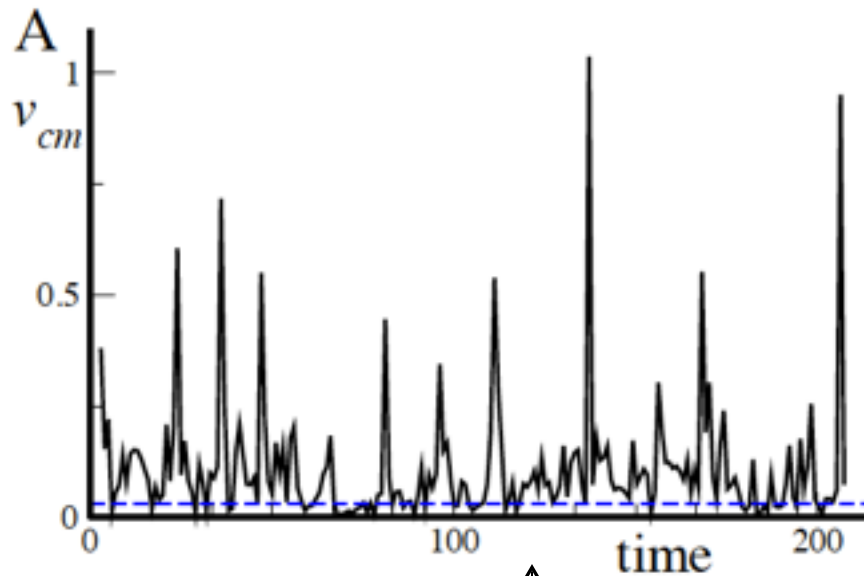


Color indicates whether the sheep is grazing (blue), moving (green), or running (red)

An aggregation event:



How is the distribution of aggregation events?



there are aggregation events of many sizes...

are these power-law distributed?

How can we model the observed behavior?

Using a Vicsek-like model:

$$\mathbf{r}_i^{t+\Delta t} = \mathbf{r}_i^t + \Delta t v(q_i^t) \mathbf{s}_i^{t+\Delta t}, \quad [1]$$

$$\theta_i^{t+\Delta t} = \text{Arg} \left[\sum_{j \in \mathcal{M}_i} \mathbf{s}_j^t \right] + \psi_i^t \quad (\text{if } q_i^t = 1), \quad [2] \quad \text{[metric neighbors]}$$

$$\theta_i^{t+\Delta t} = \text{Arg} \sum_{j \in \mathcal{V}_i} \left[\delta_{2,q_j^t} \mathbf{s}_j^t + \beta f(r_{ij}^t) \mathbf{e}_{ij}^t \right] \quad (\text{if } q_i^t = 2) \quad [3] \quad \text{[topo. neighbors]}$$

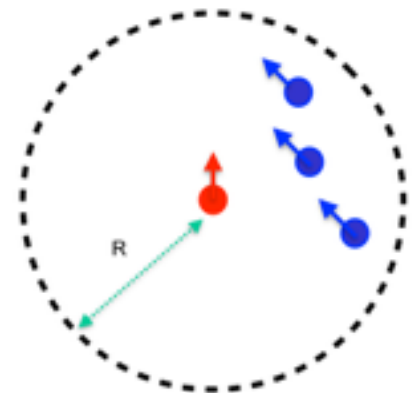
alignment

Transition between “ behavioral states ” (i.e. slow motion, fast motion, etc):

$$p_{0 \rightarrow 1}(i, t) = \frac{1 + \alpha n_1^t(i)}{\tau_{0 \rightarrow 1}}, \quad p_{1 \rightarrow 0}(i, t) = \frac{1 + \alpha n_0^t(i)}{\tau_{1 \rightarrow 0}}, \quad [4]$$

$$p_{0,1 \rightarrow 2}(i, t) = \frac{1}{\tau_{0,1 \rightarrow 2}} \left[\frac{\ell_i^t}{d_R} (1 + \alpha m_R^t(i)) \right]^\delta, \quad [5]$$

$$p_{2 \rightarrow 0}(i, t) = \frac{1}{\tau_{2 \rightarrow 0}} \left[\frac{d_S}{\ell_i^t} (1 + \alpha m_S^t(i)) \right]^\delta, \quad [6]$$



How can we model the observed behavior?

Using a Vicsek-like model:

$$\mathbf{r}_i^{t+\Delta t} = \mathbf{r}_i^t + \Delta t v(q_i^t) \mathbf{s}_i^{t+\Delta t}, \quad [1]$$

$$\theta_i^{t+\Delta t} = \text{Arg} \left[\sum_{j \in \mathcal{M}_i} \mathbf{s}_j^t \right] + \psi_i^t \quad (\text{if } q_i^t = 1), \quad [2] \quad \text{[metric neighbors]}$$

$$\theta_i^{t+\Delta t} = \text{Arg} \sum_{j \in \mathcal{V}_i} \left[\delta_{2,q_j^t} \mathbf{s}_j^t + \beta f(r_{ij}^t) \mathbf{e}_{ij}^t \right] \quad (\text{if } q_i^t = 2) \quad [3] \quad \text{[topo. neighbors]}$$

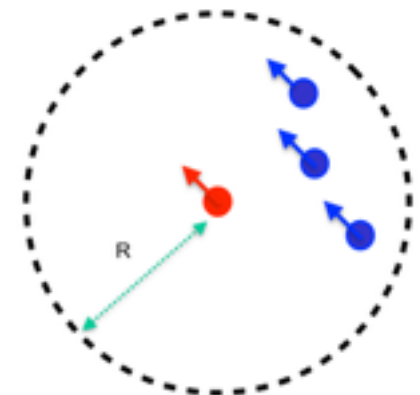
alignment

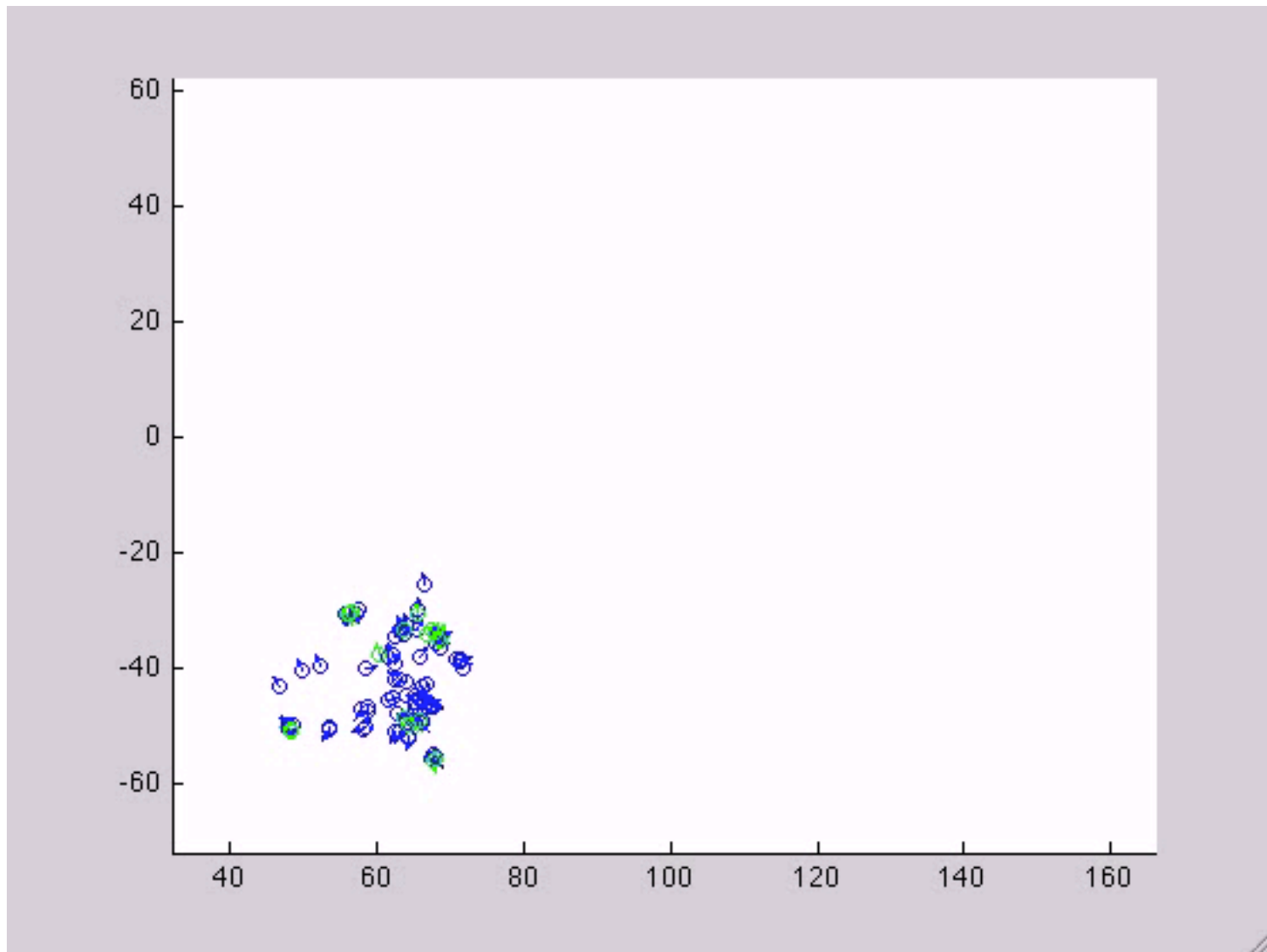
Transition between “ behavioral states ” (i.e. slow motion, fast motion, etc):

$$p_{0 \rightarrow 1}(i, t) = \frac{1 + \alpha n_1^t(i)}{\tau_{0 \rightarrow 1}}, \quad p_{1 \rightarrow 0}(i, t) = \frac{1 + \alpha n_0^t(i)}{\tau_{1 \rightarrow 0}}, \quad [4]$$

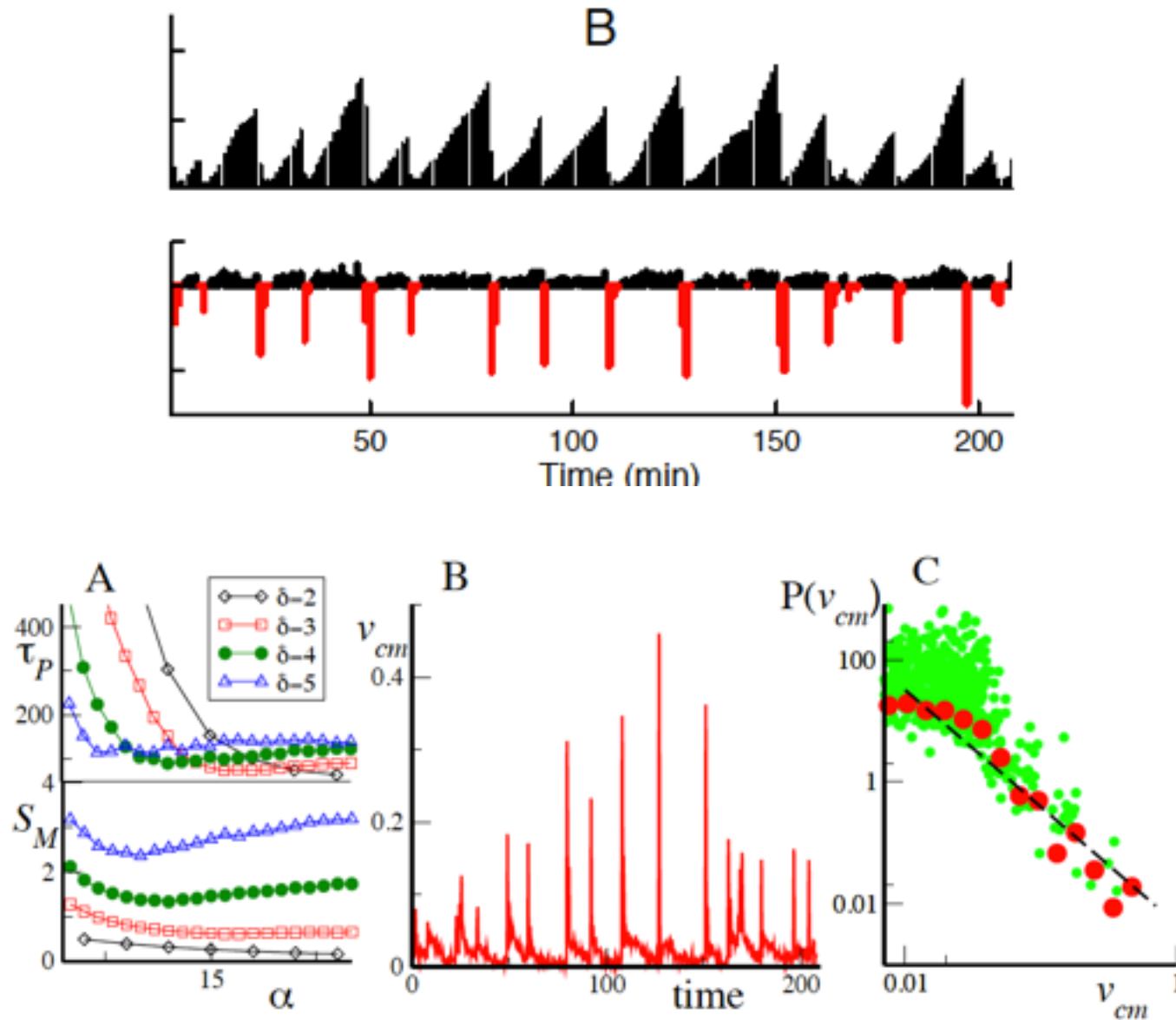
$$p_{0,1 \rightarrow 2}(i, t) = \frac{1}{\tau_{0,1 \rightarrow 2}} \left[\frac{\ell_i^t}{d_R} (1 + \alpha m_R^t(i)) \right]^\delta, \quad [5]$$

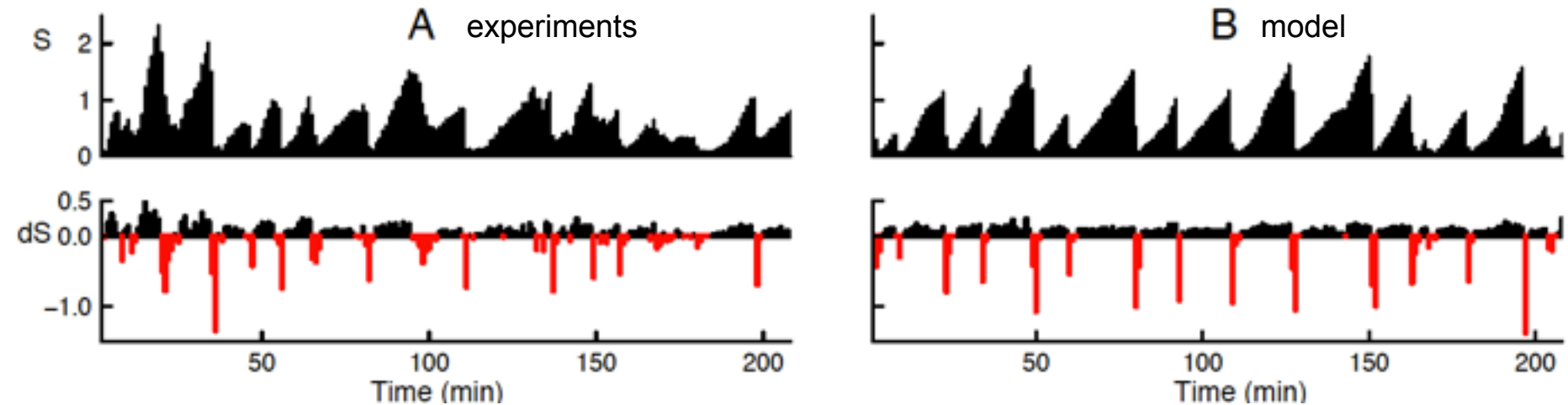
$$p_{2 \rightarrow 0}(i, t) = \frac{1}{\tau_{2 \rightarrow 0}} \left[\frac{d_S}{\ell_i^t} (1 + \alpha m_S^t(i)) \right]^\delta, \quad [6]$$



Model behavior...

Comparison between model and experiments...





messages:

Sheep alternate periods of grazing (slowly spreading) with fast aggregation events. This seems to solve the dilemma of looking for resources, while remaining together.

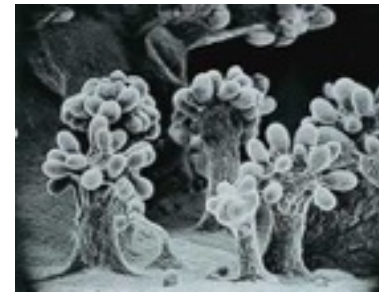
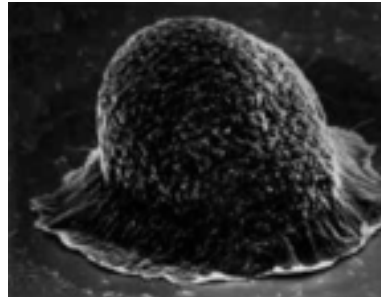
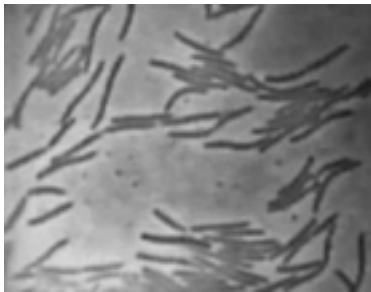
Whether the distribution of aggregation events is critical (or quasi-critical) is still an open issue, but certainly a possibility.

The proposed (complex) model is able to reproduce the data. This suggests that all the mechanisms required to produce the observed phenomena is there. Which ingredients (among the many introduced) are really necessary is an open question.

summary

Using the same theoretical framework, we can explain a large variety of collective phenomena in fundamentally different biological system

The required theoretical framework, using the language of physics, corresponds to the theory of active particles in dissipative media, which we still do not fully understand.



some coverage on this work...



Le mouton de Panurge, une réputation qui se confirme

Dans un troupeau, les moutons copient bien l'attitude de leurs voisins. La sélection naturelle aurait favorisé ce comportement d'imitation qui maximise les chances de manger sans être mangé.

Sean Bailly



Shutterstock.com/Olha Rohulya



How Sheep Are like an Avalanche

By Elizabeth Preston | September 29, 2015 12:40 pm





active matter @ Nice 2017



2014



Nice

Oleksandr Chepizkho
Stefan Otte
Luis Gomez Nava
Emiliano Perez Ipiña
Lucas Barberis
Robert Grossmann

Toulouse

Richard Bon
Richard Gautrais
Guy Theraulaz
Sylvain Toulet

Paris/Saclay

Hugues Chaté
Francesco Ginelli (Aberdeen)

Berlin & Dresden

Markus Bär (Berlin)
Andreas Deutsch (Dresden)



Thanks for your attention!

