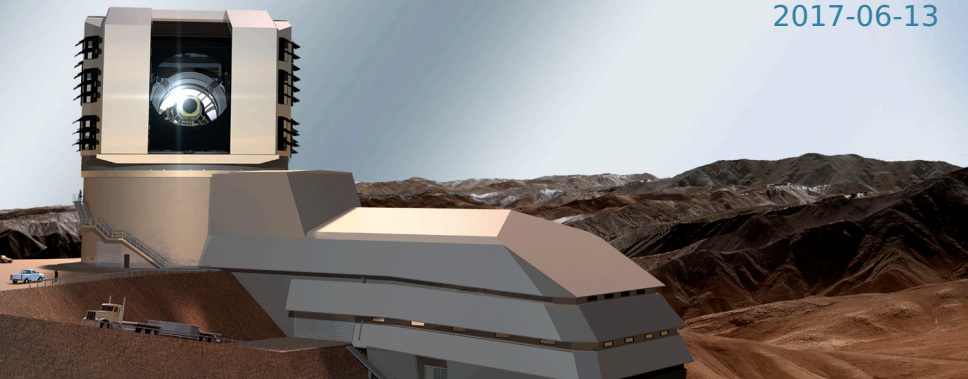


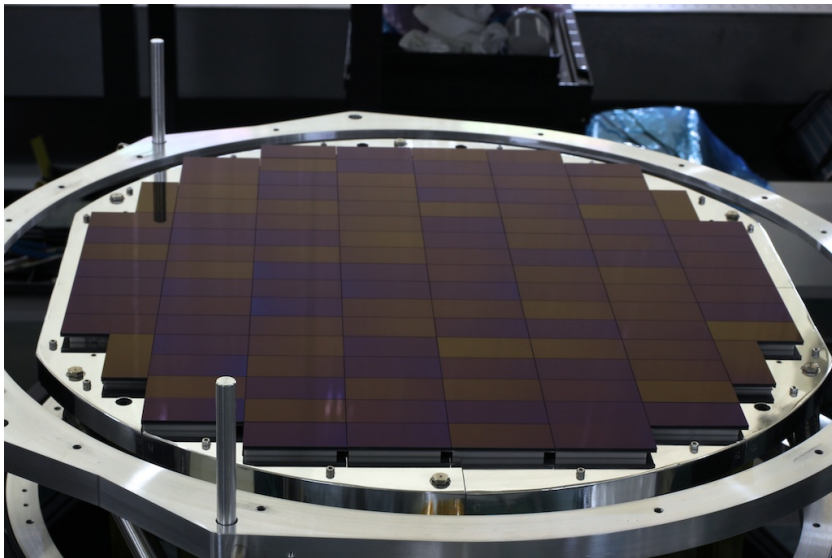


Robert Lupton
LSST Pipeline Scientist

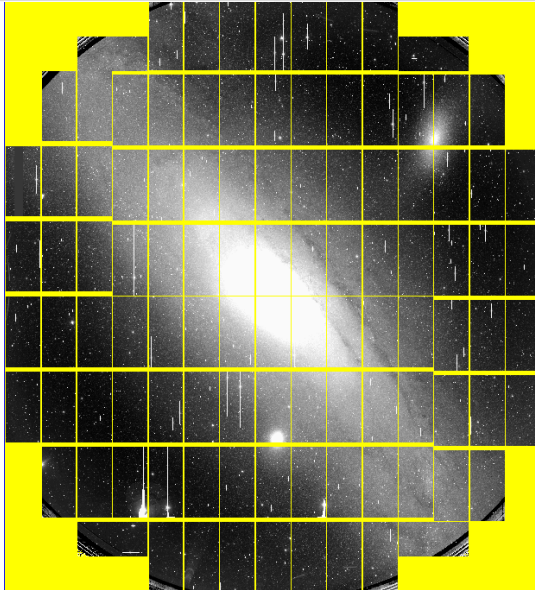
HSC pixels meet LSST Pipelines

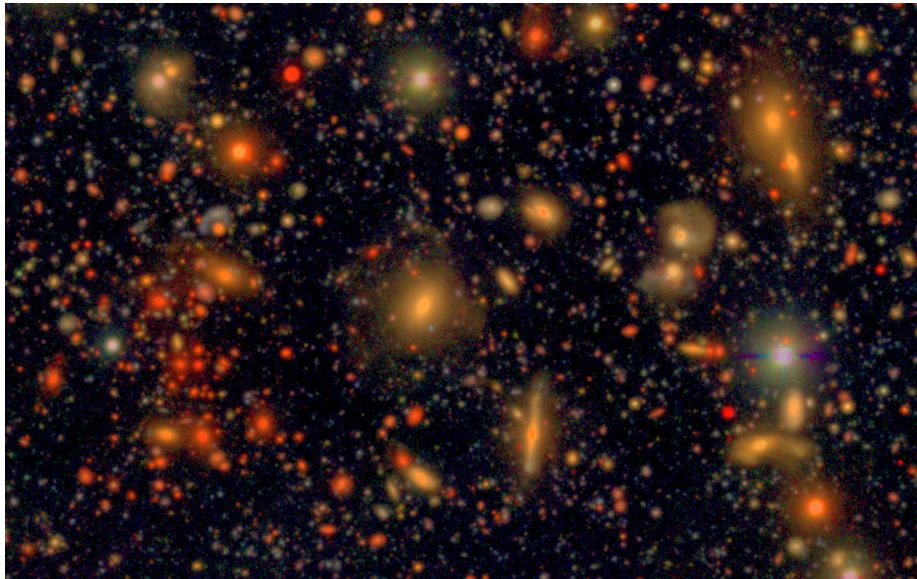
2017-06-13

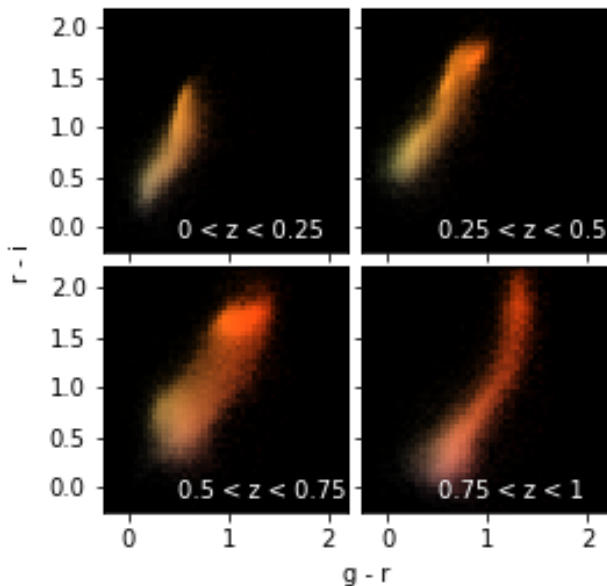




HSC's 1.8 deg² Field of View









- Use the LSST prototype codes



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- Develop them fast enough to handle HSC data



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Risky, but I *think* we got away with it. I hope Tanaka-san agrees.

I'm pretty confident that we'll have come out ahead by the time the HSC 'SSP' survey is done.

Create the tasks

```
In [6]: schema = afwTable.SourceTable.makeMinimalSchema()
algMetadata = dafBase.PropertyList()

config = CharacterizeImageTask.ConfigClass()
config.psfIterations = 1
if False:
    config.measurePsf.psfDeterminer.name = "pca"
else:
    config.measurePsf.psfDeterminer.name = "psfex"

charImageTask = CharacterizeImageTask(None, config=config)

config = SourceDetectionTask.ConfigClass()
sourceDetectionTask = SourceDetectionTask(schema=schema, config=config)

sourceDeblendTask = SourceDeblendTask(schema=schema)

config = SingleFrameMeasurementTask.ConfigClass()
config.slots.apFlux = 'base_CircularApertureFlux_12_0'
sourceMeasurementTask = SingleFrameMeasurementTask(schema=schema, config=config,
                                                    algMetadata=algMetadata)
```

Process the data

```
In [7]: butler = dafPersist.Butler("/Volumes/RHLDData/hsc-v13_0")
```

```
In [8]: dataId = dict(visit=29352, ccd=50)
exposure = butler.get('calexp', dataId)

tab = afwTable.SourceTable.make(schema)

result = charImageTask.characterize(exposure)
psfCellSet = result.psfCellSet      # we'll look at this data structure later

result = sourceDetectionTask.run(tab, exposure)
sources = result.sources

sourceDeblendTask.run(exposure, sources)

sourceMeasurementTask.run(exposure, sources)

sources.writeFits("outputTable.fits")
exposure.writeFits("example1-out.fits")
```



- Single visit processing:
 - flat fielding *etc.*
 - source detection
 - astrometric/photometric calibration
 - PSF estimation
 - deblending
 - measurement



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- Relative calibration (photometric and astrometric) of all visits on the scale of the focal plane.

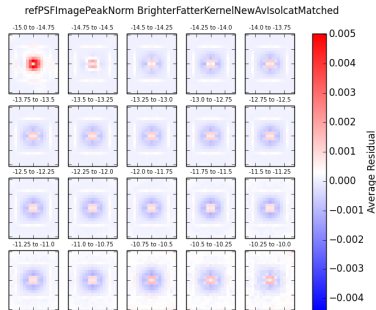
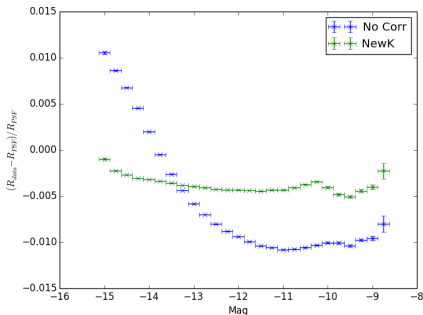


- Single visit processing:
 - flat fielding *etc.*
 - source detection
 - astrometric/photometric calibration
 - PSF estimation
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 - measurement
- Relative calibration (photometric and astrometric) of all visits on the scale of the focal plane. We're currently using PanSTARRS catalogues, but will soon switch to Gaia (at least for astrometry, maybe photometry)

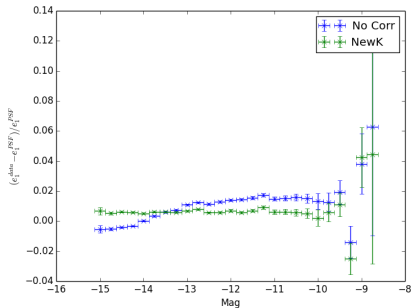


One of the parts of "flat fielding *etc.*" was Brighter-Fatter.

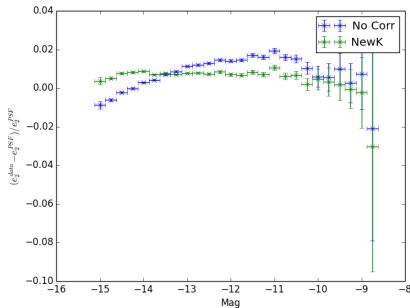
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One of the parts of "flat fielding *etc.*" was Brighter-Fatter.



(a) The difference ϵ_1 of ellipticity of stars and the average star both with and without the correction.



(b) The difference ϵ_2 of ellipticity of stars and the average star both with and without the correction.



We currently use psfEx restructured as a plugin, but are having trouble once the seeing is better than c. 0.45" (2.7 pixels).



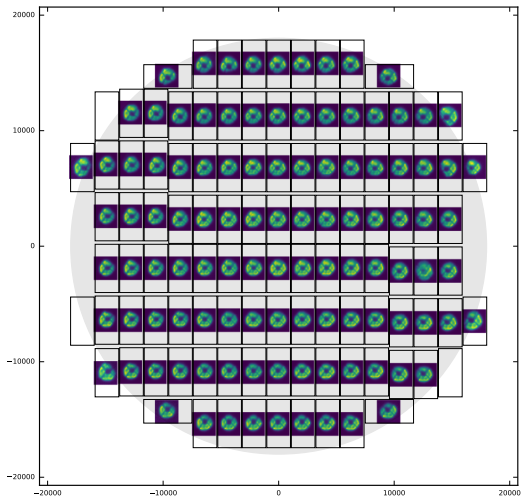
We currently use psfEx restructured as a plugin, but are having trouble once the seeing is better than c. 0.45" (2.7 pixels). We'll replace it with something better, but what?

- psfEx++?
- piff?
- CosmoStat@Saclay's RCA?
- Wavefront-based estimation?

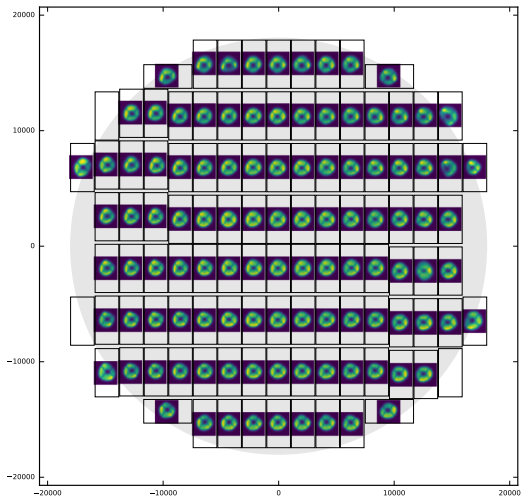


We currently use `psfEx` restructured as a plugin, but are having trouble once the seeing is better than c. $0.45''$ (2.7 pixels). We'll replace it with something better, but what?

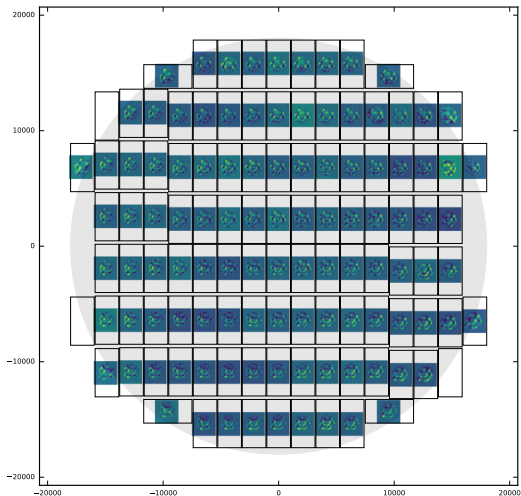
- `psfEx++`?
- `piFF`?
- CosmoStat@Saclay's RCA?
- Wavefront-based estimation?
- Your Code?



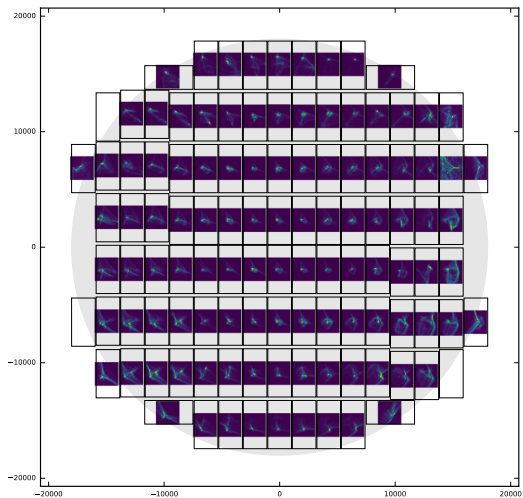
Data

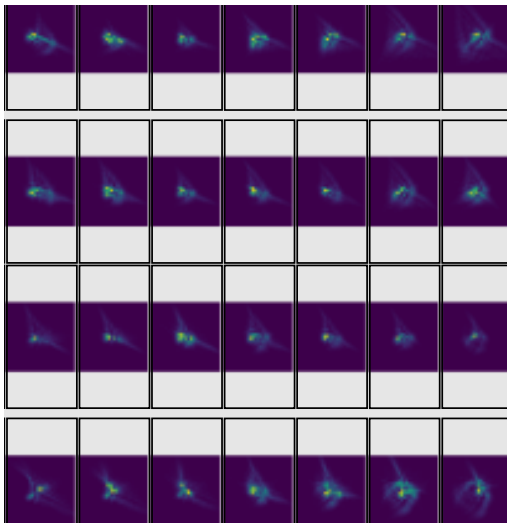


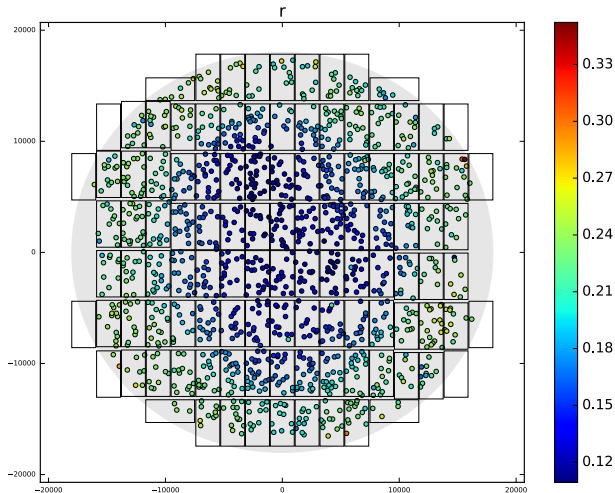
Model



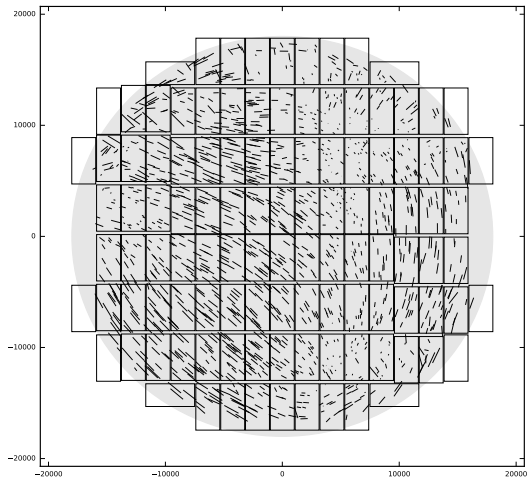
Residual







PSF radius



e_1, e_2



- Coadd creation:
Per-band coadds are created in *grizy*.
- PSF estimation



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The PSF is discontinuous at CCD and field boundaries and wherever you've masked pixels, so we add up all the contributing PSFs for each object to define its personal PSF "coaddPs f" – I first heard this suggested by James Jee.



- Coadd source detection:

The primary detection is on the scale of the PSF resulting in a set of pixels — a Footprint. Each Footprint has one or more Peaks and these sets of Peaks define our objects.



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- Association and deblending:

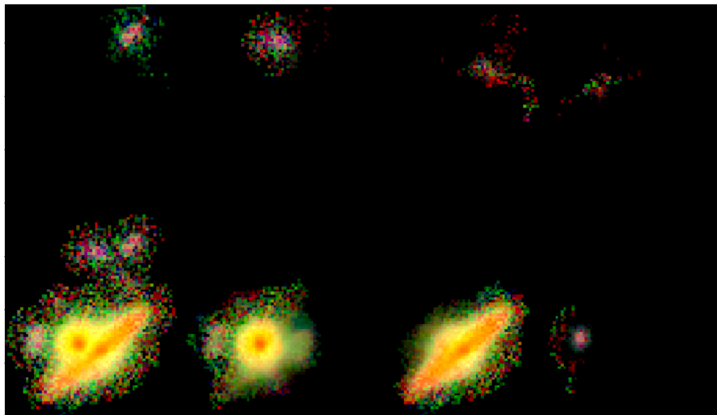
Synthesize a list of unique objects by merging Peaks from each band.

Output a list of uncharacterized deblended (*i.e.* isolated) objects.

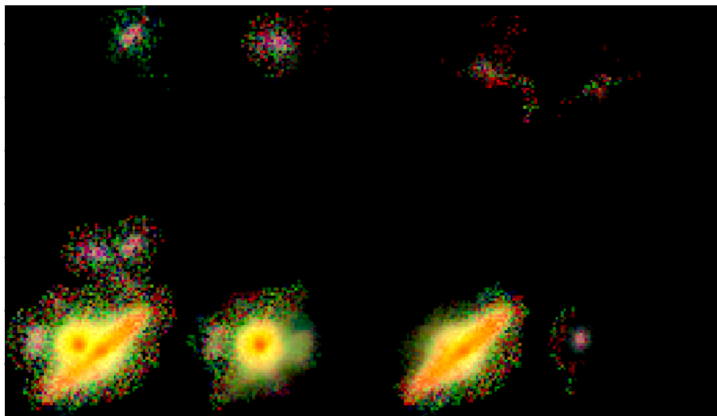


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- Object characterization on coadds:
Measure Object properties such as:
 - centroids
 - adaptive moments
 - PSF and Kron/Petrosian fluxes
 - "fibre" aperture fluxes
 - simple "cmodel" galaxy models
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- Forced Photometry:
Measure fluxes for every Object on every visit keeping all non-photometric parameters fixed



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- PSF match, then clip. But faint features still survive.
- Use a direct mean of the pixel values. But this allows the junk to leak into the coadd.
- Make use of the differences between images to remove the junk, then use a mean

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- Make a heavily clipped coadd
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- Remove the junk that's in only one image (leaving the cores of bright objects)
- Calculate a direct mean of what's left, a "Safe Clipped Coadd"



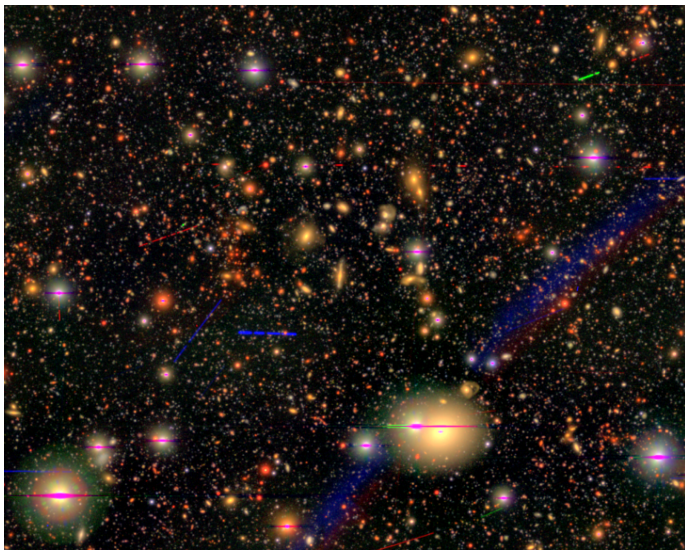
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As Nick Kaiser pointed out in 2001 (PSDC-002-011-00), and Zackay, Ofek, and Gel-Yam recently rediscovered, you can build a coadd with optimal properties by down-weighting components that are suppressed by the images' PSFs, and then flattening the noise.

We don't currently use these coadds for HSC (it's a bit complicated with a spatially varying PSF)





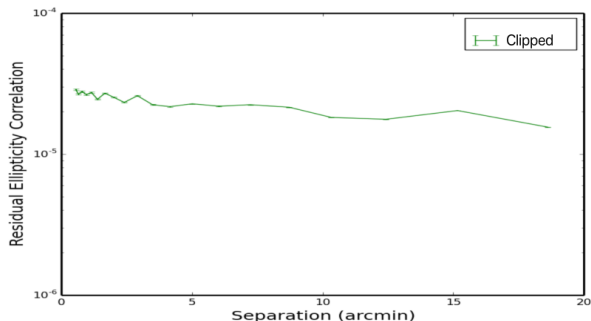
Does Clipping Really Matter?



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Courtesy Bob Armstrong σ Clipped

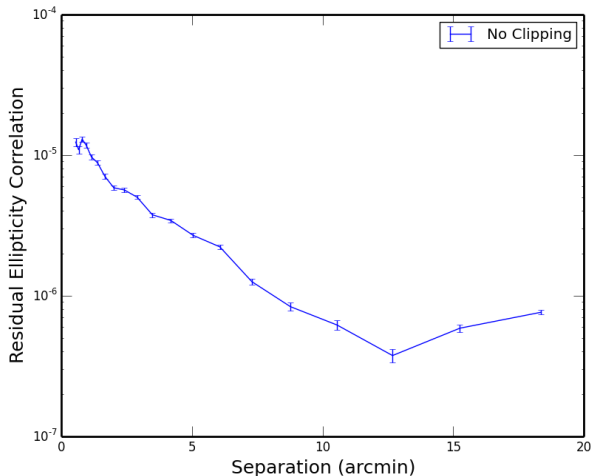


Does Clipping Really Matter?



Courtesy Bob Armstrong

Mean



"Take the code to the data"



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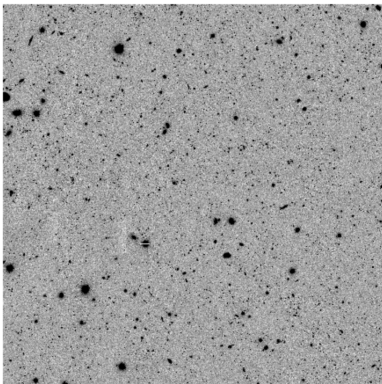
- SDSS Cas/Casjobs was an early attempt to do this
- So are the NAOJ HSC catalogues

Unfortunately SQL isn't a very expressive language. Recently many people have realised the *Jupyter Notebooks* provide a way that people can really compute close to the data. I think it's time to move to the next phase:

Keep the Code with the Data

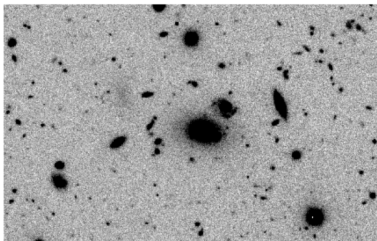
Get HSC calibrated exposure

```
In [5]: dataId = dict(tract=9348, patch='7,6', filter='HSC-I')  
exp = butler.get('deepCoadd_calexp', dataId)  
display_image(exp.getMaskedImage().getImage().getArray(), figsize=(8,8));
```



Make cutout

```
In [6]: bbox = afwGeom.Box2I()  
bbox.include(afwGeom.Point2I(2700, 3600))  
bbox.include(afwGeom.Point2I(3330, 4000))  
exp_cutout = exp.Factory(exp, bbox, afwImage.LOCAL)  
  
mi = exp_cutout.getMaskedImage()  
mask = mi.getMask()  
mask.removeAndClearMaskPlane('CR', True)  
  
display_image(mi.getImage().getArray());
```



Smooth at PSF scale

```
In [7]: psf = exp.getPsf()
sigma = psf.computeShape().getDeterminantRadius()
ngrow = int(3*sigma)
mi_smooth = smooth_gauss(mi, sigma)
print('psf fwhm = {:.2f} arcsec'.format(sigma*0.168*2.355))

psf fwhm = 0.52 arcsec
```

Image thresholding

- Find high-threshold sources that are 6σ above the background and create a mask plane

```
In [8]: high_thresh = 6
fpset_high = afwDetect.FootprintSet(
    mi_smooth, afwDetect.Threshold(high_thresh, afwDetect.Threshold.STDEV), 'HIGH_THRESH', 1)
fpset_high = afwDetect.FootprintSet(fpset_high, ngrow)
fpset_high.setMask(mask, 'HIGH_THRESH')
```

- Find low-threshold sources that are 1.5σ above the background and create a mask plane

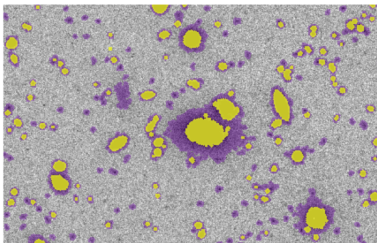
```
In [9]: low_thresh = 1.5
fpset_low = afwDetect.FootprintSet(
    mi_smooth, afwDetect.Threshold(low_thresh, afwDetect.Threshold.STDEV), 'LOW_THRESH', 10)
fpset_low = afwDetect.FootprintSet(fpset_low, ngrow)
fpset_low.setMask(mask, 'LOW_THRESH')
```


Visualize segmentation maps

- low-threshold footprints are purple
- high-threshold footprints are yellow

```
In [10]: seg_high = fpset_high.insertIntoImage(True).getArray().copy().astype(float)
seg_low = fpset_low.insertIntoImage(True).getArray().copy().astype(float)
seg_low[seg_low>0] = 1.0
seg_low[seg_low==0] = np.nan
seg_high[seg_high>0] = 1.0
seg_high[seg_high==0] = np.nan

ax = display_image(mi.getImage().getArray())
kws = dict(cmap='plasma', vmin=0, vmax=1, origin='lower')
ax.imshow(seg_low*0.2, alpha=0.4, **kws)
ax.imshow(seg_high*1.0, alpha=0.8, **kws);
```



Remove bright sources and associated diffuse light

- associate a low-thresh footprint with a high-thresh footprint if more than 5% of its light is above the high threshold

```
In [11]: max_frac = 0.05

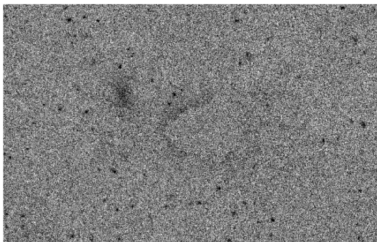
# loop over low threshold footprints
# and save those with >max_frac high
# threshold pixels
fp_list = afwDetect.FootprintList()
for fp in fpset_low.getFootprints():
    hfp = afwDetect.HeavyFootprintF(fp, mi)
    pix = hfp.getMaskArray()
    bits_high = (pix & mask.getPlaneBitMask('HIGH_THRESH')!=0).sum()
    if bits_high/float(fp.getArea()) > max_frac:
        fp_list.append(fp)

# build a new footprint set
fpset_replace = afwDetect.FootprintSet(mi.getBBox())
fpset_replace.setFootprints(fp_list)

# create a mask plane for "cleaned" footprints
if 'CLEANED' in mask.getMaskPlaneDict().keys():
    mask.clearMaskPlane(mask.getMaskPlane('CLEANED'))
mask.addMaskPlane('CLEANED')
fpset_replace.setMask(mask, 'CLEANED')
```

- replace footprints associated with bright sources with sky noise

```
In [12]: exp_clean = exp_cutout.clone()
mi_clean = exp_clean.getMaskedImage()
back_rms = mi.getImage().getArray()[mask.getArray()==0].std()
noise_array = back_rms*np.random.randn(*mask.getArray().shape)
replace = mask.getArray() & mask.getPlaneBitMask('BRIGHT_OBJECT') != 0
replace |= mask.getArray() & mask.getPlaneBitMask('CLEANED') != 0
mi_clean.getImage().getArray()[replace] = noise_array[replace]
display_image(mi_clean.getImage().getArray());
```



- smooth to emphasize extended low-surface-brightness structures

```
In [13]: smoothed = smooth_gauss(mi_clean, 4)
display_image(smoothed.getImage().getArray());
```

