B-tagging in ATLAS Experiment

Changqiao LI^{[1][2]}

[1]University of Science and Technology of China[2]Laboratoire de Physique Nucléaire et de Hautes Energies





About me

- Chang-qiao ("qiao" pronounced similar like "ciao")
- Co-Ph.D. of LPNHE and USTC(China)
- Work on the ATLAS Experiment
- Qualification work:
 - B-tagging calibration with Tag-and-Probe Method
- Thesis topic:
 - SM VH(→bb) analysis
 (Introduced in the next talk by Charles)

What is B-tagging of jet?



- Identification of jets originating from b-quarks
- Plays a vital role in many ATLAS analysis:
 - Higgs→b-quarks
 - top physics
 - search for new physics
- Hadrons containing bottom quarks have sufficient lifetime that they travel some distance before decaying

How to tag?



Tagging algorithms:

- impact parameter-based (IP)
- inclusive secondary vertex reconstruction (SV)
- decay chain multi-vertex reconstruction (JetFitter)
- combination of above in a multivariate discriminant (MV)

Procedure:

- 1. Select a jet
- Match tracks by ΔR matching
- 3. Build vertices
- 4. compute discriminant with:
 - track-based variables associated with the jet
 - large mass
 - high decay multiplicity

How to calibrate b-tagging?

- Using dileptonic ttbar events
- b-jet calibration method:



$$\kappa^{data/sim}_{\epsilon_j} = \frac{\epsilon^{data}_j}{\epsilon^{sim}_j}$$

- ttbar Probability Distribution Function (PDF) method: Measure the b-jet tag weight distribution from a Maximum Likelihood fit in eµ+2/3 jets or ee/µµ+2/3 jets
- ttbar tag-and-probe method: Measure the b-jet tag efficiency by subtracting the noneb-jets contamination in probe jets from ttbar in eµ+2 jets
- Systematics:
 - Detector related systematics
 - MC modelling: matrix element, hadronisation, showering
 - MC statistical uncertainty



Probability Distribution Function

- Use a likelihood formalism which exploits per event jet flavour correlations
 - Extract b-jet tagging efficiency from data in each jet pt bin
 - Large gain in precision when compared to determining efficiency from individual jets

Likelihood for 2 jet case:

$$\begin{aligned} \mathcal{L}(p_{T,1}, p_{T,2}, w_1, w_2) = & [f_{bb} \mathcal{P}_{bb}(p_{T,1}, p_{T,2}) \mathcal{P}_b(w_1 | p_{T,1}) \mathcal{P}_b(w_2 | p_{T,2}) \\ &+ f_{bj} \mathcal{P}_{bj}(p_{T,1}, p_{T,2}) \mathcal{P}_b(w_1 | p_{T,1}) \mathcal{P}_j(w_2 | p_{T,2}) \\ &+ f_{jj} \mathcal{P}_j(p_{T,1}, p_{T,2}) \mathcal{P}_j(w_1 | p_{T,1}) \mathcal{P}_j(w_2 | p_{T,2}) \\ &+ 1 \leftrightarrow 2]/2, \end{aligned}$$



2D PDFs for jets of flavour f1, f2 to have pT,1, pT,2

PDFs for b-tagging discriminant for b-jets (from data) and non-b-jets (MC)

Flavour fractions in 2-jet case

Tag-and-Probe

- Using eµ+2 jets:
 - tagging requirement: tag weight passing tagging working point
 - 1tag events: non tagged jet defined as probe jet
 - 2tag events: both jets defined as probe jets

Step 1 Non-*t*t events are subtracted:

$$\varepsilon_{data}^{Uncorr} = \frac{N_{data}^{pass} - N_{non-t\bar{t}}^{pass}}{N_{data} - N_{non-t\bar{t}}}$$

Step 2

Non b-labelled probes in $t\bar{t}$ events are subtracted, based on the b-labelled jet fraction $f_b^{t\bar{t} MC}$ in $t\bar{t}$ and efficiency for non b-labelled jets in $t\bar{t} \, \varepsilon_{non-b}^{t\bar{t} MC}$:

$$\mathbf{\varepsilon}_{data} = \frac{\mathbf{\varepsilon}_{data}^{Uncorr} - (1 - f_b^{t\bar{t}\ MC}) \times \mathbf{\varepsilon}_{non-b}^{t\bar{t}\ MC}}{f_b^{t\bar{t}\ MC}}$$

Tag-and-Probe

AntiBL BDT



mva cut 0.051 0.037 0.021 0.003 -0.019 -0.043 -0.073

Tag-and-Probe

BDT cut effect and optimisation

Comparison across MVA cuts at 77 WP of Calo Jets Calibration



B-jets purity in ttbar

Total uncertainty in lowest pt bin

Comparison across MVA cuts at 77 WP of Calo Jets Calibration of total in 1 ptbin



Comparison with PDF method

Comparison across MVA cuts at 77 WP of Calo Jets Calibration



Summary

- Identification of jets originating from b-quarks is very important for many analysis in ATLAS
- Three basic algorithms are used to perform b-jet tagging
- To achieve a better discrimination than any of the basic algorithms can achieve individually, a Boosted Decisions Tree (BDT) algorithm is employed. It combines the outputs of the basic taggers.
- Introduce ttbar PDF method and Tag-and-Probe methods.
- Tag-and-Probe: The worst uncertainty is in the lowest jet pt bin and smaller than 10%, for intermediate jet pt bins, it's smaller than 5%.
- Both methods gives compatible calibration results.

BACKUP

Backup

ATLAS uses a right-handed coordinate system with its origin at the nominal interaction point (IP) in the centre of the detector and the z-axis along the beam pipe. The x-axis points from the IP to the centre of the LHC ring and the y-axis points upwards. Cylindrical coordinates (r,ϕ) are used in the transverse plane, being ϕ the azimuthal angle around the z-axis. The pseudo-rapidity is defined in terms of the polar angle θ as $\eta = -\ln \tan(\theta/2)$ while $\Delta R^2 = \sqrt{\Delta \eta^2 + \Delta \phi^2}$.

$$\chi^{2}(\vec{r}) = \sum_{i=1}^{N_{trk}} (\vec{r} - \vec{r}_{i}(\hat{\phi}_{p,i}))^{T} \text{COV}_{3\times3,i}^{-1}(\hat{\phi}_{p,i})(\vec{r} - \vec{r}_{i}(\hat{\phi}_{p,i}))$$
(5.4)

The easiest way to estimate the vertex position \vec{r} and its related error is to minimise this χ^2 function numerically. The auxiliary parameters $\vec{\phi}_p$ can be dealt with by repeating the fit again in case some of the initial parameters $\vec{\phi}_p$ correspond to positions along the tracks trajectories which are significantly displaced with respect to the final estimated vertex position \vec{r} .



(Tracks') Impact parameter-based



The track selection:

- track pT above 1 GeV
- ld0l<1mm lz0sinθl<1.5mm
- silicon hits requirements

Probability density functions (PDF) obtained from reference histograms for IP significances: For a jet, given associate tracks:

- Separated into exclusive categories depending on the hit pattern
- In each category, build PDF for jet-flavour hypothesis (b,c,light)

 $P_f = \prod_{\text{trk}} \mathcal{L}_f(S_{d_0}, S_{z_0}, \text{grade})$ with $f \in \{b, c, \text{light}\}$

- Transverse impact parameter significance, d0/σd0
- Longitudinal impact parameter significance, z0*sinθ /σ(z0sinθ)
- A log-likelihood ratio (LLR) discriminant is computed as the sum of the per-track contributions,(N is the number of tracks of jet)

$$\sum_{i=1}^{N} \frac{\log p_b}{\log p_u}$$

Inclusive secondary vertex reconstruction



m(SV)	Invariant mass of tracks at the SV assuming π
	masses
$f_E(SV)$	Fraction of the charged jet energy in the SV
$N_{TrkAtVtx}(SV)$	Number of tracks used in the SV
$N_{2TrkVtx}(SV)$	Number of two track vertex candidates
$L_{xy}(SV)$	Transverse distance between the PV and the SVs
$L_{xyz}(SV)$	Distance between the PV and the SVs
$S_{xyz}(SV)$	Distance between the PV and SVs divided by its
	uncertainty
$\Delta R(jet, SV)$	ΔR between the jet axis and the direction of the
~ /	SV relative to the PV

- All selected tracks used to form all possible two-track vertices.
- Selection perform on these twotrack vertex candidates.
- All tracks corresponding to the remaining accepted two-track vertices are used to determine a single secondary vertex.
- Calculate chi-2 of the vertex, if Prob(chi-2) is very small, remove the track with the highest contribution until Prob(chi-2) acceptable

Decay chain multi-vertex reconstruction



	$N_{2TrkVtx}(JF)$	Number of 2-track vertex candidates		
Jet Fitter	m(JF)	Invariant mass of tracks from displaced vertices		
		assuming π masses		
	$S_{xyz}(JF)$	Significance of the average distance between the		
		PV and displaced vertices		
	$f_E(JF)$	Fraction of the charged jet energy in the SVs		
	$N_{1-trkvertices}(JF)$	Number of displaced vertices with one track		
	$N_{\geq 2-trkvertices}(JF)$	Number of displaced vertices with more than one		
		track		
	$N_{TrkAtVtx}(JF)$	Number of tracks from displaced vertices with at		
		least two tracks		
	$\Delta R(\vec{p}_{jet}, \vec{p}_{vtx})$	ΔR between the jet axis and the vectorial sum of		
		the momenta of all tracks attached to displaced		
		vertices		

- Exploits the topological structure of weak b- and chadron decays inside the jet.
- Tries to reconstruct the full
 PV→ b → c-hadron decay
 chainwith the Kalman filter.
- Using similar variable as SV1.
- The variables left are used as input nodes in an artificial neural network.
- It has three output nodes, corresponding to the b-, cand light-flavour-jet hypotheses.

Multivariate discriminant (default algorithm used for ATLAS)

- To achieve a better discrimination
- Combine IP, SV and JetFitter in a BDT
- Training settings: 1000 Trees, Max depth of 30, no cuts below 5% of sample





BDT Cut Value	<i>b</i> -jet Efficiency [%]	c-jet Rejection	Light-jet Rejection	τ Rejection
0.9349	60	34	1538	184
0.8244	70	12	381	55
0.6459	77	6	134	22
0.1758	85	3.1	33	8.2

Backup



		Fractional contribution [%]		
#	Category	<i>b</i> -jets	<i>c</i> -jets	light-jets
0	No hits in first two layers; expected hit in IBL and b-layer	1.9	2.0	1.9
1	No hits in first two layers; expected hit in IBL and no expected hit in b-layer	0.1	0.1	0.1
2	No hits in first two layers; no expected hit in IBL and expected hit in b-layer	0.04	0.04	0.04
3	No hits in first two layers; no expected hit in IBL and b-layer	0.03	0.03	0.03
4	No hit in IBL; expected hit in IBL	2.4	2.3	2.1
5	No hit in IBL; no expected hit in IBL	1.0	1.0	0.9
6	No hit in b-layer; expected hit in b-layer	0.5	0.5	0.5
7	No hit in b-layer; no expected hit in b-layer	2.4	2.4	2.2
8	Shared hit in both IBL and b-layer	0.01	0.01	0.03
9	At least one <i>shared</i> pixel hits	2.0	1.7	1.5
10	Two or more <i>shared</i> SCT hits	3.2	3.0	2.7
11	Split hits in both IBL and b-layer	1.0	0.87	0.6
12	Split pixel hit	1.8	1.4	0.9
13	Good	83.6	84.8	86.4

Table 1: Description of the track categories used by IP2D and IP3D together with the fraction of tracks in each category for jets in $t\bar{t}$ events. The order of the layers is explained in the text. The categories further down in the list can be more inclusive than the first ones because, when a category is not fulfilled, the next one is evaluated.

Backup

To be reliable any *b*-tagging algorithm must be calibrated on data. To facilitate the calibration and to reduce the necessary amount of data the chosen variables have been transformed (for details see [12]):

- Invariant mass: $M' = \frac{M}{M+1}$;
- Energy ratio: $R' = R^{0.7}$;
- Number of good two-track secondary vertices: $N' = \log N$.

Due to the efficiency to reconstruct a secondary vertex inside a jet not reaching 100%, the probability density functions (PDF) of the vertex based variable have to contain a δ -function [12].

$$PDF = (1 - \varepsilon) \cdot \delta(M', F', N') + \varepsilon \cdot ASH(M', F', N')$$

with ε being the efficiency to reconstruct a secondary vertex inside a jet. The continuous probability density function of the vertex variables is constructed from multidimensional calibration histograms using the ASH smoothing method [13].

Two slightly different taggers based on the *BTagVrtSec* algorithms are available in ATLAS, denoted *SV*1 and *SV*2. They use exactly the same variables but handle them in a different way. *SV*1 treats M' and R' jointly and adds N' as independent variable (2+1 decomposition), whereas *SV*2 uses joint three-dimensional probability density functions.